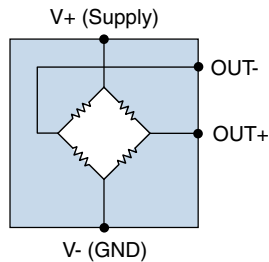
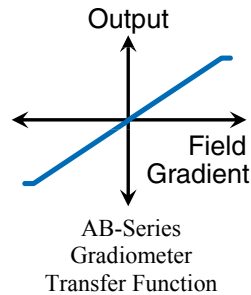
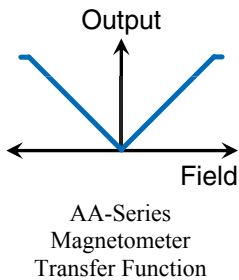


AA/AB-Series Analog Magnetic Sensors

Equivalent Circuit



Idealized Transfer Functions



Features

- Magnetometer and gradiometer configurations
- Field ranges from $\ll 1$ Oe to >4000 Oe
- Ultrasensitive, high-field, and low-hysteresis versions
- Wheatstone bridge analog outputs
- Operation to near-zero voltage
- Up to 1 MHz
- Up to 150°C operating temperature
- ULLGA4, TDFN6, MSOP8, and SOIC8 packages

Applications

- Motion, speed, and position control
- Low-field sensing
- Motor commutator sensors
- Noncontact current sensing

Description

NVE's analog GMR sensors have high sensitivity, excellent temperature stability, and small size. Their versatility and wide sensing range makes them an excellent choice for a variety of analog sensing applications including industrial and automotive position, speed, and current sensors.

The sensors are configured as inherently temperature-compensating Wheatstone bridges.

AA-Series sensors are magnetometers, which detect absolute magnetic field. AB-Series sensors are differential gradiometers, which detect field gradients.

Three magnetometer subtypes are available: the standard AA-Series; the ultrasensitive "H" subtype; the high-field, kilooersted range "K" subtype, and the low-hysteresis "L" subtype.

Packages are as small as an ultraminiature 1.1 x 1.1 mm ULLGA4.

Absolute Maximum Ratings

| Parameter | | Symbol | Min. | Max. | Units |
|------------------------|-----------------------------|-----------------|------|-----------|-------|
| Supply voltage | AAxxx/ABxxx/AAL002 | V _{CC} | | 24 | Volts |
| | AAHxxx/AAKxxx/ABHxxx/AAL004 | | | 12 | |
| Operating temperature | AAxxx/AAKxxx/ABxxx/AALxxx | | -50 | 125 | °C |
| | AAHxxx/ABHxxx | | | 150 | °C |
| Storage temperature | AAxxx/AAKxx/ABxxx/AALxxx | | -65 | 135 | °C |
| | AAHxxx/ABHxxx | | -65 | 150 | |
| ESD (Human Body Model) | | | | 400 | Volts |
| Applied magnetic field | | H | | Unlimited | Oe |

Operating Specifications

| Parameter | Symbol | Min. | Typ. | Max. | Units | Test Condition | |
|-------------------------------------|---------------------------------|--------------------|------|-------|-------|--|-----|
| Supply voltage | AAHxxx/AAKxxx/ ABHxxx/AAL004 | <1 | | 12 | Volts | Maximum limited by power dissipation | |
| | AAxxx/ABxxx/AAL002 | | | 24 | | | |
| Operating temperature | AAKxxx | -40 | | 85 | °C | | |
| | AAxxx/ABxxx/AALxxx | -50 | | 125 | | | |
| | AAHxxx/ABHxxx | | | 150 | | | |
| Electrical offset | AAxxx/AAKxxx/AALxxx/ABxxx | -4 | | +4 | mV/V | | |
| | AAHxxx/ABHxxx | -5 | | +5 | | | |
| Output at maximum field | AAxxx/ABxxx | | | 60 | mV/V | | |
| | AAHxxx/ABHxxx | | | 40 | | | |
| | AAKxxx | | | 19 | | | 25 |
| | AALxxx | | | | | | 45 |
| Non-linearity | AAxxx/AAKxxx/ABxxx/AALxxx | | | 2 | % | Unipolar field sweep | |
| | AAHxxx/ABHxxx | | | 4 | | | |
| Hysteresis | AAHxxx/ABHxxx | | | 15 | % | | |
| | AAxxx/AAKxxx/ABxxx | | | 4 | | | |
| | AALxxx | | | 2 | | | |
| Resistance tolerance | | -20 | | +20 | % | 25°C | |
| Resistance vs. temperature | AAxxx/ABxxx | TC _R | | +0.14 | %/°C | No applied field | |
| | AAHxxx/AAKxxx/ AALxxx/ABHxxx | | | +0.11 | | | |
| Output temperature coefficient | AAxxx/ABxxx | TC _{O-I} | | +0.03 | %/°C | Constant-current supply | |
| | AAHxxx/ABHxxx | | | +0.1 | | | |
| | AAKxxx | | | +0.13 | | | |
| | AALxxx | | | -0.28 | | | |
| | AAxxx/ABxxx | TC _{O-V} | | -0.1 | %/°C | Constant-voltage supply | |
| | AAHxxx/ABHxxx | | | 0 | | | |
| | AAKxxx | | | -0.3 | | | |
| | AALxxx | | | -0.4 | | | |
| | AAKxxx | TC _{HSAT} | | -0.19 | %/°C | | |
| Operating frequency | AAKxxx | f _{MAX} | DC | 50 | kHz | | |
| | AAxxx/AAHxxx/AALxxx | | | 100 | | | |
| | ABxxx/ABHxxx | | | 1 | | | MHz |
| Junction–Ambient thermal resistance | ULLGA4 (-14 suffix) | θ _{JA} | | 500 | °C/W | Soldered to double-sided board; free air | |
| | TDFN6 (-10 suffix) | | | 320 | | | |
| | MSOP8 (-00 suffix) | | | 320 | | | |
| | SOIC8 (-02 suffix) | | | 240 | | | |
| Power Dissipation | ULLGA4 (-14 suffix) | P _D | | 100 | mW | | |
| | TDFN6 (-10 suffix) | | | 500 | | | |
| | MSOP8 (-00 suffix) | | | 500 | | | |
| | SOIC8 (-02 suffix) | | | 675 | | | |

Operation

Sensor Subtypes

There are four AA/AB-Series subtypes, as summarized in the table below. “H” subtypes are designed for very high sensitivity, and “K” types have low sensitivity and high saturation for high-field sensing. “L” types offer low hysteresis. AAH-Series parts also have a 150°C maximum temperature specification.

| Parameter | AAxxx/ ABxxx | AAHxxx/ ABHxxx | AAKxxx | AALxxx |
|-----------------------|-----------------|-------------------|------------|--------|
| Field Sensitivity | High | Very High | Low | High |
| Operating Field Range | High | Low | Very High | Medium |
| Hysteresis | Medium | High | Medium | Low |
| Max. Temperature | High | Very High | Commercial | High |

Magnetometer Operation

AA-Series sensors are *magnetometers*, which detect the absolute magnetic field.

Direction of Sensitivity

Unlike Hall effect or other sensors, the direction of sensitivity of GMR sensors is in the plane of the package, which more convenient for many applications. Two permanent magnet orientations that will activate the sensor are shown in Figure 1:

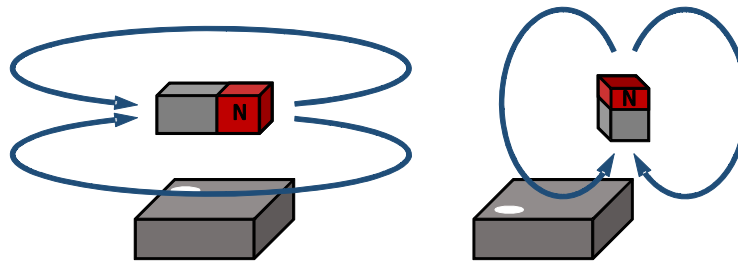


Figure 1. Planar magnetic sensitivity.

Omnipolar

AA-Series sensors are “omnipolar,” meaning the output is equally sensitive to either magnetic field polarity and the output is always a positive voltage:

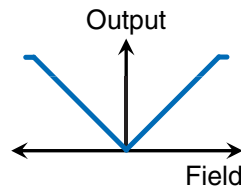


Figure 2. The omnipolar response of AA-Series sensors.

Standard and Cross-Axis Directional Sensitivity

The standard axis of sensitivity is along the part axis, but there are some parts available with cross-axis sensitivity, and AAKxxx sensors are not directionally sensitive in the IC plane, and are therefore sensitive in both standard and cross-axis axis directions.

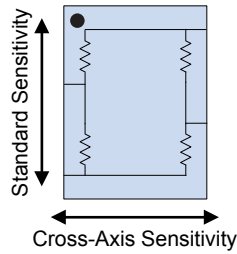


Figure 3. Standard versus cross-axis-sensitivity for AA-Series sensors.

Gradiometer Operation

AB-Series sensors are differential *gradiometers* that reject common mode magnetic fields, making them ideal for high magnetic noise environments such as near electric motors or current-carrying wires. The devices are sensitive to a field gradient along the part axis.

The figure below shows a typical gradiometer response:

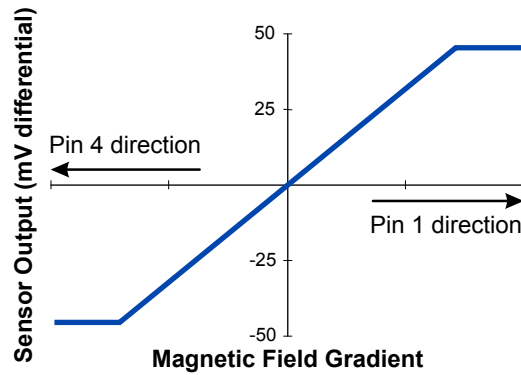


Figure 4. Typical AB-Series gradiometer response.

Typical Performance Graphs

Figures 5–7 show the response of three types of high-sensitivity models. The standard version, the AA002, has excellent temperature stability, especially with constant-current drive. The AAH002 has very high sensitivity but more temperature dependence, and the AAL002 offers low hysteresis at the expense of more temperature dependence:

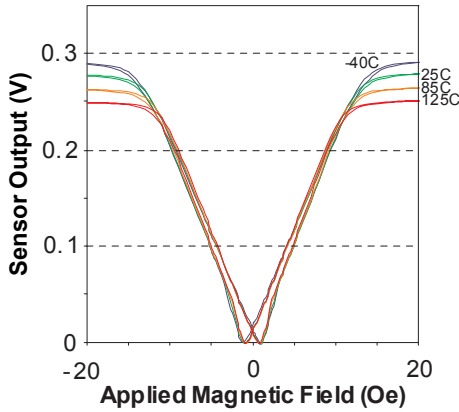


Figure 5a. Typical AA002 output with 1 mA constant-current drive.

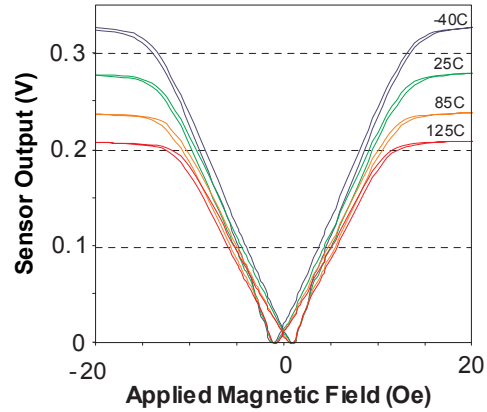


Figure 5b. Typical AA002 output with a 5V supply.

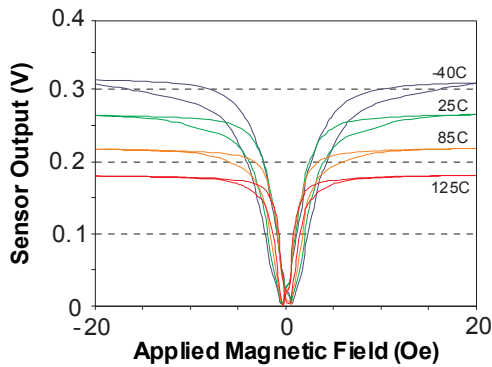


Figure 6a. Typical AAH002 output with 2.28 mA constant-current drive.

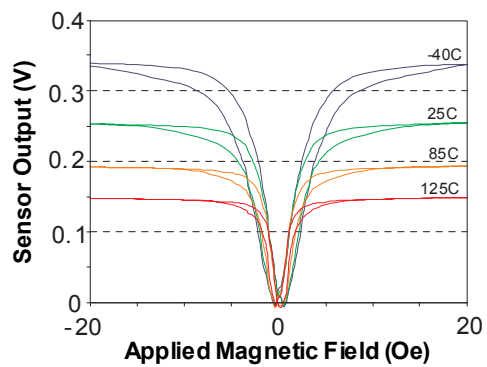


Figure 6b. Typical AAH002 output with a 5V supply.

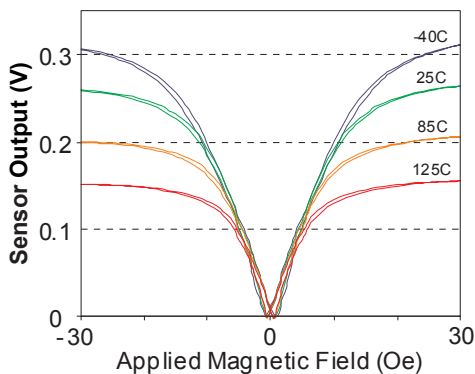


Figure 7a. Typical AAL002 output with 1 mA constant-current drive.

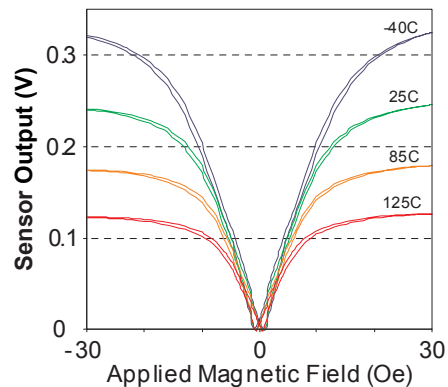


Figure 7b. Typical AAL002 output with a 5V supply.

Figure 8 shows the typical output of an AAK001 high-field sensor. The sensor responds from zero field to 4 kOe, and is highly linear from 400 Oe to 2.5 kOe. The saturation field is dependant on temperature, but sensitivity is quite stable with temperature.

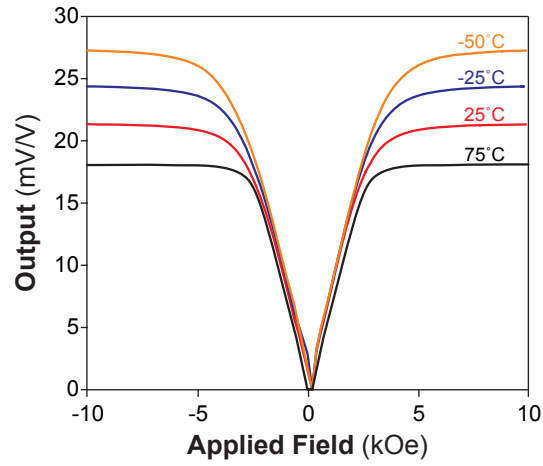


Figure 8. AAK001 high-field sensor output.

Illustrative Applications

Traditional Differential Amplifier

Traditional differential amplifiers use low-cost op-amps to provide a single-ended analog output. The circuit below has a gain of 20, which provides a full-scale output at slightly less than the sensor's saturation. A low-cost, low bias current op amp allows large resistors to avoid loading the sensor bridge. The 250 KΩ input resistors are 100 times the 2.5 KΩ sensor output impedance to avoid loading.

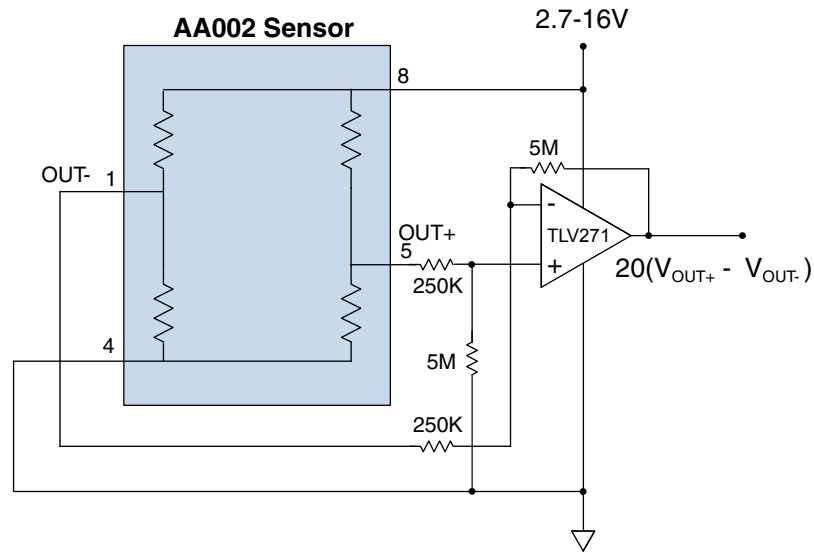


Figure 9. Traditional op-amp differential amplifier.

Sensor Instrumentation Amplifier

Instrumentation amplifiers such as the INA826 are popular bridge sensor preamplifiers because they have a low component count and have excellent common-mode rejection ratios without needing to match resistors. These amplifiers can run on single or dual supplies. AC coupling can be used for small, dynamic signals.

The circuit below has a gain of 20. The general equation for the output voltage is:

$$V_{OUT} = (1 + 49.4K / R_G)V_{IN} + V_{REF}; V_{IN} = V_{OUT+} - V_{OUT-}$$

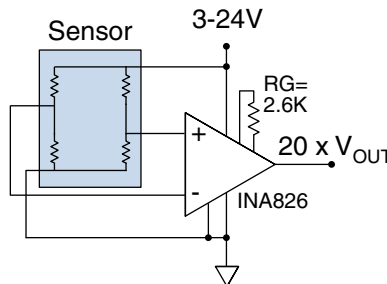


Figure 10. Single-ended analog sensor instrumentation amplifier.

Note that the instrumentation amplifier has a minimum output of 0.1V, so to detect very low fields on a single supply, an offset can be provided by using a non-zero V_{REF} .

Constant-Current Sensor Drive

Using a constant current rather than conventional constant voltage sensor supply can significantly improve temperature stability of AAxxx/ABxxx sensors. AA00x sensors, for example, have an output temperature coefficient (TC_{O-I}) of 0.03%/°C with constant current, versus -0.1%/°C with constant voltage (TC_{O-V}).

A simple constant-current supply is illustrated below:

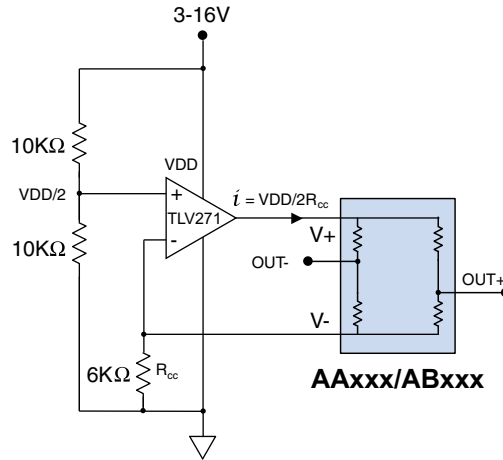


Figure 11. Constant-current supply.

The supply current for the circuit above is $V_{cc}/2R_{cc}$. R_{cc} can be set to the maximum sensor bridge resistance (e.g., 6 KΩ for many sensors) to provide the highest possible output without saturating the op-amp. The sensor will be driven with 1 mA for a 12 V supply in the circuit above. Similar op-amp or instrumentation amplifiers can be used for constant-current or constant-voltage supplies.

Variable Threshold Magnetic Switch

NVE offers AD-Series factory-set GMR Switches, but AA-Series analog sensors can be used for special thresholds or hysteresis, or for variable thresholds. In this circuit, the threshold is varied by changing R_G , which sets the gain of the differential amplifier. The 1 MΩ resistor sets the threshold hysteresis:

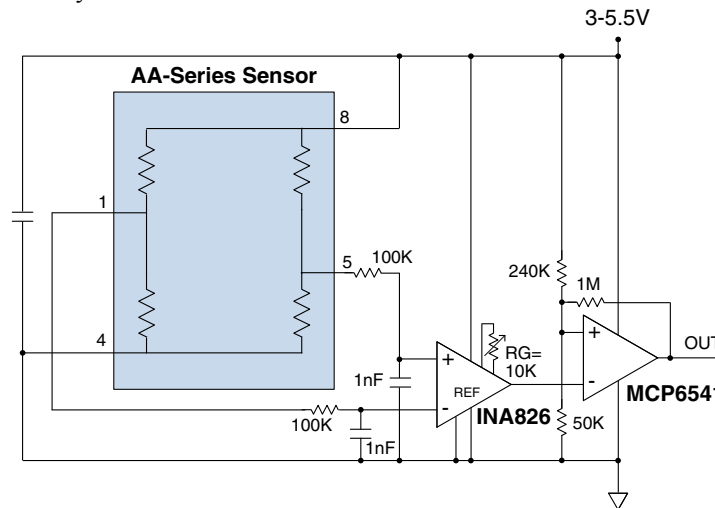


Figure 12. Variable threshold magnetic switch.

LED Field-Strength Indicator

The op-amp circuit in Figure 13 below can be used to change the brightness of an LED to indicate magnetic field strength at a glance:

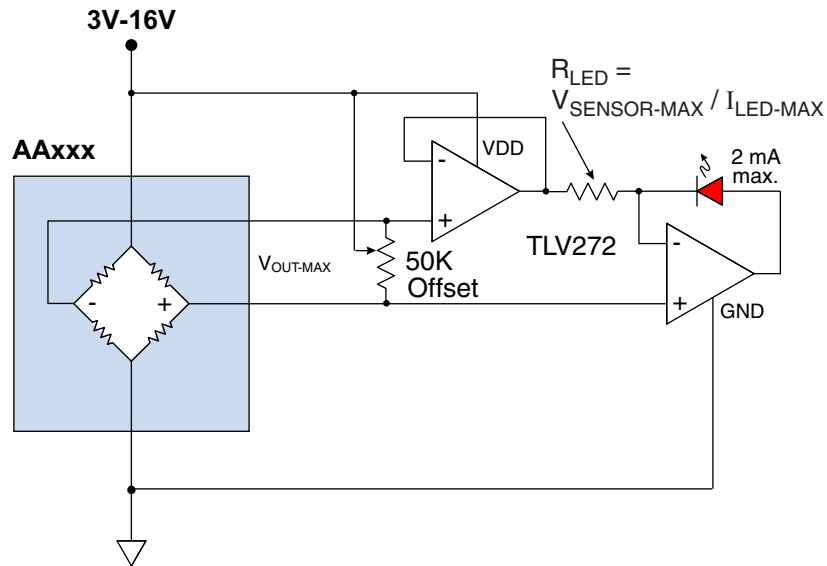


Figure 13. LED brightness indicates the magnetic field.

The LED current is proportional to the sensor output:

$$I_{LED} = (V_{OUT+} - V_{OUT-}) / R_{LED}$$

The maximum LED current can be set to the maximum sensor output. For example, for an AAK001, typical $V_{OUT-MAX}$ is 25 mV/V, so for a three-volt supply the maximum is approximately 75 mV. For a high-efficiency with a forward current of 2 mA, $R_{LED} = 75 \text{ mV} / 2 \text{ mA} = 38\Omega$.

The 50 K Ω potentiometer is optional, to correct for sensor offset or to set the minimum field to turn on the LED.

The 16-volt maximum supply voltage noted in Figure 13 is limited by the op-amp selected, but note that some sensors have a 12-volt maximum supply rating. The three-volt minimum supply is to provide enough voltage to turn on the LED; the sensors can operate on lower voltages.

Noncontact Current Sensing

AA-Series sensors are often used to measure the current over a circuit board trace. The sensor measures the current by detecting the magnetic field generated by the current through the trace this application, and other AA-Series sensors can be used depending on required sensitivity and hysteresis.

The AAL024 is ideal for this application because its cross-axis sensitivity provides sensitivity to a current trace directly under the part, and its low hysteresis provides repeatability. The AA003-02 is popular for overcurrent protection where hysteresis is needed and extreme accuracy is not required.

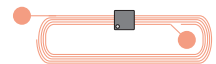
Typical current sensing configurations are shown below:



**Figure 14a. 0.09" (2.3 mm) trace
(0 – 10 A with AA003 sensor)**



**Figure 14b. 0.05" (1.3 mm) trace
(0 – 5 A with AAL024 sensor).**



**Figure 14c. Five turns of
0.0055" (0.14 mm) trace
(0 – 1 A with AAL024 sensor).**

For the geometry shown in Figure 15 and narrow traces with, the magnetic field generate can be approximated by Ampere’s law:

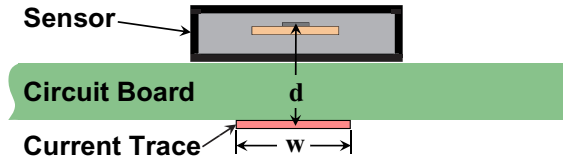


Figure 15. The geometry of current-sensing over a circuit board trace.

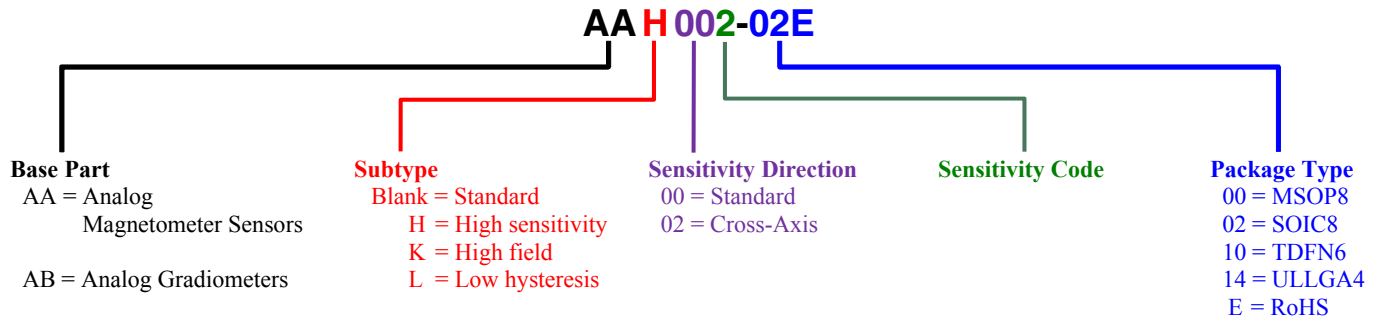
$$H = \frac{2I}{d} \quad [\text{“H” in oersteds, “I” in amps, and “d” in millimeters}]$$

The trace can also be run on the top side of the PCB for more current sensitivity.

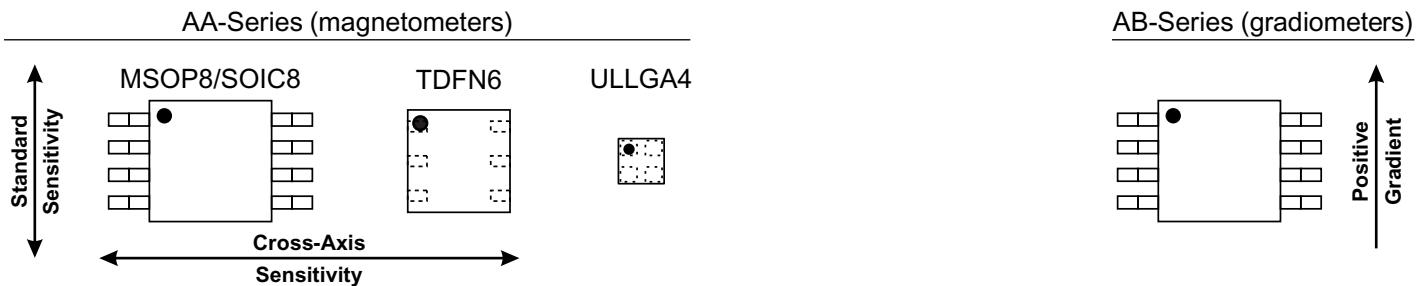
More precise calculations can be made by breaking the trace into a finite element array of thin traces, and calculating the field from each array element. We have a free, Web-based application with a finite-element model to estimate magnetic fields and sensor outputs in this application:

www.nve.com/spec/calculators.php#tabs-Current-Sensing

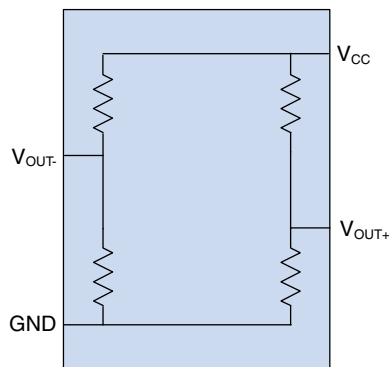
Part Numbering



Direction of Sensitivity



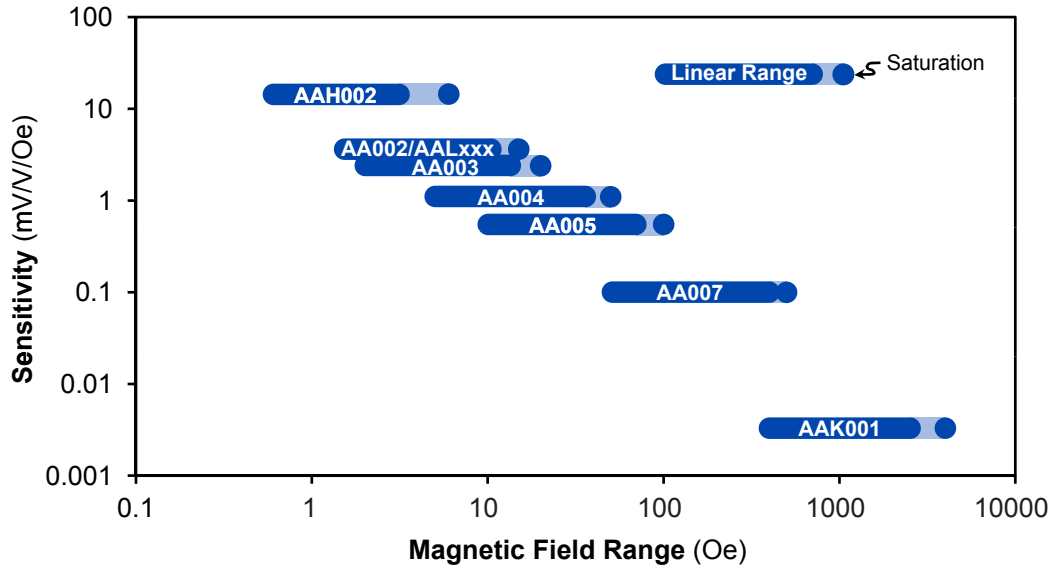
Pinouts



| AA-Series Pinout | | | | | | |
|----------------------|-----------|------|------------------------|------|-------------------|---|
| Sensitivity | | | | | Symbol | Description |
| Standard (AAx00x-xx) | | | Cross-Axis (AAx02x-xx) | | | |
| ULLGA | MSOP/SOIC | TDFN | MSOP/SOIC | TDFN | | |
| 3 | 1 | 1 | 5 | 4 | V _{OUT-} | Negative bridge output (decreases with increasing field). |
| | 2 | 2 | 2 | 2 | NC | No internal connection. |
| | 3 | | 3 | | | |
| 4 | 4 | 3 | 4 | 3 | V-/GND | Negative supply or ground. |
| 1 | 5 | 4 | 1 | 1 | V _{OUT+} | Positive bridge output (increases with field). |
| | 6 | 5 | 6 | 5 | NC | No internal connection. |
| | 7 | | 7 | | | |
| 2 | 8 | 6 | 8 | 6 | V+ | Positive supply voltage. |

| AB-Series Pinout | | |
|------------------|-------------------|---|
| Pin | Symbol | Description |
| 1 | V _{OUT-} | Negative bridge output (decreases with gradient). |
| 2 | NC | No internal connection. |
| 3 | | |
| 4 | V-/GND | Negative supply or ground. |
| 5 | V _{OUT+} | Positive bridge output (increases with gradient). |
| 6 | NC | No internal connection. |
| 7 | | |
| 8 | V+ | Positive supply. |

AA-Series Sensor Selector Chart



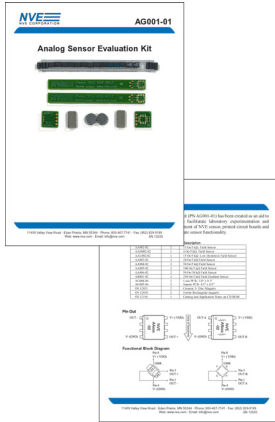
Available Parts

| Magnetometers (AA-Series) | | | | | | | | | | |
|---------------------------|-------------------|------|-----------------|-----------------------|-------|-----------------------------|--------------------------|----------------------|-----------------|--------------------|
| Available Part | Linear Range (Oe) | | Saturation (Oe) | Sensitivity (mV/V-Oe) | | Max. Non-linearity (% Uni.) | Max. Hysteresis (% Uni.) | Max. Operating Temp. | Typ. Resistance | Package |
| | Min. | Max. | | Min. | Max. | | | | | |
| AA002-02 | 1.5 | 10.5 | 15 | 3 | 4.2 | 2% | 4% | 125°C | 5 kΩ | SOIC8 |
| AA003-02 | 2 | 14 | 20 | 2 | 3.2 | 2% | 4% | 125°C | 5 kΩ | SOIC8 |
| AA004-00 | 5 | 35 | 50 | 0.9 | 1.3 | 2% | 4% | 125°C | 5 kΩ | MSOP8 |
| AA024-00 | 5 | 35 | 50 | 0.9 | 1.3 | 2% | 4% | 125°C | 5 kΩ | MSOP8 (cross-axis) |
| AA004-02 | 5 | 35 | 50 | 0.9 | 1.3 | 2% | 4% | 125°C | 5 kΩ | SOIC8 |
| AA005-02 | 10 | 70 | 100 | 0.45 | 0.65 | 2% | 4% | 125°C | 5 kΩ | SOIC8 |
| AA006-00 | 5 | 35 | 50 | 0.9 | 1.3 | 2% | 4% | 125°C | 30 kΩ | MSOP8 |
| AA006-02 | 5 | 35 | 50 | 0.9 | 1.3 | 2% | 4% | 125°C | 30 kΩ | SOIC8 |
| AA007-00 | 50 | 450 | 500 | 0.08 | 0.12 | 2% | 4% | 125°C | 5 kΩ | MSOP8 |
| AAH002-02 | 0.6 | 3 | 6 | 11 | 18 | 4% | 15% | 150°C | 2 kΩ | SOIC8 |
| AAH004-00 | 1.5 | 7.5 | 15 | 3.2 | 4.8 | 4% | 15% | 150°C | 2 kΩ | MSOP8 |
| AAL002-02 | 1.5 | 10.5 | 15 | 3 | 4.2 | 2% | 2% | 125°C | 5.5 kΩ | SOIC8 |
| AAL004-10 | 1.5 | 10.5 | 15 | 3 | 4.2 | 2% | 2% | 125°C | 2.2 kΩ | TDFN6 |
| AAL024-10 | 1.5 | 10.5 | 15 | 3 | 4.2 | 2% | 2% | 125°C | 2.2 kΩ | TDFN6 (cross-axis) |
| AAK001-14 | 400 | 2500 | 4000 | 0.0025 | 0.004 | 2% | 4% | 85°C | 3.5 kΩ | ULLGA4 |

| Gradiometers (AB-Series) | | | | | | | | | | |
|--------------------------|-------------------|------|-----------------|---------------------|------|-----------------------------|--------------------------|----------------------|-----------------|---------|
| Available Part | Linear Range (Oe) | | Saturation (Oe) | Sensitivity (%R/Oe) | | Max. Non-linearity (% Uni.) | Max. Hysteresis (% Uni.) | Max. Operating Temp. | Typ. Resistance | Package |
| | Min. | Max. | | Min. | Max. | | | | | |
| AB001-02 | 10 | 175 | 250 | 0.02 | 0.03 | 2% | 4% | 125°C | 2.5 kΩ | SOIC8 |
| AB001-00 | 10 | 175 | 250 | 0.02 | 0.03 | 2% | 4% | 125°C | 2.5 kΩ | MSOP8 |
| ABH001-00 | 5 | 40 | 70 | 0.06 | 0.12 | 4% | 15% | 150°C | 1.2 kΩ | MSOP8 |

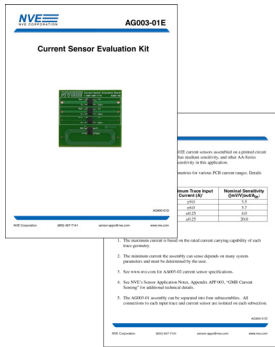
Evaluation Kits

Four inexpensive evaluation kits including AA- or AB-Series analog sensors are available:



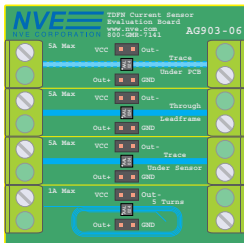
AG001-01: Analog Sensor Evaluation Kit

This kit features several types of NVE’s AA and AB series parts, a selection of permanent magnets for activation or bias purposes, and circuit boards to mount the parts for testing.



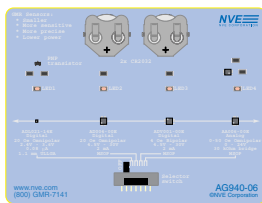
AG003-01: AA003 Current Sensor Evaluation Kit

This kit features a circuit board with different trace configurations running under four AA003-02E analog sensors to evaluate the sensor as non-contact current sensors. The board supports current ranges of 0–9 amps, 0–6 amps, and 0–250 milliamps. Boards measure 2 by 1.85 inches (51 mm by 47 mm), and include four sensors.



AG903-01: AA003 Current Sensor Evaluation Kit

This board includes four ADL024-10E TDFN current sensors on a PCB with four different current-trace configurations, and include four sensors. The boards measure 2 by 2 inches (50 mm x 50 mm) and include screw connections for current to be measured.



AG940-07E: Digital/Analog/Omnipolar/Bipolar Sensor Demo Board

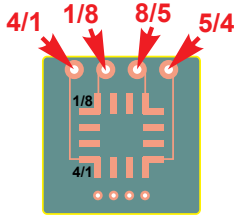
The kit includes a demo board with our most popular digital, analog, omnipolar, and bipolar sensors, including an AA006-00E analog sensor. Each sensor drives an indicator LED. A bar magnet is included so you can see for yourself how the sensors work. The evaluation boards are 3.75 by 5 inches (95 mm by 127 mm), and are powered by two coin cells (included).

Bare Circuit Boards for Sensors

NVE offers several bare circuit boards specially designed for easy connections to surface-mount sensors. Popular PCBs are shown below (images are actual size):



AG004-06: 3" x 0.3" (75 x 8 mm) SOIC8 circuit board



AG005-06:
0.5" x 0.5" (13 mm x 13 mm)
SOIC8



AG915-06:
0.25" (6 mm) octagonal
MSOP8



AG918-06 (standard) / AG919-06 (cross-axis):
2" x 0.25" (50 mm x 6 mm) MSOP8



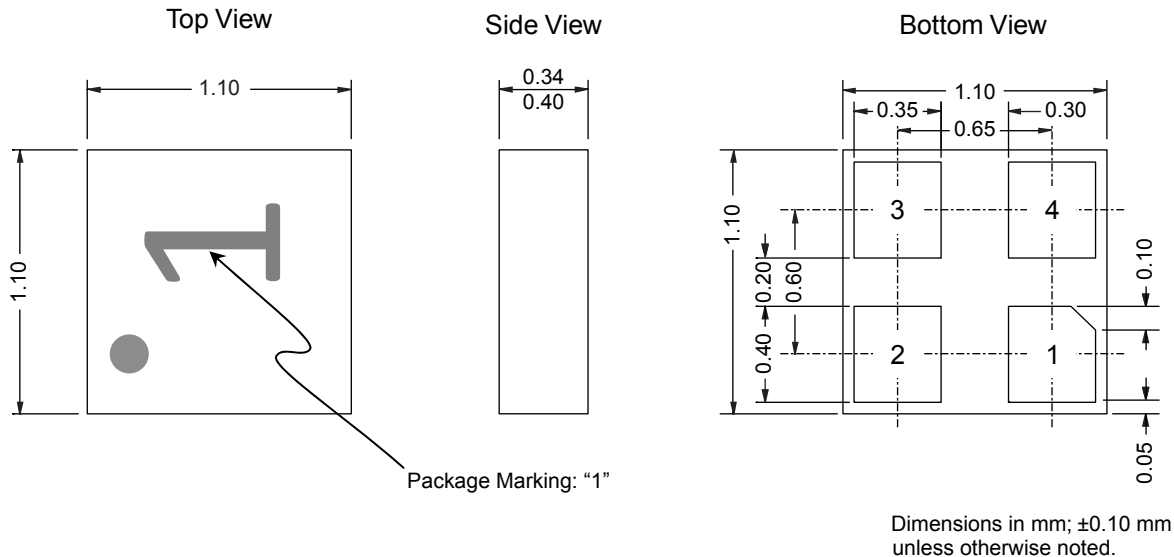
AG035-06:
1.57" x 0.25" (40 mm x 6 mm) TDFN6



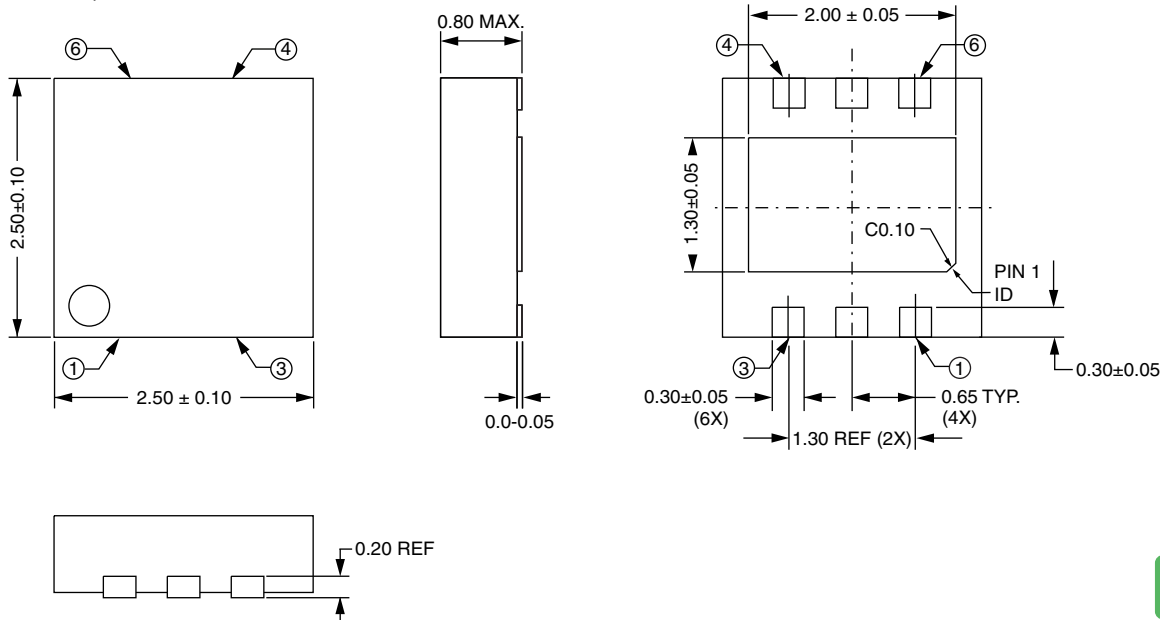
AG904-06:
1.2" x 0.25" (30 mm x 6 mm)
ULLGA

Package Drawings

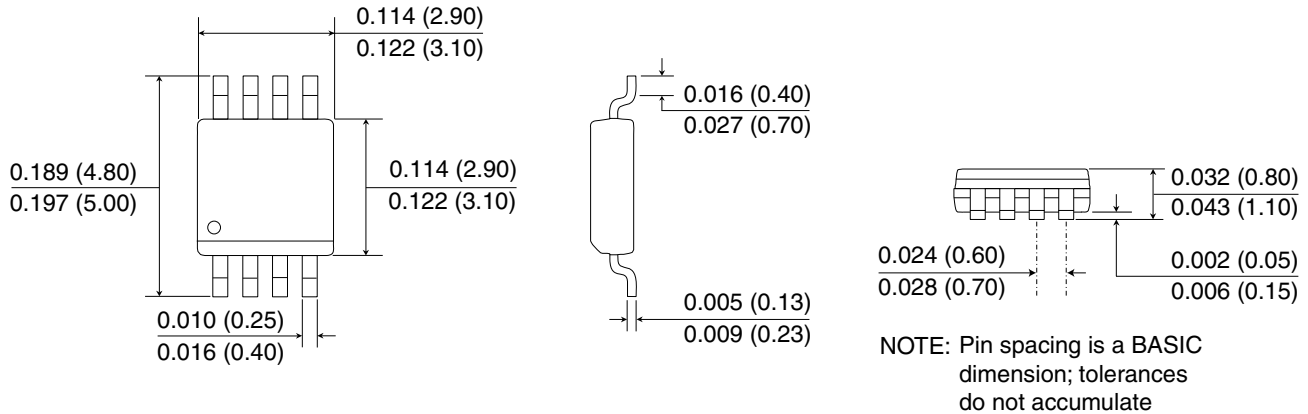
ULLGA4 (-14E suffix)



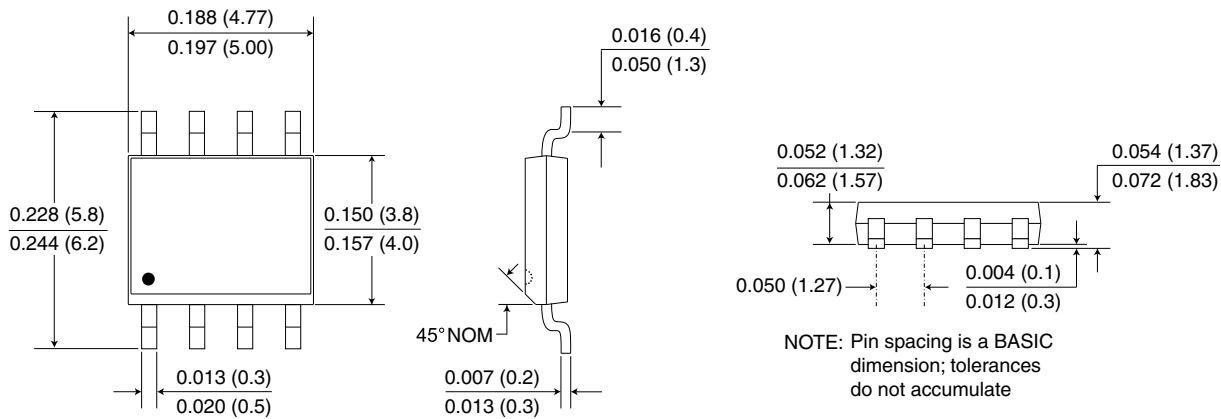
TDFN6 (-10 suffix)



MSOP8 (-00 suffix)



SOIC8 (-02 suffix)



RoHS
COMPLIANT

RoHS
COMPLIANT

Soldering profiles per JEDEC J-STD-020C, MSL 1.

Revision History

SB-00-059-D

October 2017

Change

- Added AAK001 ultrahigh-field model.
- Added LED field-strength indicator and current-sensing applications (p. 10).
- Added AA selector chart (p. 13).
- Added Evaluation Kits (p. 14) and bare circuit boards (p. 15).
- Misc. cosmetic changes and additional illustrations.

SB-00-059-C

September 2017

Change

- Added AA007-00E high-field model.

SB-00-059-B

August 2017

Change

- Added AA024-10E and AAL024-10E cross-axis versions.

SB-00-059-A

April 2017

Change

- Initial datasheet release superseding catalog.

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SB-00-059_RevD

October 2017