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FSB32560 Motion SPM[®] 3 Series

Features

- UL Certified No. E209204 (UL1557)
- 600 V 25 A 3-Phase IGBT Inverter with Integral Gate Drivers and Protection
- Low-Loss, Short-Circuit Rated IGBTs
- Low Thermal Resistance Using Ceramic Substrate
- Dedicated Vs Pins Simplify PCB Layout
- Separate Open-Emitter Pins from Low-Side IGBTs for Three-Phase Current Sensing
- Single-Grounded Power Supply
- Isolation Rating: 2500 V_{rms} / min.

Applications

• Motion Control - Home Appliance / Industrial Motor

Related Resources

• AN-9035 - Motion SPM 3 Series Ver.2 User's Guide

General Description

FSB32560 is a Motion SPM[®] 3 module providing a fullyfeatured, high-performance inverter output stage for AC Induction, BLDC, and PMSM motors. These modules integrate optimized gate drive of the built-in IGBTs to minimize EMI and losses, while also providing multiple on-module protection features including under-voltage lockouts, over-current shutdown, and fault reporting. The built-in, high-speed HVIC requires only a single supply voltage and translates the incoming logic-level gate inputs to the high-voltage, high-current drive signals required to properly drive the module's internal IGBTs. Separate negative IGBT terminals are available for each phase to support the widest variety of control algorithms.

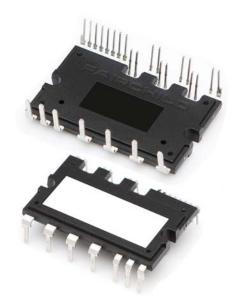


Figure 1. Package Overview

Package Marking and Ordering Information

Device	Device Marking	Package	Packing Type	Quantity
FSB32560	FSB32560	SPMBA-027	Rail	10

September 2014

Integrated Power Functions

• 600 V - 25 A IGBT inverter for three-phase DC / AC power conversion (please refer to Figure 3)

Integrated Drive, Protection and System Control Functions

For inverter high-side IGBTs: gate drive circuit, high-voltage isolated high-speed level shifting
 control circuit Under-Voltage Lock-Out Protection (UVLO)

Note: Available bootstrap circuit example is given in Figures 10 and 11.

- For inverter low-side IGBTs: gate drive circuit, Short-Circuit Protection (SCP)
 control supply circuit Under-Voltage Lock-Out Protection (UVLO)
- Fault signaling: corresponding to UVLO (low-side supply) and SC faults
- Input interface: active-HIGH interface, works with 3.3 / 5 V logic, Schmitt-trigger input

Pin Configuration

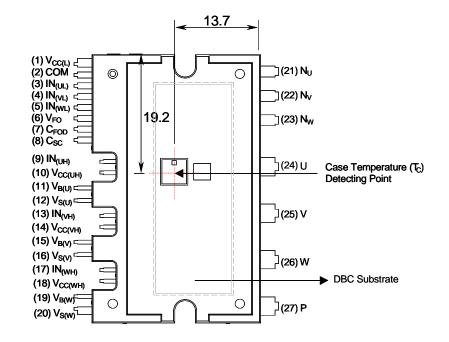


Figure 2. Top View

Pin Number	Pin Name	Pin Description
1	V _{CC(L)}	Low-Side Common Bias Voltage for IC and IGBTs Driving
2	СОМ	Common Supply Ground
3	IN _(UL)	Signal Input for Low-Side U-Phase
4	IN _(VL)	Signal Input for Low-Side V-Phase
5	IN _(WL)	Signal Input for Low-Side W-Phase
6	V _{FO}	Fault Output
7	C _{FOD}	Capacitor for Fault Output Duration Selection
8	C _{SC}	Capacitor (Low-pass Filter) for Short-Circuit Current Detection Input
9	IN _(UH)	Signal Input for High-Side U-Phase
10	V _{CC(UH)}	High-Side Bias Voltage for U-Phase IC
11	V _{B(U)}	High-Side Bias Voltage for U-Phase IGBT Driving
12	V _{S(U)}	High-Side Bias Voltage Ground for U-Phase IGBT Driving
13	IN _(VH)	Signal Input for High-Side V-Phase
14	V _{CC(VH)}	High-Side Bias Voltage for V-Phase IC
15	V _{B(V)}	High-Side Bias Voltage for V-Phase IGBT Driving
16	V _{S(V)}	High-Side Bias Voltage Ground for V-Phase IGBT Driving
17	IN _(WH)	Signal Input for High-Side W Phase
18	V _{CC(WH)}	High-Side Bias Voltage for W-Phase IC
19	V _{B(W)}	High-Side Bias Voltage for W-Phase IGBT Driving
20	V _{S(W)}	High-Side Bias Voltage Ground for W-Phase IGBT Driving
21	NU	Negative DC-Link Input for U-Phase
22	N _V	Negative DC-Link Input for V-Phase
23	N _W	Negative DC-Link Input for W-Phase
24	U	Output for U-Phase
25	V	Output for V-Phase
26	W	Output for W-Phase
27	Р	Positive DC-Link Input

Internal Equivalent Circuit and Input/Output Pins P (27) (19) V_{B(} VB (18) V_{CC(WH)} VCC OUT СОМ (17) IN_{(WI} VS W (26) IN (20) V_{S(W)} (15) V_{B(V)} VB (14) V_{CC(VH} VCC OUT СОМ (13) IN_(V) IN VS V (25) (16) V_{S(V)} (11) V_{B(U)} VB (10) V_{CC(UH)} VCC OUT сом (9) IN_(UH) VS U (24) IN ζ(12) V_{S(U)} (8) C_{SC} C(SC) OUT(WL) (7) C_{FOD} C(FOD) N_w (23) (6) V_{FO} VFO (5) IN_(WL) OUT(VL) IN(WL) (4) IN_(VL) IN(VL) N_V (22) (3) IN_{(UL} IN(UL) (2) COM сом OUT(UL) (1) V_{CC(L)} VCC V_{SL} N_U (21)

Figure 3. Internal Block Diagram

1st Notes:

1. Inverter low-side is composed of three IGBTs, freewheeling diodes for each IGBT, and one control IC. It has gate drive and protection functions.

2. Inverter power side is composed of four inverter DC-link input terminals and three inverter output terminals.

3. Inverter high-side is composed of three IGBTs, freewheeling diodes, and three drive ICs for each IGBT.





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Absolute Maximum Ratings ($T_J = 25^{\circ}C$, unless otherwise specified.)

Inverter Part

Symbol	Parameter	Conditions	Rating	Unit
V _{PN}	Supply Voltage	Applied between P- N_U , N_V , N_W	450	V
V _{PN(Surge)}	Supply Voltage (Surge)	Applied between P- N_U , N_V , N_W	500	V
V _{CES}	Collector - Emitter Voltage		600	V
± I _C	Each IGBT Collector Current	$T_{\rm C} = 25^{\circ}{\rm C}$	25	А
		$T_{\rm C} = 100^{\circ}{\rm C}$	12	А
P _C	Collector Dissipation	T _C = 25°C per Chip	29	W
ТJ	Operating Junction Temperature	(2nd Note 1)	-20 ~ 125	°C

2nd Notes:

1. The maximum junction temperature rating of the power chips integrated within the Motion SPM^(®) 3 product is 150°C (at $T_C \le 100°$ C). However, to insure safe operation of the Motion SPM 3 product, the average junction temperature should be limited to $T_{J(ave)} \le 125°$ C (at $T_C \le 100°$ C)

Control Part

Symbol	Parameter	Conditions	Rating	Unit	
V _{CC}	Control Supply Voltage	Applied between V _{CC(UH)} , V _{CC(VH)} , V _{CC(WH)} , V _{CC(L)} - COM	20	V	
V_{BS}	High-Side Control Bias Voltage	Applied between V_B(U) - V_S(U), V_B(V) - V_S(V), V_B(W) - V_S(W)	20	V	
V _{IN}	Input Signal Voltage	Applied between $\rm IN_{(UH)},~\rm IN_{(VH)},~\rm IN_{(WH)},~\rm IN_{(UL)},~\rm IN_{(VL)},~\rm IN_{(VL)},~\rm IN_{(WL)}$ - COM	-0.3 ~ 17	V	
V _{FO}	Fault Output Supply Voltage	Applied between V _{FO} - COM	-0.3 ~ V _{CC} +0.3	V	
I _{FO}	Fault Output Current	Sink Current at V _{FO} Pin	5	mA	
V _{SC}	Current-Sensing Input Voltage	Applied between C _{SC} - COM	$-0.3 \sim V_{CC}+0.3$	V	

Total System

Symbol	Parameter	Conditions	Rating	Unit
V _{PN(PROT)}	Self-Protection Supply Voltage Limit (Short-Circuit Protection Capability)	$V_{CC} = V_{BS} = 13.5 \sim 16.5 \text{ V}$ T _J = 125°C, Non-Repetitive, < 2 µs	400	V
т _с	Module Case Operation Temperature	-20°C \leq T _J \leq 125°C, See Figure 2	-20 ~ 100	°C
T _{STG}	Storage Temperature		-40 ~ 125	°C
V _{ISO}	Isolation Voltage	60 Hz, Sinusoidal, AC 1 Minute, Connect Pins to Heat Sink Plate	2500	V _{rms}

Thermal Resistance

Symbol	Parameter	Condition	Min.	Тур.	Max.	Unit
R _{th(j-c)Q}	Junction to Case Thermal	Inverter IGBT Part (per 1 / 6 module)	-	-	3.5	°C/W
R _{th(j-c)F}	Resistance	Inverter FWD Part (per 1 / 6 module)	-	-	4.7	°C/W

2nd Notes:

2. For the measurement point of case temperature(T_C), please refer to Figure 2.

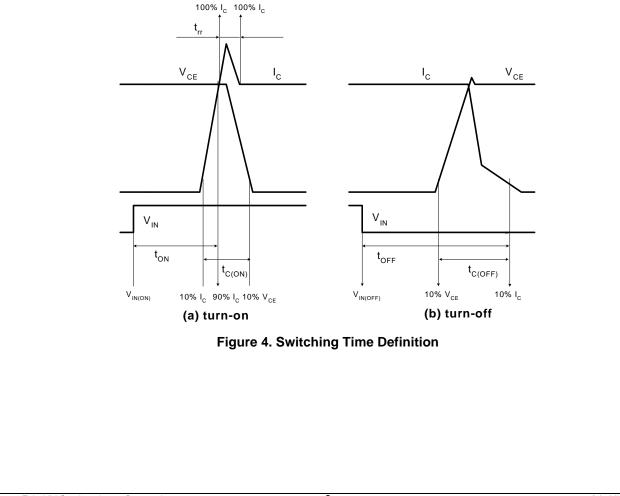
Electrical Characteristics ($T_J = 25^{\circ}C$, unless otherwise specified.)

Inverter Part

S	ymbol	Parameter	Cond	itions	Min.	Тур.	Max.	Unit
V	CE(SAT)	Collector - Emitter Saturation Voltage			2.15	2.85	V	
	V _F	FWDi Forward Voltage	V _{IN} = 0 V	$I_{\rm C} = 25 \text{ A}, \text{ T}_{\rm J} = 25^{\circ} \text{C}$	-	2.20	2.90	V
HS	t _{ON}	Switching Times	$\label{eq:VPN} \begin{array}{l} V_{PN} = 300 \; V, \; V_{CC} = V_{BS} = 15 \; V \\ I_{C} = 12 \; A \\ V_{IN} = 0 \; V \leftrightarrow 5 \; V, \; Inductive \; \mathsf{Load} \\ (2nd \; Note \; 3) \end{array}$		-	0.31	-	μS
	t _{C(ON)}				-	0.15	-	μS
	t _{OFF}				-	0.90	-	μS
	t _{C(OFF)}				-	0.34	-	μS
	t _{rr}				-	0.10	-	μS
LS	t _{ON}		$V_{PN} = 300 \text{ V}, V_{CC} = V_{B2}$	_S = 15 V	-	0.58	-	μS
	t _{C(ON)}		$I_{C} = 12 \text{ A}$ $V_{IN} = 0 \text{ V} \leftrightarrow 5 \text{ V}$, Induct	tive Load	-	0.30	-	μS
	t _{OFF}		(2nd Note 3)		-	0.96	-	μS
	t _{C(OFF)}				-	0.37	-	μS
	t _{rr}]			-	0.10	-	μS
	I _{CES}	Collector - Emitter Leakage Current	$V_{CE} = V_{CES}$		-	-	250	μA

2nd Notes:

3. t_{ON} and t_{OFF} include the propagation delay of the internal drive IC. t_{C(ON)} and t_{C(OFF)} are the switching time of IGBT itself under the given gate driving condition internally. For the detailed information, please see Figure 4.



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Electrical Characteristics ($T_J = 25^{\circ}C$, unless otherwise specified.)

Symbol	Parameter	Co	nditions	Min.	Тур.	Max.	Unit
IQCCL	Quiescent V _{CC} Supply Current	V _{CC} = 15 V IN _(UL, VL, WL) = 0 V	V _{CC(L)} - COM	-	-	23	mA
I _{QCCH}		V _{CC} = 15 V IN _(UH, VH, WH) = 0 V	V _{CC(UH)} , V _{CC(VH)} , V _{CC(WH)} - COM	-	-	200	μA
I _{QBS}	Quiescent V _{BS} Supply Current	V _{BS} = 15 V IN _(UH, VH, WH) = 0 V	$ \begin{array}{l} V_{B(U)} \mbox{-} V_{S(U)}, \ V_{B(V)} \mbox{-} V_{S(V)}, \\ V_{B(W)} \mbox{-} V_{S(W)} \end{array} $	-	-	500	μA
V _{FOH}	Fault Output Voltage	V_{SC} = 0 V, V_{FO} Circuit: 4.7 k Ω to 5 V Pull-up		4.5	-	-	V
V _{FOL}		V_{SC} = 1 V, V_{FO} Circuit: 4.7 k Ω to 5 V Pull-up		-	-	0.8	V
V _{SC(ref)}	Short Circuit Current Trip Level	V _{CC} = 15 V (2nd Note 4)		0.45	0.50	0.55	V
UV _{CCD}	Supply Circuit Under-Voltage	Detection Level		10.7	11.9	13.0	V
UV _{CCR}	Protection	Reset Level		11.2	12.4	13.2	V
UV _{BSD}		Detection Level		10	11	12	V
UV _{BSR}		Reset Level		10.5	11.5	12.5	V
t _{FOD}	Fault-out Pulse Width	C _{FOD} = 33 nF (2nd Note 5)		1.0	1.8	-	ms
V _{IN(ON)}	ON Threshold Voltage		_(UH) , IN _(VH) , IN _(WH) , IN _(UL) ,	3.0	-	-	V
V _{IN(OFF)}	OFF Threshold Voltage	IN _(VL) , IN _(WL) - COM		-	-	0.8	V

2nd Notes:

4. Short-circuit protection is functioning only at the low-sides.

5. The fault-out pulse width t_{FOD} depends on the capacitance value of C_{FOD} according to the following approximate equation: C_{FOD} = 18.3 x 10⁻⁶ x t_{FOD} [F]

Recommended Operating Conditions

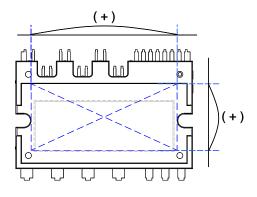
Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
V _{PN}	Supply Voltage	Applied between P - N_U , N_V , N_W	-	300	400	V
V _{CC}	Control Supply Voltage	Applied between V _{CC(UH)} , V _{CC(VH)} , V _{CC(WH)} , V _{CC(UH)} , V _{CC(UH)} ,	13.5	15	16.5	V
V _{BS}	High-Side Bias Voltage	Applied between V_B(U) - V_S(U), V_B(V) - V_S(V), V_B(W) - V_S(W)	13.0	15	18.5	V
dV _{CC} / dt, dV _{BS} / dt	Control Supply Variation		-1	-	1	V / μs
t _{dead}	Blanking Time for Preventing Arm-Short	For Each Input Signal	2.0	-	-	μS
f _{PWM}	PWM Input Signal	$-20^\circ C \leq T_C \leq 100^\circ C, \ -20^\circ C \leq T_J \leq 125^\circ C$	-	-	20	kHz
V_{SEN}	Voltage for Current Sensing	Applied between N _U , N _V , N _W - COM (Including Surge Voltage)	-4		4	V

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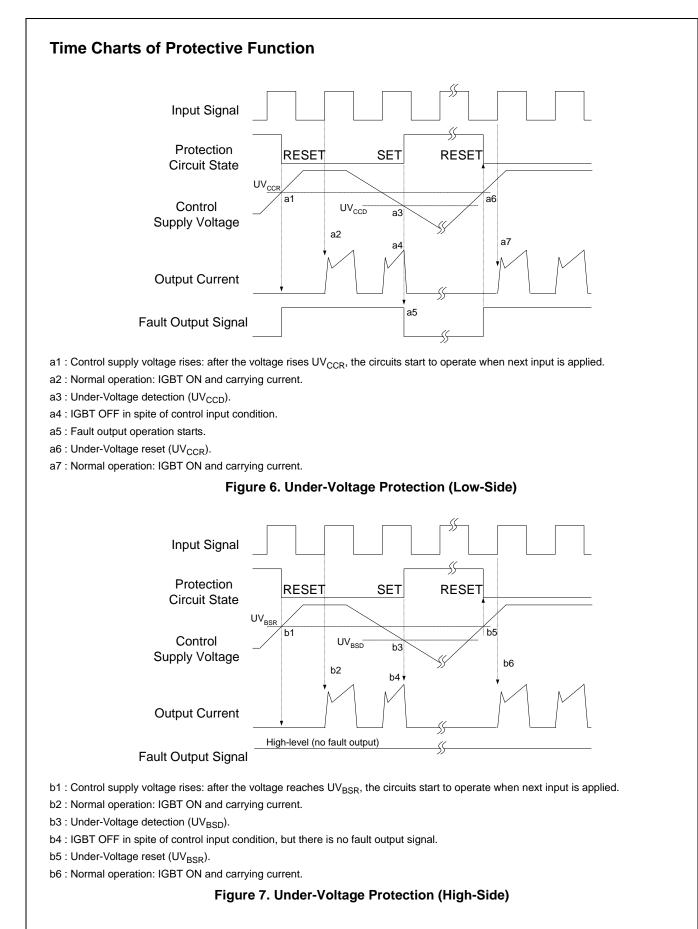
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Mechanical Characteristics and Ratings

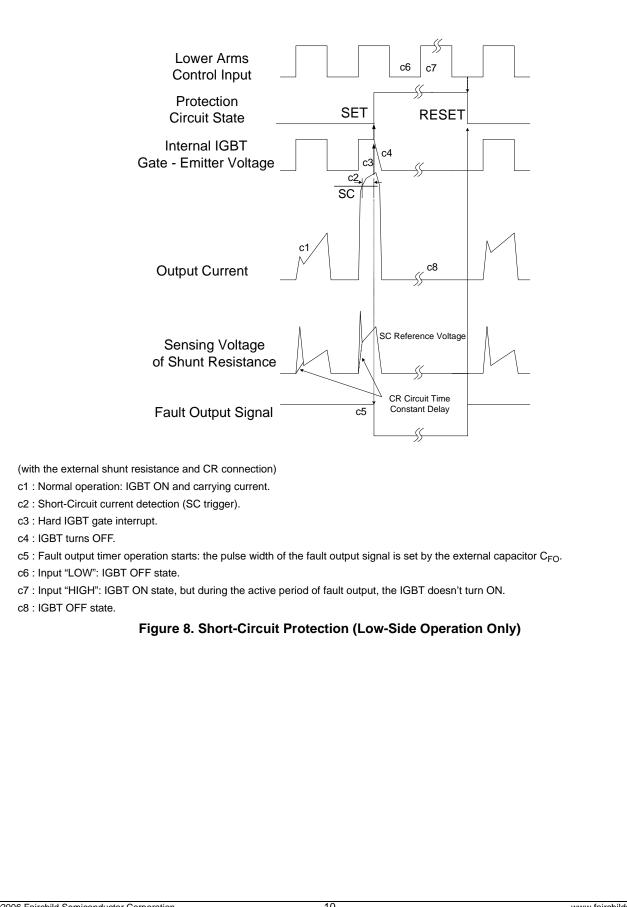
Parameter	Co	Min.	Тур.	Max.	Unit	
Mounting Torque	Mounting Screw: M3	Recommended 0.62 N•m	0.51	0.62	0.72	N∙m
Device Flatness		See Figure 5	0	-	+120	μm
Weight			-	15.40	-	g







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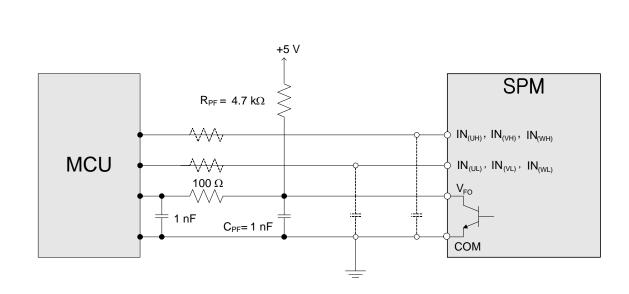
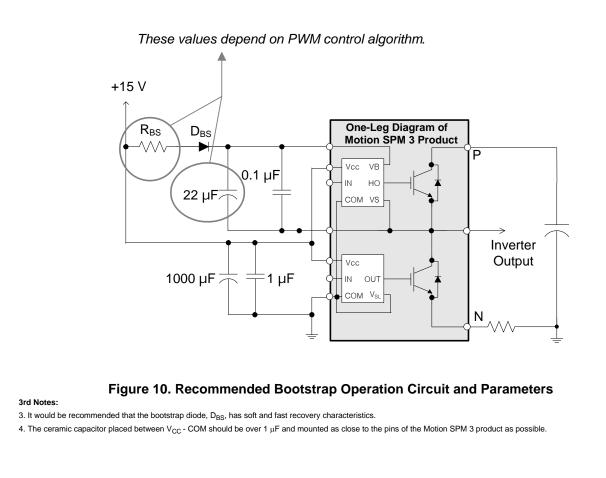


Figure 9. Recommended MCU I/O Interface Circuit

3rd Notes:

- 1. RC coupling at each input (parts shown dotted) might change depending on the PWM control scheme in the application and the wiring impedance of the application's printed circuit board. The Motion SPM[®] 3 Product input signal section integrates a 3.3 kΩ(typ.) pull-down resistor. Therefore, when using an external filtering resistor, pay attention to the signal voltage drop at input terminal.
- 2. The logic input works with standard CMOS or LSTTL outputs.



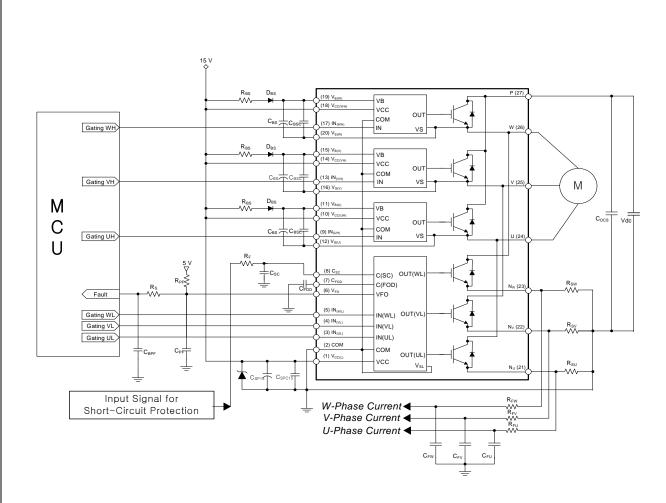
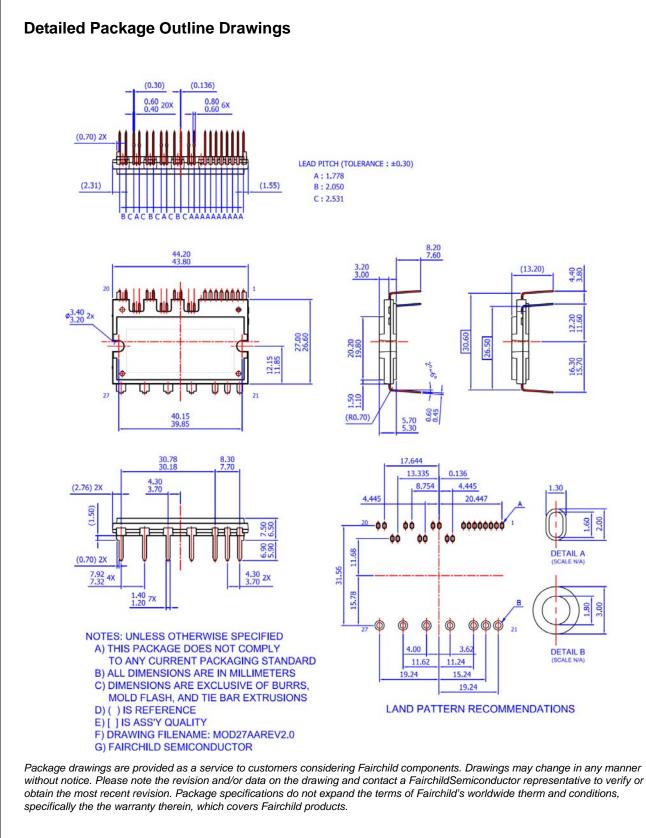


Figure 11. Typical Application Circuit

4th Notes:

- 1. To avoid malfunction, the wiring of each input should be as short as possible (less than 2 3 cm).
- 2. By virtue of integrating an application-specific type of HVIC inside the Motion SPM[®] 3 product, direct coupling to MCU terminals without any optocoupler or transformer isolation is possible.
- 3. V_{FO} output is open-collector type. This signal line should be pulled up to the positive side of the 5 V power supply with approximately 4.7 kΩ resistance (please refer to Figure 9).
- 4. $C_{\mbox{\scriptsize SP15}}$ of around seven times larger than bootstrap capacitor $C_{\mbox{\scriptsize BS}}$ is recommended.
- 5. V_{FO} output pulse width should be determined by connecting an external capacitor (C_{FOD}) between C_{FOD} (pin 7) and COM (pin 2). (Example : if C_{FOD} = 33 nF, then t_{FO} = 1.8 ms (typ.)) Please refer to the 2nd note 5 for calculation method.
- 6. Input signal is active-HIGH type. There is a 3.3 kΩ resistor inside the IC to pull down each input signal line to GND. When employing RC coupling circuits, set up such RC couple that input signal agree with turn-off / turn-on threshold voltage.
- 7. To prevent errors of the protection function, the wiring around $R_{\textrm{F}}$ and $C_{\textrm{SC}}$ should be as short as possible.
- 8. In the short-circuit protection circuit, please select the $R_F C_{SC}$ time constant in the range 1.5 ~ 2 $\mu s.$
- 9. Each capacitor should be mounted as close to the pins of the Motion SPM 3 product as possible.
- 10. To prevent surge destruction, the wiring between the smoothing capacitor and the P & GND pins should be as short as possible. The use of a high-frequency non-inductive capacitor of around 0.1 ~ 0.22 μF between the P & GND pins is recommended.
- Relays are used in almost every systems of electrical equipment in home appliances. In these cases, there should be sufficient distance between the MCU and the relays.
 C_{SPC15} should be over 1 µF and mounted as close to the pins of the Motion SPM 3 product as possible.



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http://www.fairchildsemi.com/dwg/MO/MOD27AA.pdf

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No Identification Needed	Full Production	Datasheet contains final specifications. Fairchild Semiconductor reserves the right to make changes at any time without notice to improve the design.
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