# MTi-630

- Small, IP51-rated AHRS
- 0.2 deg roll/pitch, 1 deg heading accuracy
- Full Graphical User Interface (GUI) and

Software Development Kit (SDK) available

The MTi-630 is an Attitude and Heading Reference System with a small form-factor design for deep integration into your application. Building on the proven Xsens MTi 600-series technology it enables a robust and easy to use orientation tracking. It is designed for easy integration and seamless interfacing with other equipment.

The MTi-630 is supported by the MT Software Suite which includes MT Manager (GUI for Windows/Linux), SDK, example codes and drivers for many platforms including ROS.



- White label and OEM integration options available
- 3D models available on request

#### **Sensor Fusion Performance**

Roll, Pitch	0.2 deg RMS
Yaw/Heading	1 deg RMS
Strandown Integration (SDI)	Yes

# Gyroscope

Standard full range —————	2000 deg/s
In-run bias stability	8 deg/h
Bandwidth (-3dB)	520 Hz
Noise Density	0.007 $^{\rm o}/{\rm s}/\sqrt{\rm Hz}$
g-sensitivity (calibr.)	0.1 °/s/g

#### **Accelerometer**

Standard full range	10 g
In-run bias stability	10 (x,y) 15(z) μg
Bandwidth (-3dB)	500 Hz
Noise Density	60 μg/√Hz

## Magnetometer

Standard full range	+/- 8 G
Total RMS noise	1 mG
Non-linearity	0.2%
Resolution ————————————————————————————————————	0.25 mG

## **Barometer**

Standard full range	300-1250 hPa
Total RMS noise	1.2 Pa
Relative accuracy	+/- 8 Pa (~0.5m)

This document is informational and not binding.

Complete and detailed specifications are available at 
mtidocs.movella.com

#### Mechanical

IP-rating	IP51
Operating Temperature ——	-40 to 85 °C
Casing material	PC-ABS
Mounting orientation ————	No restriction, full 360° in all axes
Dimensions ————	28x31.5x13 mm
Connector —	Main: Phoenix Contact 16 pin, 1.27 mm
	pitch
Weight ————	8.9 g
Certifications	CE, FCC, RoHS
Electrical	

# Electrical

Input voltage —————	4.5 to 24V
Power consumption (typ) —	<0.5 W

## Interfaces / IO

Turkeuferee	UART, CAN, RS232
Interfaces ——————	UARI, CAN, RS232
Sync Options	SyncIn, SyncOut, ClockSync
Protocols	Xbus, ASCII (NMEA) or CAN
Clock drift	10 ppm (or external)
Output Frequency	Up to 2 kHz, 400 Hz SDI
Built-in-self test	Gyr, Acc, Mag, Baro

<b>Software Suite</b>	
GUI (Windows/Linux)	MT Manager, Firmware updater,
	Magnetic Field Mapper
SDK (Example code)	C++, C#, Python, Matlab, Nucleo,
	public source code
Drivers ————	LabVIEW, ROS, GO
Support	Online manuals, community and
	knowledge base



