



**CY7C135**  
**CY7C1342**

**4K x 8 Dual-Port Static RAMs**  
**and 4K x 8 Dual-Port Static RAM with Semaphores**

**Features**

- True Dual-Ported memory cells which allow simultaneous reads of the same memory location
- 4K x 8 organization
- 0.65-micron CMOS for optimum speed/power
- High-speed access: 15 ns
- Low operating power:  $I_{CC} = 160 \text{ mA (max.)}$
- Fully asynchronous operation
- Automatic power-down
- Semaphores included on the 7C1342 to permit software handshaking between ports
- Available in 52-pin PLCC
- Pin-compatible and functionally equivalent to IDT7134/IDT71342

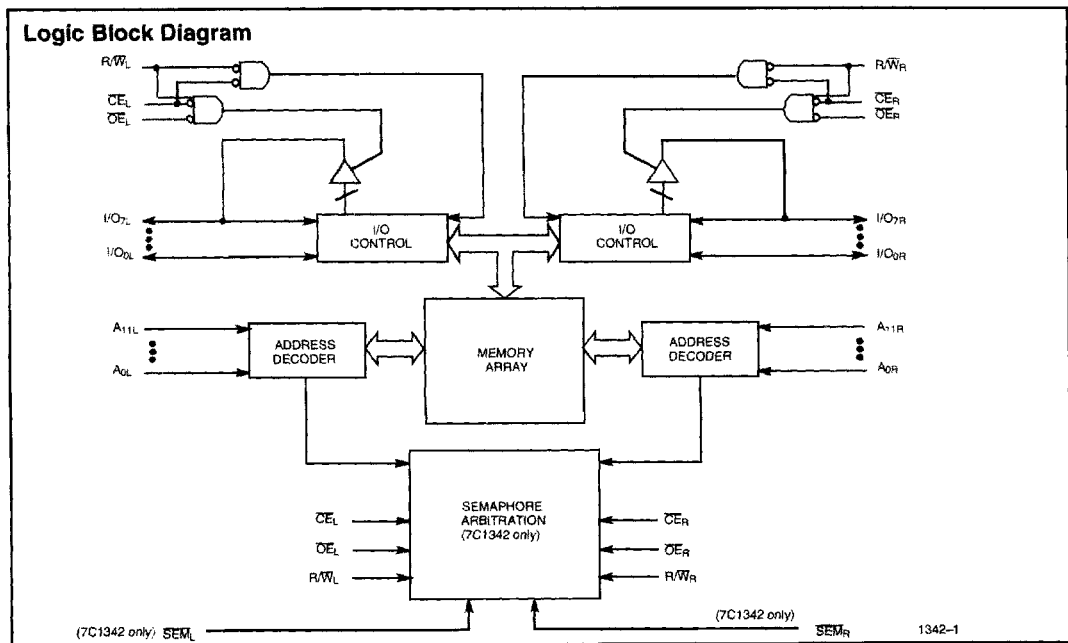
that provide a means to allocate portions of the dual-port RAM or any shared resource. Two ports are provided permitting independent, asynchronous access for reads and writes to any location in memory. Application areas include interprocessor/multiprocessor designs, communications status buffering, and dual-port video/graphics memory.

Each port has independent control pins: chip enable ( $\overline{CE}$ ), read or write enable ( $R/\overline{W}$ ), and output enable ( $\overline{OE}$ ). The CY7C135 is suited for those systems that do not require on-chip arbitration or are intolerant of wait states. Therefore, the user must be aware that simultaneous access to a location is possible. Semaphores are offered on the CY7C1342 to assist in arbitrating between ports. The semaphore logic is comprised of eight shared latches. Only one side can control the latch (semaphore) at any time. Control of a semaphore indicates that a shared resource is in use. An automatic power-down feature is controlled independently on each port by a chip enable ( $\overline{CE}$ ) pin or SEM pin (CY7C1342 only).

The CY7C135 and CY7C1342 are available in 52-pin PLCC.

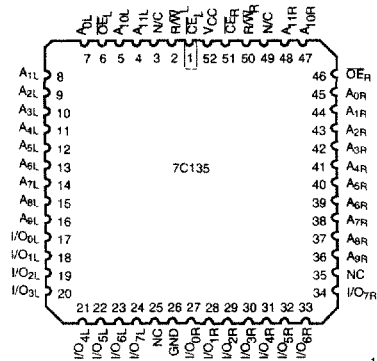
**Functional Description**

The CY7C135 and CY7C1342 are high-speed CMOS 4K x 8 dual-port static RAMs. The CY7C1342 includes semaphores

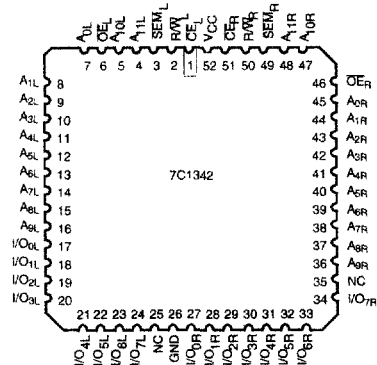


**Selection Guide**

		7C135-15 7C1342-15	7C135-20 7C1342-20	7C135-25 7C1342-25	7C135-35 7C1342-35	7C135-55 7C1342-55
Maximum Access Time (ns)		15	20	25	35	55
Maximum Operating Current (mA)	Commercial	220	190	180	160	160
Maximum Standby Current for $I_{SB1}$ (mA)	Commercial	60	50	40	30	30

**Pin Configurations**
**PLCC  
Top View**


1342-3

**PLCC  
Top View**


1342-4



**Pin Definitions**

Left Port	Right Port	Description
A <sub>0L-11L</sub>	A <sub>0R-11R</sub>	Address Lines
CE <sub>L</sub>	CE <sub>R</sub>	Chip Enable
OE <sub>L</sub>	OE <sub>R</sub>	Output Enable
R/W <sub>L</sub>	R/W <sub>R</sub>	Read/Write Enable
SEM <sub>L</sub> (CY7C1342 only)	SEM <sub>R</sub> (CY7C1342 only)	Semaphore Enable. When asserted LOW, allows access to eight semaphores. The three least significant bits of the address lines will determine which semaphore to write or read. The I/O <sub>0</sub> pin is used when writing to a semaphore. Semaphores are requested by writing a 0 into the respective location.

**Maximum Ratings**

Storage Temperature ..... -65°C to +150°C  
 Ambient Temperature with Power Applied ..... -55°C to +125°C  
 Supply Voltage to Ground Potential (Pin 48 to Pin 24) ..... -0.5V to +7.0V  
 DC Voltage Applied to Outputs in High Z State ..... -0.5V to +7.0V  
 DC Input Voltage<sup>[1]</sup> ..... -3.0V to +7.0V

Static Discharge Voltage ..... > 2001V (per MIL-STD-883, Method 3015)

Latch-Up Current ..... > 200 mA

**Operating Range**

Range	Ambient Temperature	V <sub>CC</sub>
Commercial	0°C to +70°C	5V ± 10%
Industrial	-40°C to +85°C	5V ± 10%

3

**Electrical Characteristics Over the Operating Range<sup>[3]</sup>**

Parameter	Description	Test Conditions	7C135-15 7C1342-15		7C135-20 7C1342-20		7C135-25 7C1342-25		Unit
			Min.	Max.	Min.	Max.	Min.	Max.	
V <sub>OH</sub>	Output HIGH Voltage	V <sub>CC</sub> = Min., I <sub>OH</sub> = -4.0 mA	2.4		2.4		2.4		V
V <sub>OL</sub>	Output LOW Voltage	V <sub>CC</sub> = Min., I <sub>OL</sub> = 4.0 mA		0.4		0.4		0.4	V
V <sub>IH</sub>	Input HIGH Voltage		2.2		2.2		2.2		V
V <sub>IL</sub>	Input LOW Voltage			0.8		0.8		0.8	V
I <sub>Ix</sub>	Input Load Current	GND ≤ V <sub>I</sub> ≤ V <sub>CC</sub>	-10	+10	-10	+10	-10	+10	μA
I <sub>OZ</sub>	Output Leakage Current	Outputs Disabled, GND ≤ V <sub>O</sub> ≤ V <sub>CC</sub>	-10	+10	-10	+10	-10	+10	μA
I <sub>CC</sub>	Operating Current	V <sub>CC</sub> = Max., I <sub>OUT</sub> = 0 mA	Com'l	220		190		180	mA
			Ind.					190	
I <sub>SB1</sub>	Standby Current (Both Ports TTL Levels)	CE <sub>L</sub> and CE <sub>R</sub> ≥ V <sub>IH</sub> , f = f <sub>MAX</sub> <sup>[4]</sup>	Com'l	60		50		40	mA
			Ind.					50	
I <sub>SB2</sub>	Standby Current (One Port TTL Level)	CE <sub>L</sub> and CE <sub>R</sub> ≥ V <sub>IH</sub> , f = f <sub>MAX</sub> <sup>[4]</sup>	Com'l	130		120		110	mA
			Ind.					120	
I <sub>SB3</sub>	Standby Current (Both Ports CMOS Levels)	Both Ports CE and CE <sub>R</sub> ≥ V <sub>CC</sub> - 0.2V, V <sub>IN</sub> ≥ V <sub>CC</sub> - 0.2V or V <sub>IN</sub> ≤ 0.2V, f = 0 <sup>[4]</sup>	Com'l	15		15		15	mA
			Ind.					30	
I <sub>SB4</sub>	Standby Current (One Port CMOS Level)	One Port CE <sub>L</sub> or CE <sub>R</sub> ≥ V <sub>CC</sub> - 0.2V, V <sub>IN</sub> ≥ V <sub>CC</sub> - 0.2V or V <sub>IN</sub> ≤ 0.2V, Active Port Outputs, f = f <sub>MAX</sub> <sup>[4]</sup>	Com'l	125		115		100	mA
			Ind.					115	

**Notes:**

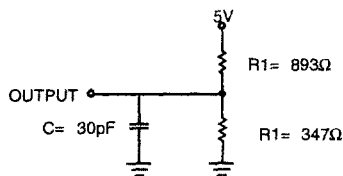
1. Pulse width < 20 ns.
2. T<sub>A</sub> is the 'instant on' case temperature.
3. See the last page of this specification for Group A subgroup testing information.
4. I<sub>MAX</sub> = 1/f<sub>RC</sub> = All inputs cycling at f = 1/f<sub>RC</sub> (except output enable). f = 0 means no address or control lines change. This applies only to inputs at CMOS level standby I<sub>SB3</sub>.

**Electrical Characteristics** Over the Operating Range<sup>[3]</sup>(continued)

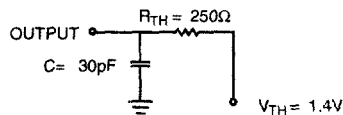
Parameter	Description	Test Conditions	7C135-35 7C1342-35		7C135-55 7C1342-55		Unit
			Min.	Max.	Min.	Max.	
V <sub>OH</sub>	Output HIGH Voltage	V <sub>CC</sub> = Min., I <sub>OH</sub> = -4.0 mA	2.4		2.4		V
V <sub>OL</sub>	Output LOW Voltage	V <sub>CC</sub> = Min., I <sub>OL</sub> = 4.0 mA		0.4		0.4	V
V <sub>IH</sub>			2.2		2.2		V
V <sub>IL</sub>	Input LOW Voltage			0.8		0.8	V
I <sub>IX</sub>	Input Load Current	GND ≤ V <sub>I</sub> ≤ V <sub>CC</sub>	-10	+10	-10	+10	μA
I <sub>OZ</sub>	Output Leakage Current	Outputs Disabled, GND ≤ V <sub>O</sub> ≤ V <sub>CC</sub>	-10	+10	-10	+10	μA
I <sub>CC</sub>	Operating Current	V <sub>CC</sub> = Max., I <sub>OUT</sub> = 0 mA	Com'l	160	160		mA
			Ind.	180	180		
I <sub>SB1</sub>	Standby Current (Both Ports TTL Levels)	C <sub>EL</sub> and C <sub>ER</sub> ≥ V <sub>IH</sub> , f = f <sub>MAX</sub> <sup>[4]</sup>	Com'l	30	30		mA
			Ind.	40	40		
I <sub>SB2</sub>	Standby Current (One Port TTL Level)	C <sub>EL</sub> and C <sub>ER</sub> ≥ V <sub>IH</sub> , f = f <sub>MAX</sub> <sup>[4]</sup>	Com'l	100	100		mA
			Ind.	110	110		
I <sub>SB3</sub>	Standby Current (Both Ports CMOS Levels)	Both Ports C <sub>E</sub> and C <sub>R</sub> ≥ V <sub>CC</sub> - 0.2V, V <sub>IN</sub> ≥ V <sub>CC</sub> - 0.2V or V <sub>IN</sub> ≤ 0.2V, f = 0 <sup>[4]</sup>	Com'l	15	15		mA
			Ind.	30	30		
I <sub>SB4</sub>	Standby Current (One Port CMOS Level)	One Port C <sub>E</sub> or C <sub>R</sub> ≥ V <sub>CC</sub> - 0.2V, V <sub>IN</sub> ≥ V <sub>CC</sub> - 0.2V or V <sub>IN</sub> ≤ 0.2V, Active Port Outputs, f = f <sub>MAX</sub> <sup>[4]</sup>	Com'l	90	90		mA
			Ind.	100	100		

**Capacitance**<sup>[5]</sup>

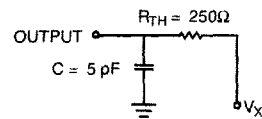
Parameter	Description	Test Conditions	Max.	Unit
C <sub>IN</sub>	Input Capacitance	T <sub>A</sub> = 25°C, f = 1 MHz, V <sub>CC</sub> = 5.0V	10	pF
C <sub>OUT</sub>	Output Capacitance		10	pF

**AC Test Loads and Waveforms**

**(a) Normal Load (Load 1)**

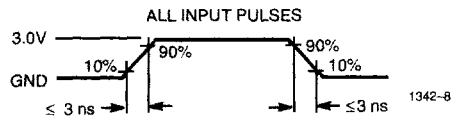
1342-5


**(b) Thévenin Equivalent (Load 1)**

1342-6


**(c) Three-State Delay (Load 3)**

1342-7


**Note:**

5. Tested initially and after any design or process changes that may affect these parameters.

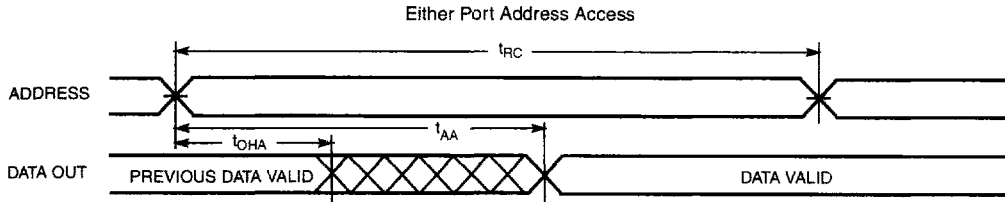


**Switching Characteristics** Over the Operating Range<sup>[6, 7]</sup>

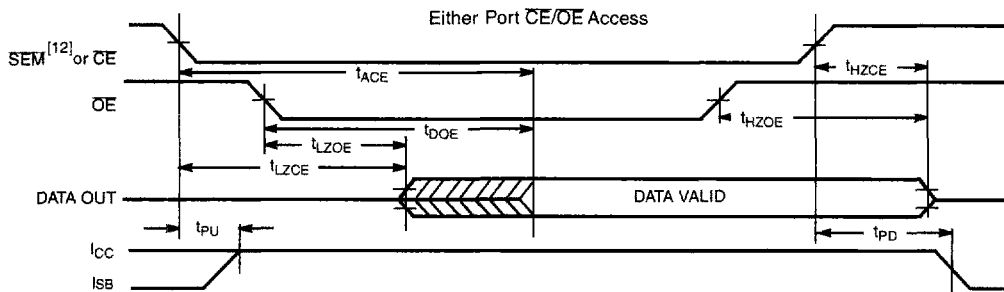
Parameter	Description	7C135-15 7C1342-15		7C135-20 7C1342-20		7C135-25 7C1342-25		7C135-35 7C1342-35		7C135-55 7C1342-55		Unit
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
<b>READ CYCLE</b>												
t <sub>RC</sub>	Read Cycle Time	15		20		25		35		55		ns
t <sub>AA</sub>	Address to Data Valid		15		20		25		35		55	ns
t <sub>OHA</sub>	Output Hold From Address Change	3		3		3		3		3		ns
t <sub>ACE</sub>	CE LOW to Data Valid		15		20		25		35		55	ns
t <sub>DOE</sub>	OE LOW to Data Valid		10		13		15		20		25	ns
t <sub>LZOE</sub> <sup>[8,9,10]</sup>	OE Low to Low Z	3		3		3		3		3		ns
t <sub>HZOE</sub> <sup>[8,9,10]</sup>	OE HIGH to High Z		10		13		15		20		25	ns
t <sub>LZCE</sub> <sup>[8,9,10]</sup>	CE LOW to Low Z	3		3		3		3		3		ns
t <sub>HZCE</sub> <sup>[8,9,10]</sup>	CE HIGH to High Z		10		13		15		20		25	ns
t <sub>PU</sub> <sup>[10]</sup>	CE LOW to Power Up	0		0		0		0		0		ns
t <sub>PD</sub> <sup>[10]</sup>	CE HIGH to Power Down		15		20		25		35		55	ns
<b>WRITE CYCLE</b>												
t <sub>WC</sub>	Write Cycle Time	15		20		25		35		55		ns
t <sub>SCE</sub>	CE LOW to Write End	12		15		20		30		50		ns
t <sub>AW</sub>	Address Set-Up to Write End	12		15		20		30		50		ns
t <sub>HA</sub>	Address Hold from Write End	2		2		2		2		2		ns
t <sub>SA</sub>	Address Set-Up to Write Start	0		0		0		0		0		ns
t <sub>PWE</sub>	Write Pulse Width	12		15		20		25		50		ns
t <sub>SD</sub>	Data Set-Up to Write End	10		13		15		15		25		ns
t <sub>HD</sub>	Data Hold from Write End	0		0		0		0		0		ns
t <sub>HZWE</sub> <sup>[9,10]</sup>	R/W LOW to High Z		10		13		15		20		25	ns
t <sub>LZWE</sub> <sup>[9,10]</sup>	R/W HIGH to Low Z	3		3		3		3		3		ns
t <sub>WDD</sub> <sup>[11]</sup>	Write Pulse to Data Delay		30		40		50		60		70	ns
t <sub>DDD</sub> <sup>[11]</sup>	Write Data Valid to Read Data Valid		25		30		30		35		40	ns
<b>SEMAPHORE TIMING<sup>[12]</sup></b>												
t <sub>SOP</sub>	SEM Flag Update Pulse (OE or SEM)	10		10		10		15		15		ns
t <sub>SWRD</sub>	SEM Flag Write to Read Time	5		5		5		5		5		ns
t <sub>SPS</sub>	SEM Flag Contention Window	5		5		5		5		5		ns

**Notes:**

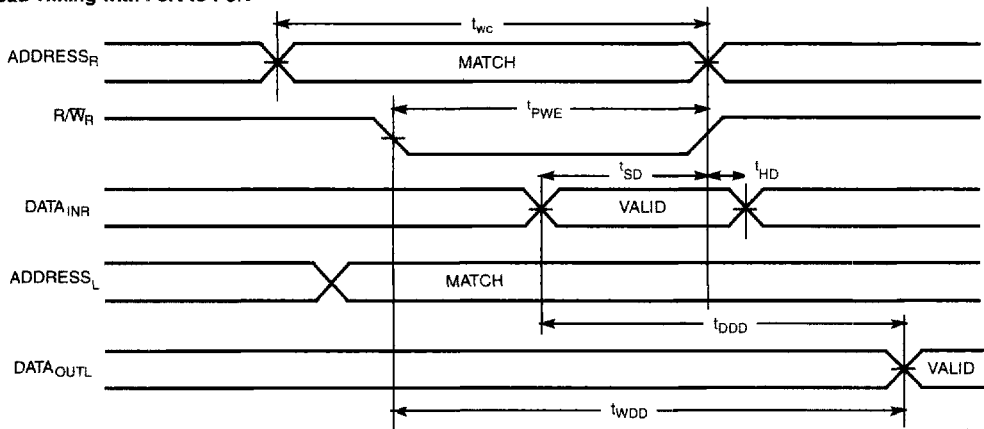
- See the last page of this specification for Group A subgroup testing information.
- Test conditions assume signal transition time of 3 ns or less, timing reference levels of 1.5V, input pulse levels of 0 to 3.0V, and output loading of the specified I<sub>OL</sub>/t<sub>OH</sub> and 30-pF load capacitance.
- At any given temperature and voltage condition for any given device, t<sub>HZCE</sub> is less than t<sub>LZCE</sub> and t<sub>HZOE</sub> is less than t<sub>LZOE</sub>.
- Test conditions used are Load 3.
- This parameter is guaranteed but not tested.
- For information on port-to-port delay through RAM cells from writing port to reading port, refer to Read Timing with Port-to-Port Delay waveform.
- Semaphore timing applies only to CY7C1342.

**Switching Waveforms**
**Read Cycle No. 1<sup>[13,14]</sup>**


1342-9

**Read Cycle No. 2<sup>[13,15]</sup>**


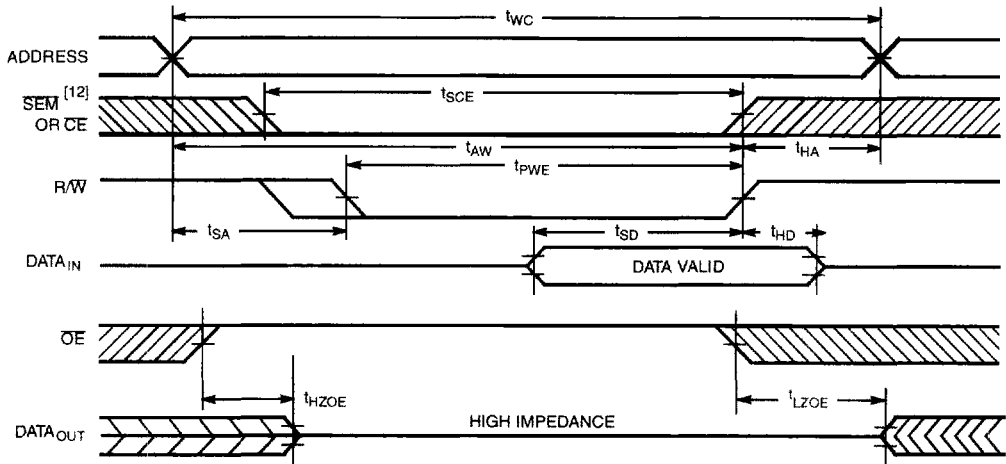
1342-10

**Read Timing with Port-to-Port<sup>[16]</sup>**


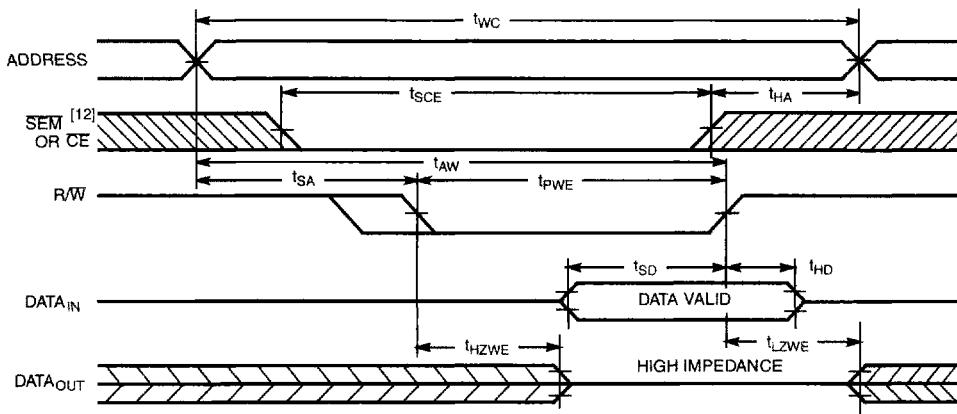
1342-11

**Notes:**

13. R/W is HIGH for read cycle.
14. Device is continuously selected. CE = V<sub>IL</sub> and OE = V<sub>IL</sub>.
15. Address valid prior to or coincident with CE transition LOW.
16. CE<sub>L</sub> = CE<sub>R</sub> = LOW; R/W<sub>L</sub> = HIGH

**Switching Waveforms (continued)**
**Write Cycle No. 1: OE Three-States Data I/Os (Either Port)<sup>[17,18,19]</sup>**


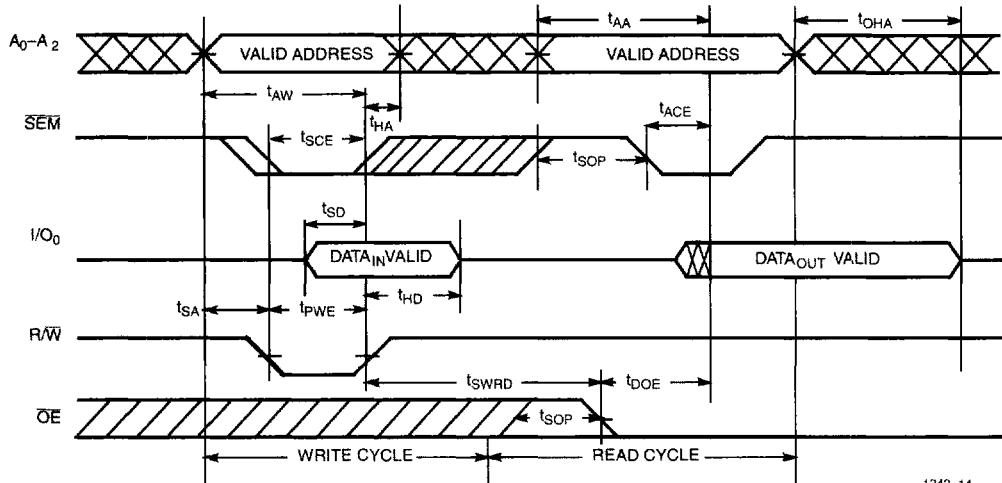
1342-12

**Write Cycle No. 2: R/W Three-States Data I/Os (Either Port)<sup>[18, 20]</sup>**


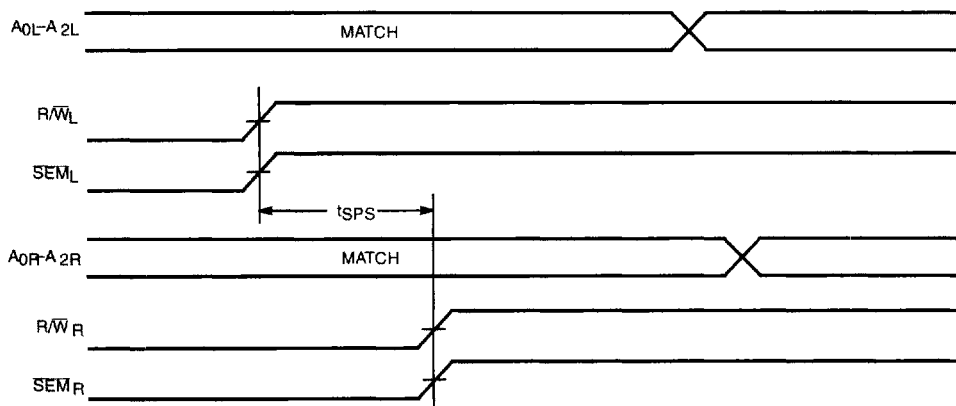
1342-13

**Notes:**

17. The internal write time of the memory is defined by the overlap of CE or SEM LOW and R/W LOW. Both signals must be LOW to initiate a write and either signal can terminate a write by going HIGH. The data input set-up and hold timing should be referenced to the rising edge of the signal that terminates the write.
18. R/W must be HIGH during all address transactions.
19. If OE is LOW during a R/W controlled write cycle, the write pulse width must be the larger of  $t_{PWE}$  or  $(t_{HZWE} + t_{SD})$  to allow the I/O drivers to turn off and data to be placed on the bus for the required  $t_{SD}$ . If OE is HIGH during a R/W controlled write cycle (as in this example), this requirement does not apply and the write pulse can be as short as the specified  $t_{PWE}$ .
20. Data I/O pins enter high-impedance when OE is held LOW during write.

**Switching Waveforms (continued)**
**Semaphore Read After Write Timing, Either Side (CY7C1342 only)<sup>[21]</sup>**


1342-14

**Timing Diagram of Semaphore Contention (CY7C1342 only)<sup>[22,23,24]</sup>**


1342-15

**Notes:**

21.  $\bar{CE} = \text{HIGH}$  for the duration of the above timing (both write and read cycle).
22.  $I/O_{0R} = I/O_{0L} = \text{LOW}$  (request semaphore);  $CE_P = CE_L = \text{HIGH}$ .
23. Semaphores are reset (available to both ports) at cycle start.
24. If  $t_{SPS}$  is violated, it is guaranteed that only one side will gain access to the semaphore.



## Architecture

The CY7C135 consists of an array of 4K words of 8 bits each of dual-port RAM cells, I/O and address lines, and control signals (CE, OE, R/W). Two semaphore control pins exist for the CY7C1342 (SEM<sub>UR</sub>).

## Functional Description

### Write Operation

Data must be set up for a duration of  $t_{SD}$  before the rising edge of R/W in order to guarantee a valid write. Since there is no on-chip arbitration, the user must be sure that a specific location will not be accessed simultaneously by both ports or erroneous data could result. A write operation is controlled by either the OE pin (see Write Cycle No. 1 timing diagram) or the R/W pin (see Write Cycle No. 2 timing diagram). Data can be written  $t_{HZOE}$  after the OE is deasserted or  $t_{HZWE}$  after the falling edge of R/W. Required inputs for write operations are summarized in Table 1.

If a location is being written to by one port and the opposite port attempts to read the same location, a port-to-port flowthrough delay is met before the data is valid on the output. Data will be valid on the port wishing to read the location  $t_{DD}$  after the data is presented on the writing port.

### Read Operation

When reading the device, the user must assert both the OE and CE pins. Data will be available  $t_{ACE}$  after CE or  $t_{DOE}$  after OE are asserted. If the user of the CY7C1342 wishes to access a semaphore, the SEM pin must be asserted instead of the CE pin. Required inputs for read operations are summarized in Table 1.

### Semaphore Operation

The CY7C1342 provides eight semaphore latches which are separate from the dual port memory locations. Semaphores are used to reserve resources which are shared between the two ports. The state of the semaphore indicates that a resource is in use. For example, if the left port wants to request a given resource, it sets a latch by writing a zero to a semaphore location. The left port then verifies its success in setting the latch by reading it. After writing to the semaphore, SEM or OE must be deasserted for  $t_{SDP}$  before attempting to read the semaphore. The semaphore value will be available  $t_{SWRP} + t_{DOE}$  after the rising edge of the semaphore write. If the left port was successful (reads a zero), it assumes control over the shared resource, otherwise (reads a one) it assumes the right port has control and continues to poll the semaphore. When the right side has relinquished control of the semaphore (by writing a one), the left side will succeed in gaining control of the semaphore. If the left side no longer requires the semaphore, a one is written to cancel its request.

Semaphores are accessed by asserting SEM LOW. The SEM pin functions as a chip enable for the semaphore latches. CE must remain HIGH during SEM LOW. A<sub>0-2</sub> represents the semaphore address. OE and R/W are used in the same manner as a normal memory access. When writing or reading a semaphore, the other address pins have no effect.

When writing to the semaphore, only I/O<sub>0</sub> is used. If a 0 is written to the left port of an unused semaphore, a one will

appear at the same semaphore address on the right port. That semaphore can now only be modified by the side showing a zero (the left port in this case). If the left port now relinquishes control by writing a one to the semaphore, the semaphore will be set to one for both sides. However, if the right port had requested the semaphore (written a zero) while the left port had control, the right port would immediately own the semaphore. Table 2 shows sample semaphore operations.

When reading a semaphore, all eight data lines output the semaphore value. The read value is latched in an output register to prevent the semaphore from changing state during a write from the other port. If both ports request a semaphore control by writing a 0 to a semaphore within  $t_{SPS}$  of each other, it is guaranteed that only one side will gain access to the semaphore.

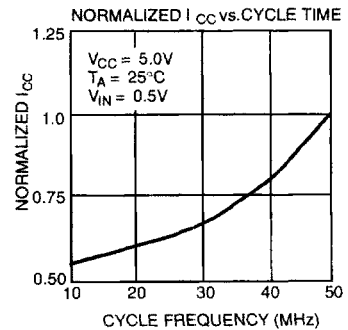
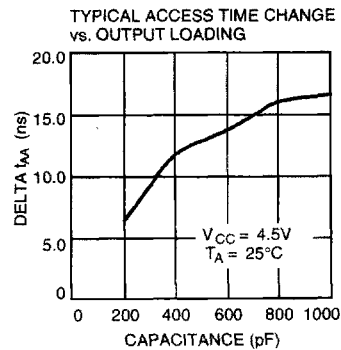
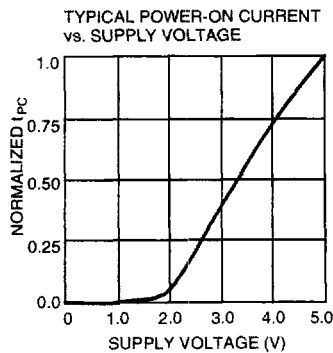
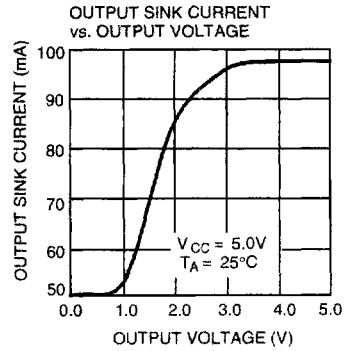
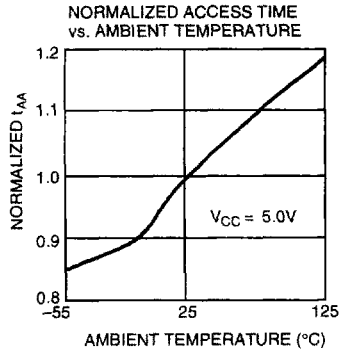
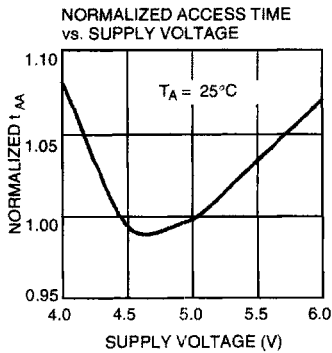
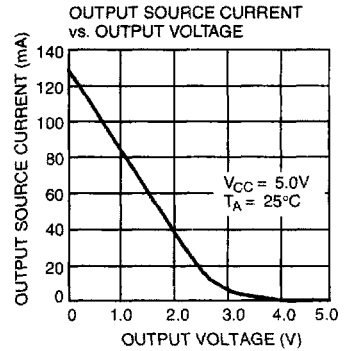
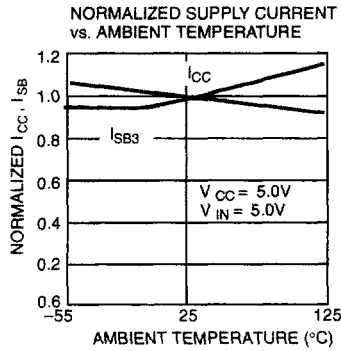
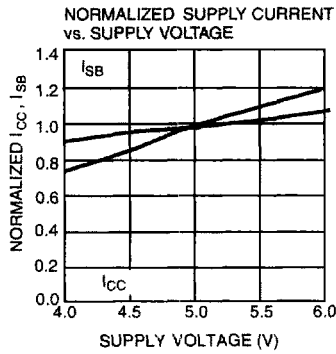
Initialization of the semaphore is not automatic and must be reset during initialization program at power-up. All semaphores on both sides should have a one written into them at initialization from both sides to assure that they will be free when needed.

**Table 1. Non-Contending Read/Write**

Inputs				Outputs	
CE	R/W	OE	SEM	I/O <sub>0</sub> - I/O <sub>7</sub>	Operation
H	X	X	H	High Z	Power-Down
H	H	L	L	Data Out	Read Semaphore
X	X	H	X	High Z	I/O Lines Disabled
H	L	X	L	Data In	Write to Semaphore
L	H	L	H	Data Out	Read
L	L	X	H	Data In	Write
L	X	X	L		Illegal Condition

**Table 2. Semaphore Operation Example**

Function	I/O <sub>0-7</sub> Left	I/O <sub>0-7</sub> Right	Status
No Action	1	1	Semaphore free
Left port writes semaphore	0	1	Left port obtains semaphore
Right port writes 0 to semaphore	0	1	Right side is denied access
Left port writes 1 to semaphore	1	0	Right port is granted access to Semaphore
Left port writes 0 to semaphore	1	0	No change. Left port is denied access
Right port writes 1 to semaphore	0	1	Left port obtains semaphore
Left port writes 1 to semaphore	1	1	No port accessing semaphore address
Right port writes 0 to semaphore	1	0	Right port obtains semaphore
Right port writes 1 to semaphore	1	1	No port accessing semaphore
Left port writes 0 to semaphore	0	1	Left port obtains semaphore
Left port writes 1 to semaphore	1	1	No port accessing semaphore

**Typical DC and AC Characteristics**




**Ordering Information**

**4K x8 Dual-Port SRAM**

Speed (ns)	Ordering Code	Package Name	Package Type	Operating Range
15	CY7C135-15JC	J69	52-Lead Plastic Leaded Chip Carrier	Commercial
20	CY7C135-20JC	J69	52-Lead Plastic Leaded Chip Carrier	Commercial
25	CY7C135-25JC	J69	52-Lead Plastic Leaded Chip Carrier	Commercial
	CY7C135-25JI	J69	52-Lead Plastic Leaded Chip Carrier	Industrial
35	CY7C135-35JC	J69	52-Lead Plastic Leaded Chip Carrier	Commercial
	CY7C135-35JI	J69	52-Lead Plastic Leaded Chip Carrier	Industrial
55	CY7C135-55JC	J69	52-Lead Plastic Leaded Chip Carrier	Commercial
	CY7C135-55JI	J69	52-Lead Plastic Leaded Chip Carrier	Industrial

**4K x8 Dual-Port SRAM with Semaphores**

Speed (ns)	Ordering Code	Package Type	Package Type	Operating Range
15	CY7C1342-15JC	J69	52-Lead Plastic Leaded Chip Carrier	Commercial
20	CY7C1342-20JC	J69	52-Lead Plastic Leaded Chip Carrier	Commercial
25	CY7C1342-25JC	J69	52-Lead Plastic Leaded Chip Carrier	Commercial
	CY7C1342-25JI	J69	52-Lead Plastic Leaded Chip Carrier	Industrial
35	CY7C1342-35JC	J69	52-Lead Plastic Leaded Chip Carrier	Commercial
	CY7C1342-35JI	J69	52-Lead Plastic Leaded Chip Carrier	Industrial
55	CY7C1342-55JC	J69	52-Lead Plastic Leaded Chip Carrier	Commercial
	CY7C1342-55JI	J69	52-Lead Plastic Leaded Chip Carrier	Industrial

Document #: 38-00541

