# Rectangular Standard Proximity Sensor

#### CSM\_TL-N\_TL-Q\_TL-G\_DS\_E\_9\_1

# A Wealth of Models for All Types of Applications

- Easy installation, high-speed pulse generator, high-speed rotation control, and more.
- Direct mounted to metal (-N Models).
- A wealth of models ideal for limit control, counting control, and other applications (-N Models).



Be sure to read *Safety Precautions* on page 9.

(excluding TL-G)

# **Ordering Information**

#### Sensors [Refer to *Dimensions* on page 10.] DC 2-Wire Models

|            |         |                  |      |       | Model          |              |  |
|------------|---------|------------------|------|-------|----------------|--------------|--|
| Appearance |         | Sensing distance |      |       | Operation mode |              |  |
|            |         |                  |      | NO    | NC             |              |  |
|            | 17 × 17 | <b>5</b> r       | nm   |       | TL-Q5MD1 2M    | TL-Q5MD2 2M  |  |
| Unshielded | 25 × 25 | 7                | mm   |       | TL-N7MD1 2M    | TL-N7MD2 2M  |  |
|            | 30 × 30 |                  | 12 m | m     | TL-N12MD1 2M   | TL-N12MD2 2M |  |
|            | 40 × 40 |                  |      | 20 mm | TL-N20MD1 2M   | TL-N20MD2 2M |  |

Note: Models with a different frequency are available to prevent mutual interference. The model numbers are TL-NIMDIS and TL-Q5MDIS (e.g., TL-N7MD15).

## DC 3-Wire and AC 2-Wire Models

|            |                    |              |                  |                |                       | Model                 |                           |  |
|------------|--------------------|--------------|------------------|----------------|-----------------------|-----------------------|---------------------------|--|
| Appear     | Appearance         |              | Sensing distance |                | Output configuration  | Operation mode        |                           |  |
|            |                    |              |                  |                |                       | NO                    | NC                        |  |
|            | 8×9                | <b>2</b> mn  | ņ                |                | – DC 3-wire, NPN      | TL-Q2MC1 2M           | _                         |  |
|            | 17 × 17            | <b>5</b> r   | nm               |                |                       | TL-Q5MC1 2M *2        | TL-Q5MC2 2M               |  |
|            | 25 × 25            | <b>– – –</b> |                  |                | DC 3-wire, NPN        | *1<br>TL-N5ME1 2M *2  | TL-N5ME2 2M <sup>*1</sup> |  |
| Unshielded |                    | 5 n          | nm               |                | AC 2-wire             | TL-N5MY1 2M           | TL-N5MY2 2M               |  |
|            | 30 × 30<br>40 × 40 | 10 mm        |                  | DC 3-wire, NPN | *1<br>TL-N10ME1 2M *2 | TL-N10ME2 2M *1       |                           |  |
|            |                    |              |                  | AC 2-wire      | TL-N10MY1 2M          | TL-N10MY2 2M          |                           |  |
|            |                    |              |                  | 20 mm          | DC 3-wire, NPN        | *1<br>TL-N20ME1 2M *2 | TL-N20ME2 2M              |  |
|            |                    |              |                  | 20 mm          | AC 2-wire             | TL-N20MY1 2M          | TL-N20MY2 2M              |  |
|            | Grooved            |              | 7.5 mm           |                | DC 3-wire, NPN        | TL-G3D-3 1M           | _                         |  |

Note: Models with a different frequency are available to prevent mutual interference. Models numbers for Sensors with different frequencies are TL-U\_M\_\_5 (example: TL-N5ME15).

\*1. Models are also available with 5-m cables. Add the cable length to the model number (example: TL-N5ME1 5M).

\*2. Models with robotics cables are also available. Add -R to the end of the model number (example: TL-N5ME1-R).

# **Accessories (Order Separately)**

Mounting Brackets A Mounting Bracket is provided with the Sensor depending on the model number. Check the column for the applicable Sensor. [Refer to Dimensions on page 12.]

| Туре                           | Model       | Applicable Sensors          |                     |  |
|--------------------------------|-------------|-----------------------------|---------------------|--|
| Туре                           | Woder       | Provided with these Sensors | Order separately    |  |
|                                | Y92E-C5     | TL-N5ME, TL-N7MD            | TL-N5MY             |  |
| Mounting Brackets              | Y92E-C10    | TL-N10ME , TL-N12MD         | TL-N10MY            |  |
|                                | Y92E-C20    | TL-N20ME , TL-N20MD         | TL-N20MY            |  |
| Mounting Brackets for Conduits | Y92E-N5C15  |                             | TL-N5ME, TL-N5MY    |  |
|                                | Y92E-N10C15 |                             | TL-N10ME , TL-N10MY |  |

# **Ratings and Specifications**

#### **DC 2-Wire Models**

| Item                                 | Model                     | TL-Q5MD   | TL-N7MD  | TL-N12MD   | TL-N20MD   |  |  |  |
|--------------------------------------|---------------------------|---|--|--|--|--|--|--|
| Sensing d                            | listance                  | 5 mm ±10%   | 7 mm ±10%  | 12 mm ±10%   | 20 mm ±10%   |  |  |  |
| Set distan                           | ce                        | 0 to 4 mm   | 0 to 5.6 mm  | 0 to 9.6 mm  | 0 to 16 mm   |  |  |  |
| Differentia                          | al travel                 | 0% max. of sensing distance   |  |  |  |  |  |  |
| Detectable                           | e object                  | Ferrous metal (The sensing distance decreases with non-ferrous metal. Refer to Engineering Data on page 5.)     |  |  |  |  |  |  |
| Standard :<br>object                 | sensing                   | Iron, $18 \times 18 \times 1$ mm  | Iron, $30 \times 30 \times 1 \text{ mm}$                                       | Iron, $40 \times 40 \times 1 \text{ mm}$                                       | Iron, $50 \times 50 \times 1 \text{ mm}$                                       |  |  |  |
| Response<br>frequency                |                           | 500 Hz 300 Hz   |  |  |  |  |  |  |
| Power sup<br>(operating<br>range)    | oply voltage<br>j voltage | 12 to 24 VDC (10 to 30 VDC), rip  | ple (p-p): 10% max.  |  |  |  |  |  |
| Leakage c                            | urrent                    | 0.8 mA max.   |  |  |  |  |  |  |
| Control                              | Load<br>current           | 3 to 100 mA   |  |  |  |  |  |  |
| output                               | Residual voltage          | 3.3 V max. (Load current: 100 m/  | A, Cable length: 2 m)  |  |  |  |  |  |
| Indicators                           | ;                         | D1 Models: Operation indicator (i<br>D2 Models: Operation indicator (i  |  |  |  |  |  |  |
| Operation<br>(with sens<br>approachi | sing object               | D1 Models: NO D2 Models: NC Refer to the timing charts under <i>I/O Circuit Diagrams</i> on page 7 for details. |  |  |  |  |  |  |
| Protectior                           | n circuits                | Load short-circuit protection, Sur  | ge suppressor  |  |  |  |  |  |
| Ambient<br>temperatu                 | ire range                 | Operating/Storage: –25 to 70°C (  | with no icing or condensation)   |  |  |  |  |  |
| Ambient<br>humidity r                | range                     | Operating/Storage: 35% to 95% (   | with no condensation)  |  |  |  |  |  |
| Temperate                            | ure influence             | $\pm 10\%$ max. of sensing distance a   | t 23°C in the temperature range of   | –25 to 70°C  |  |  |  |  |
| Voltage in                           | fluence                   | $\pm 2.5\%$ max. of sensing distance a  | at rated voltage in the rated voltage  | ±15% range   |  |  |  |  |
| Insulation                           | resistance                | 50 M $\Omega$ min. (at 500 VDC) betwee  | n current-carrying parts and case  |  |  |  |  |  |
| Dielectric                           | strength                  | 1,000 VAC for 1 min between cur   | rent-carrying parts and case   |  |  |  |  |  |
| Vibration<br>resistance              | •                         | Destruction: 10 to 55 Hz, 1.5-mm  | double amplitude for 2 hours each  | in X, Y, and Z directions  |  |  |  |  |
| Shock res                            | istance                   | Destruction: 500 m/s <sup>2</sup> 3 times each in X, Y, and Z directions  | Destruction: 1,000 m/s <sup>2</sup> 10 times                                   | each in X, Y, and Z directions   |  |  |  |  |
| Degree of                            | protection                | IEC 60529 IP67, in-house standa   | rds: oil-resistant   |  |  |  |  |  |
| Connectio                            | on method                 | Pre-wired Models (Standard cabl   | e length: 2 m)   |  |  |  |  |  |
| Weight (pa                           | acked state)              | Approx. 45 g  | Approx. 145 g  | Approx. 170 g  | Approx. 240 g  |  |  |  |
|                                      | Case                      |   |  |  |  |  |  |  |
| Materials                            | Sensing<br>surface        | Heat-resistant ABS  |  |  |  |  |  |  |
| Accessori                            | ies                       | Instruction manual  | Mounting Bracket,<br>Mounting phillips screws (M4 × 25),<br>Instruction manual | Mounting Bracket,<br>Mounting phillips screws (M4 × 30),<br>Instruction manual | Mounting Bracket,<br>Mounting phillips screws (M5 × 40),<br>Instruction manual |  |  |  |
|                                      |                           | 1   | 1  | 1  | l  |  |  |  |

\* The response frequency is an average value. Measurement conditions are as follows: standard sensing object, a distance of twice the standard sensing object, and a set distance of half the sensing distance.

# **DC 3-Wire Models**

| ltem   | Model   | TL-Q2MC1  | TL-Q5MC   | TL-G3D-3  |  |
|--|---|---|---|---|--|
| Sensing<br>distanc   |   | 2 mm ±15%   | 5 mm ±10%   | 7.5±0.5mm   |  |
| Set dist   | tance   | 0 to 1.5 mm   | 0 to 4 mm   | 10 mm   |  |
| Differer   | ntial travel  | 10% max. of sensing distance  |   | !   |  |
| Detecta  | able object   | Ferrous metal (The sensing distance de  | Engineering Data on page 6.)  |   |  |
| Standa<br>sensing  | rd<br>g object  | Iron, $8 \times 8 \times 1$ mm  | Iron, $15 \times 15 \times 1$ mm  | Iron, $10 \times 5 \times 0.5$ mm   |  |
| Respor   | nse time  |   | 2 ms max.   | 1 ms max.   |  |
| Respor<br>frequer  |   |   | 500 Hz  |   |  |
| Power supply<br>voltage(operating<br>voltage range)        |   | 12 to 24 VDC (10 to 30 VDC), ripple (p-p  | b): 10% max.  | 12 to 24 VDC, ripple (p-p): 5% max.   |  |
| Current<br>consun  |   | 15 mA max. at 24 VDC (no-load)  | 10 mA max. at 24 VDC  | 2 mA max. at 24 VDC (no-load)   |  |
| Con-<br>trol   | Load<br>current   | NPN open collector<br>100 mA max. at 30 VDC max.  | NPN open collector<br>50 mA max. at 30 VDC max.                                     | NPN transistor output<br>20 mA max.   |  |
| output   | Residual voltage  | 1 V max. (under load current of 100 mA with cable length of 2 m) $$                           | 1 V max. (under load current of 50 mA with cable length of 2 m)                     |   |  |
| Indicate   | ors   | Detection indicator (red)   |   |   |  |
| (with se   | ion mode<br>ensing ob-                                  | NO  | C1 Models: NO<br>C2 Models: NC  | NO  |  |
| ect approaching) Refer to the timing charts under I/O Circ |   | Refer to the timing charts under I/O Circ   | uit Diagrams on page 7 for details.   |   |  |
|  | Protection<br>circuits Reverse polarity protection, Sur |   | ressor  | Surge suppressor  |  |
| Ambier<br>tempera<br>range                                 |   | Operating/Storage: -10 to 60°C (with no icing or condensation)                                | Operating/Storage: -25 to 70°C (with no icing or condensation)                      |   |  |
| Ambier<br>humidi   | nt<br>ty range  | Operating/Storage: 35% to 95% (with no  | o condensation)   |   |  |
| Tempei<br>influen  |   | $\pm 10\%$ max. of sensing distance at 23°C in the temperature range of $-10$ to $60^\circ C$ | $\pm 20\%$ max. of sensing distance at 23°C in the temperature range of –25 to 70°C | $\pm 10\%$ max. of sensing distance at 23°C in the temperature range of –10 to 55°C |  |
| Voltage<br>influen   |   | ±2.5% max. of sensing distance at rated   | voltage in rated voltage $\pm 10\%$ range   |   |  |
| Insulati<br>resistai                                       |   | 50 $\mbox{M}\Omega$ min. (at 500 VDC) between current-carrying parts and case                 | 5 M $\Omega$ min. (at 500 VDC) between currer                                       | nt-carrying parts and case  |  |
| Dielect<br>strengt   |   | 1,000 VAC for 1 min between current-<br>carrying parts and case                               | 500 VAC, 50/60 Hz for 1 min between c   | urrent-carrying parts and case  |  |
| Vibratio<br>resista  |   |   | e amplitude for 2 hours each in X, Y, and   | Z directions  |  |
| Shock  | resistance  | Destruction: 1,000 m/s <sup>2</sup> 10 times each<br>in X, Y, and Z directions                | Destruction: 200 m/s <sup>2</sup> 10 times each in 3                                | 0 times each in X, Y, and Z directions  |  |
| Degree<br>protect  |   | IEC 60529 IP67,<br>in-house standards: oil-resistant  | IEC IP67  | IEC IP66  |  |
| Connec<br>method   |   | Pre-wired Models (Standard cable lengtl   | n: 2 m)   | Pre-wired Models<br>(Standard cable length: 1m)                                     |  |
| Weight<br>(packed  | d state)  | Approx. 30 g  | Approx. 60 g  | Approx. 30 g  |  |
| Mate-<br>rials   | Case<br>Sensing   | Heat-resistant ABS  |   | PPO, etc.<br>(Refer to page 11)   |  |
|  | surface   |   | Γ   |   |  |
| Access   | ories   | Instruction manual  | -   |   |  |

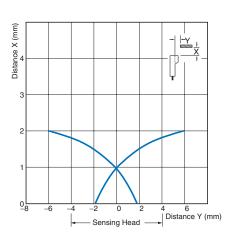
\* The response frequency is an average value. Measurement conditions are as follows: standard sensing object, a distance of twice the standard sensing object, and a set distance of half the sensing distance.

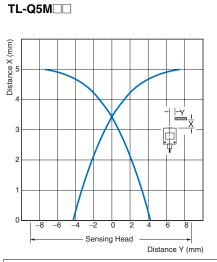
| Item                    | Model   | TL-N5ME , TL-N5MY  | TL-N10ME , TL-N10MY  | TL-N20ME , TL-N20MY  |  |
|-------------------------|---|--|--|--|--|
| Sensing                 | distance  | 5 mm ±10%  | 10 mm ±10%   | 20 mm ±10%   |  |
| Set dista               | nce   | 0 to 4 mm  | 0 to 8 mm  | 0 to 16 mm   |  |
| Differenti              | ial travel  | 15% max. of sensing distance   |  | +  |  |
| Detectab                | le object   | Ferrous metal (The sensing distance de   | creases with non-ferrous metal. Refer to   | Engineering Data on pages 6 and 7.)  |  |
| Standard sensing object |   | Iron, $30 \times 30 \times 1 \text{ mm}$   | Iron, $40 \times 40 \times 1 \text{ mm}$   | Iron, $50 \times 50 \times 1 \text{ mm}$   |  |
| Response<br>frequency   | equency *1 E Models: 500 Hz E Models: 40 Hz Y Models: 10 Hz Y Models: 10 Hz   |  |  |  |  |
| voltage *               | Power supply         voltage *2         (operating voltage range)    E Models: 12 to 24 VDC (10 to 30 VDC), ripple (p-p): 10% max. Y Models: 100 to 220 VAC (90 to 250 VAC), 50/60 Hz |  |  |  |  |
| Current<br>consump      | otion   | E Models: 8 mA max. at 12 VDC, 15 mA   | A max. at 24 VDC   |  |  |
| Leakage                 | current   | Y Models: Refer to Engineering Data or   | page 5.  |  |  |
| Control                 | Load<br>current   | E Models: 100 mA max. at 12 VDC, 200<br>Y Models: 10 to 200 mA   | ) mA max. at 24 VDC  |  |  |
| output                  | Residual voltage  | E Models: 1 V max. (load current: 200 n<br>Y Models: Refer to <i>Engineering Data</i> or                                 |  |  |  |
| Indicators              | s   | E Models: Detection indicator (red)<br>Y Models: Operation indicator (red)   |  |  |  |
| Operation<br>(with sen  |   | E1/Y1 Models: NO<br>E2/Y2 Models: NC   |  |  |  |
| ject appro              | approaching) Refer to the timing charts under I/O Circuit Diagrams on page 8 for details.   |  |  |  |  |
| Protectio               | on circuits   | E Models: Reverse polarity protection, S<br>Y Models: Surge suppressor   | Surge suppressor   |  |  |
| Ambient<br>temperat     | perature range Operating/Storage: -25 to 70°C (with no icing or condensation)   |  |  |  |  |
| Ambient<br>humidity     |   | Operating/Storage: 35% to 95% (with no   | o condensation)  |  |  |
| Temperat                |   | $\pm 10\%$ max. of sensing distance at 23°C  | in the temperature range of -25 to 70°C  |  |  |
| Voltage i               | nfluence  |  | tice at rated voltage in rated voltage $\pm 10^{\circ}$ e at rated voltage in rated voltage $\pm 10\%$                   |  |  |
| Insulation<br>resistanc |   | 50 M $\Omega$ min. (at 500 VDC) between curre  | ent-carrying parts and case  |  |  |
| Dielectric              | c strength  |  | in between current-carrying parts and ca<br>in between current-carrying parts and ca                                     |  |  |
| Vibration resistanc     |   | Destruction: 10 to 55 Hz, 1.5-mm double  | e amplitude for 2 hours each in X, Y, and  | Z directions   |  |
| Shock re                | sistance  | Destruction: 500 m/s <sup>2</sup> 10 times each in 2   | X, Y, and Z directions   |  |  |
| Degree o<br>protectio   |   | IEC 60529 IP67, in-house standards: oi   | -resistant   |  |  |
| Connecti<br>method      | on  | Pre-wired Models (Standard cable lengt   | h: 2 m)  |  |  |
| Weight<br>(packed s     | state)  | Approx. 145 g  | Approx. 170 g  | Approx. 240 g  |  |
| Materi                  | Case  |  |  | ·  |  |
| Materi-<br>als          | Sensing surface   | Heat-resistant ABS   |  |  |  |
| Accesso                 | ries  | E Models: Mounting Bracket,<br>Mounting phillips screws (M4 × 25),<br>Instruction manual<br>Y Models: Instruction manual | E Models: Mounting Bracket,<br>Mounting phillips screws (M4 × 30),<br>Instruction manual<br>Y Models: Instruction manual | E Models: Mounting Bracket,<br>Mounting phillips screws (M5 × 40),<br>Instruction manual<br>Y Models: Instruction manual |  |

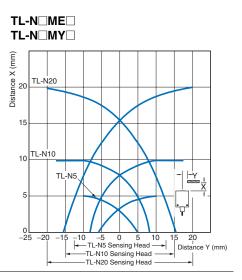
\*1. The response frequency is an average value. Measurement conditions are as follows: standard sensing object, a distance of twice the standard sensing object, and a set distance of half the sensing distance.
 \*2. E Models (DC switching models): A full-wave rectification power supply of 24 VDC ±10% (average value) can be used.

# **Engineering Data (Typical)**

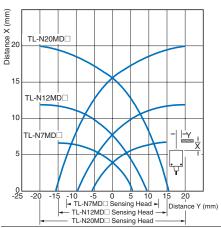
# Sensing Area TL-Q2MC1



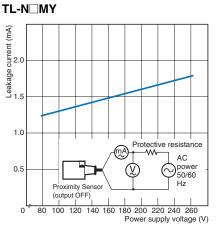






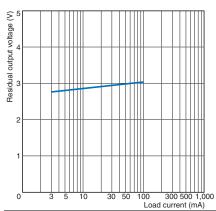


# Leakage Current

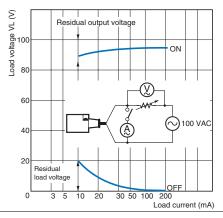


# **Residual Output Voltage**

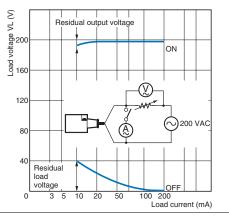
# TL-N MD



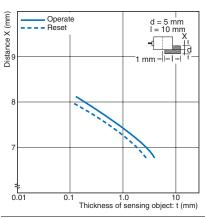
## TL-N MY at 100 VAC



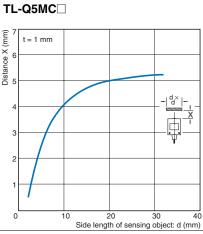
#### TL-N MY at 200 VAC

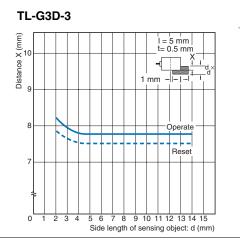


# Thickness of Sensing Object vs. Sensing Distance TL-G3D-3

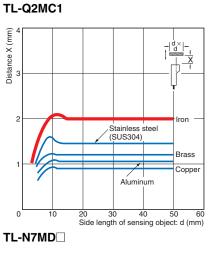


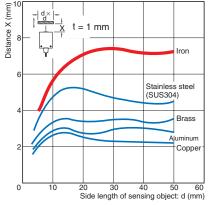
## Sensing Object Size vs. Sensing Distance

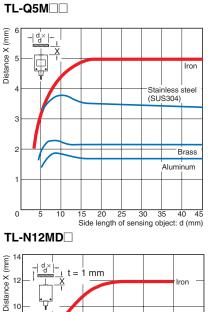


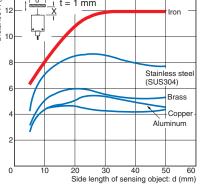


# Influence of Sensing Object Size and Material

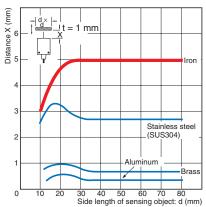




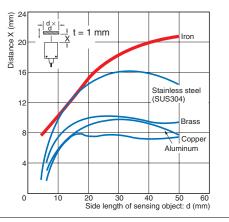


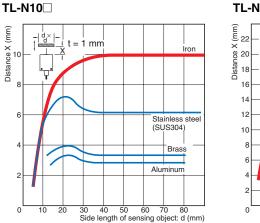




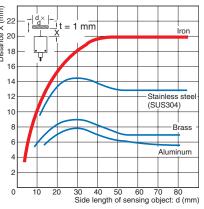


#### TL-N20MD



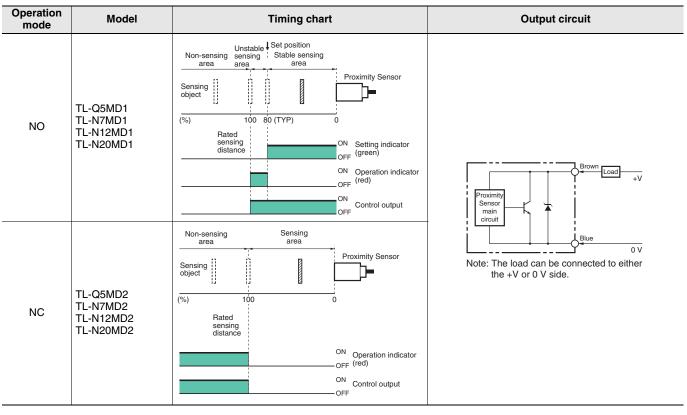






# I/O Circuit Diagrams

#### **DC 2-Wire Models**



## **DC 3-Wire Models**

| Operation<br>mode    | Model                              | Timing chart  | Output circuit  |
|----------------------|------------------------------------|---|---|
| NO                   | TL-Q2MC1<br>TL-Q5MC1               | Sensing object Present Not present Output transistor (load) Detection indicator (red) OFF OFF OFF OFF   | Proximity<br>Sensor   |
| NC                   | TL-Q5MC2                           | Sensing object Present<br>Not present<br>Output transistor<br>(load) OFF<br>Detection indicator<br>(red) OFF  | * Load current: 100 mA max., TL-Q2MC1<br>Load current: 50 mA max., TL-Q5MC1 |
| NO                   | TL-N5ME1<br>TL-N10ME1<br>TL-N20ME1 | Sensing object     Present<br>Not present       Load (between brown<br>and black leads)     Operate<br>Reset       Output voltage (between<br>black and blue leads)     High<br>Low       Detection indicator (red)     ON<br>OFF | Proximity<br>Sensor<br>main<br>simula<br>H = 2,2 Ω (Output)                 |
| NC                   | TL-N5ME2<br>TL-N10ME2<br>TL-N20ME2 | Sensing object     Present<br>Not present       Load (between brown<br>and black leads)     Operate<br>Reset       Output voltage (between<br>black and blue leads)     High<br>Low       Detection indicator (red)     ON<br>OFF | *1. Load current: 200 mA max.<br>*2. When a transistor is connected.        |
| Transistor<br>output | TL-G3D-3                           | Present<br>Not present<br>Output transistor<br>(load)<br>OFF  | Proximity<br>Sensor<br>main<br>circuit<br>* Load current: 20 mA max.        |

# AC 2-Wire Models

| Operation<br>mode | Model                              | Timing chart  | Output circuit      |
|-------------------|------------------------------------|---|---------------------|
| NO                | TL-N5MY1<br>TL-N10MY1<br>TL-N20MY1 | Sensing object Present<br>Not present<br>Load Operate<br>Reset<br>Operation indicator (red) ON<br>OFF | Proximity<br>Sensor |
| NC                | TL-N5MY2<br>TL-N10MY2<br>TL-N20MY2 | Sensing object Present<br>Not present<br>Load Operate<br>Reset<br>Operation indicator (red) ON<br>OFF | Blue                |

# **Safety Precautions**

# Refer to Warranty and Limitations of Liability.

# <u> WARNING</u>

This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.

- $\bigcirc$
- Do not short-circuit the load, otherwise the Sensor may be damaged.
- Do not supply power to the Sensor with no load, otherwise the Sensor may be damaged. Applicable Models: AC 2-Wire Models

# Precautions for Correct Use

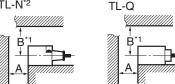
Do not use this product under ambient conditions that exceed the ratings.

# Design

#### Influence of Surrounding Metal

When mounting the Sensor within a metal panel, ensure that the clearances given in the following table are maintained. Failure to maintain these distances may cause deterioration in the performance of the Sensor.

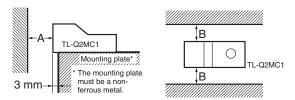
#### Rectangular Models TL-N\*2



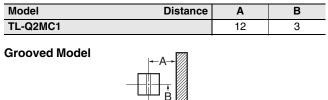
#### Influence of Surrounding Metal (Unit: mm)

| Model Distance     | Α  | B *1 |
|--------------------|----|------|
| TL-Q5M             | 20 | 20   |
| TL-N7MD            | 40 | 35   |
| TL-N12MD           | 50 | 40   |
| TL-N20MD           | 70 | 60   |
| TL-N5ME, TL-N5MY   | 20 | 23   |
| TL-N10ME, TL-N10MY | 40 | 30   |
| TL-N20ME, TL-N20MY | 80 | 45   |

\*1. The B dimension applies to the top, right-side, and left-side surfaces.
\*2. The values for A or B for the TL-N apply when there is metal on only one side of the sensor. If there is metal on two or more sides, the value must be multiplied by two or more.



# Influence of Surrounding Metal (Unit: mm)



| Influence of Surrounding Metal (Unit: mm) |          |   |  |
|---|----------|---|--|
| Model                                     | Distance | ۸ |  |

| wodei    | Distance | A  | в  |
|----------|----------|----|----|
| TL-G3D-3 |          | 11 | 17 |
|          |          |    |    |

#### **Mutual Interference**

When installing Sensors face-to-face or side-by-side, ensure that the minimum distances given in the following table are maintained.

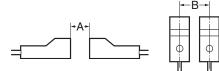
Parallel A-

Face-to-face

#### Mutual Interference (Unit: mm)

| Model Dis          | ance | Α*        | В*        |
|--------------------|------|-----------|-----------|
| TL-Q5MC            |      | 60 (17)   | 120 (60)  |
| TL-Q5MD            |      | 60 (30)   | 120 (80)  |
| TL-N7MD            |      | 100 (50)  | 120 (60)  |
| TL-N12MD           |      | 120 (60)  | 200 (100) |
| TL-N20MD           |      | 200 (100) | 200 (100) |
| TL-N5ME            |      | 80 (40)   | 80 (40)   |
| TL-N5MY            |      | 80 (40)   | 90 (40)   |
| TL-N10ME, TL-N10MY |      | 120 (60)  | 120 (60)  |
| TL-N20ME, TL-N20MY |      | 200 (100) | 120 (60)  |

\* Values in parentheses apply to Sensors operating at different frequencies.

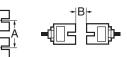


# Mutual Interference (Unit: mm)

| Model Distance | e A*    | В*     |
|----------------|---------|--------|
| TL-Q2MC1       | 90 (45) | 30 (8) |

\* Values in parentheses apply to Sensors operating at different frequencies.

#### **Grooved Model**

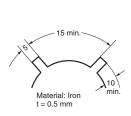


## Mutual Interference (Unit: mm)

| Model    | Distance | Α  | В  |
|----------|----------|----|----|
| TL-G3D-3 |          | 31 | 25 |

# Designing the Sensing Object for TL-G3D-3 Grooved Model

For high-speed response to a toothed metal plate, the sensing objects must be at least the size of the standard sensing object and there must be sufficient distance between sensing objects. The response frequency for a toothed wheel like the one shown at the right is 1 kHz min. The response frequency will be reduced if the wheel is smaller or the width of the teeth or the distance between the teeth is reduced.



Adjustment

**Grooved Model** 

must be 1 mm or less.

# Mounting

When tightening the mounting screws, do not exceed the torque in the following table.

| Model    | Torque         |  |
|----------|----------------|--|
| TL-Q2MC1 | 0.59 N·m       |  |
| TL-Q5M   |                |  |
| TL-N     | 0.9 to 1.5 N·m |  |
| TL-G3D-3 | 2 N⋅m          |  |
|          |                |  |

# **Dimensions**

(Unit: mm) Tolerance class IT16 applies to dimensions in this data sheet unless otherwise specified.

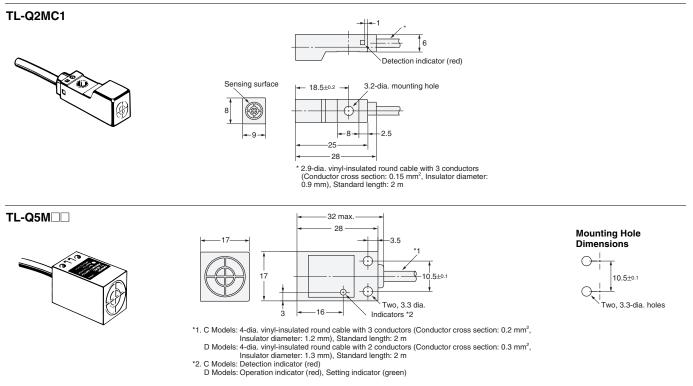
Sensing Object Passing Position for the TL-G3D-3

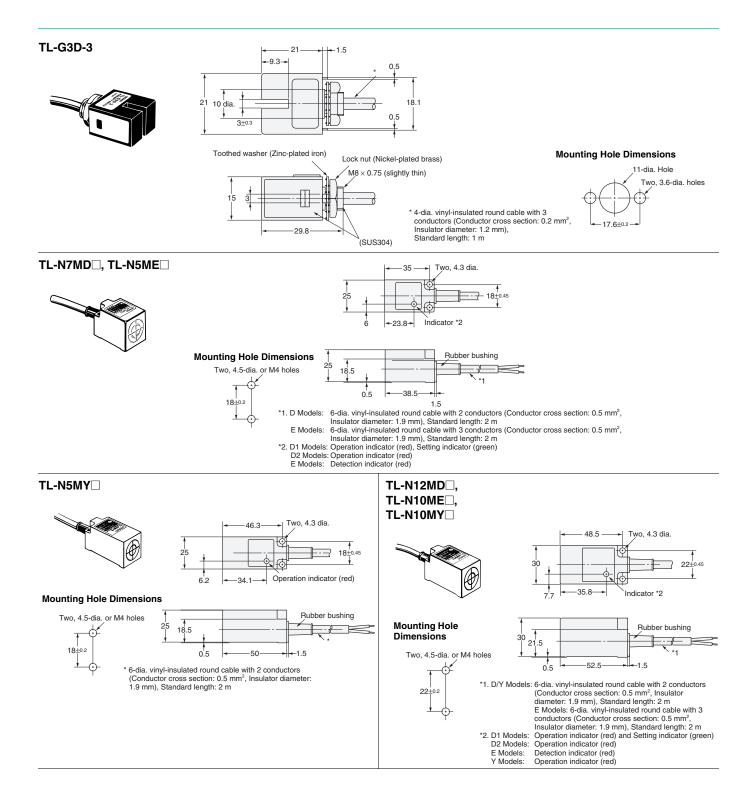
The gap between the sensing object and the bottom of the groove

1 mm max

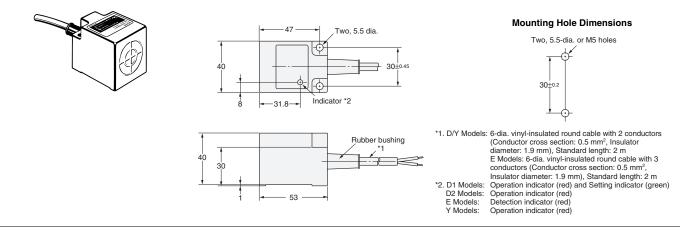
Sensing object

# Sensors

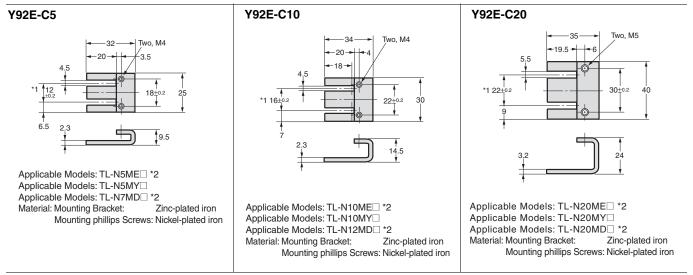




## TL-N20MD, TL-N20ME, TL-N20MY



## Accessories (Order Separately) Mounting Bracket

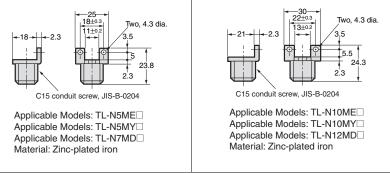


\*1. These are the mounting dimensions of the base of the Mounting Bracket.

\*2. Provided with the product.

# Mounting Brackets for Wiring Conduit Use (Sold Separately)

# Y92E-N5C15



Y92E-N10C15

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