

NM24C02/C04/C08/C16 2K-/4K-/8K-/16K-Bit Serial EEPROM (I²C Synchronous 2-Wire Bus)

General Description

The NM24C02/C04/C08/C16 devices are 2048/4096/8192/16,384 bits, respectively, of CMOS non-volatile electrically erasable memory. These devices conform to all specifications in the I²C 2-wire protocol and are designed to minimize device pin count and simplify PC board layout requirements.

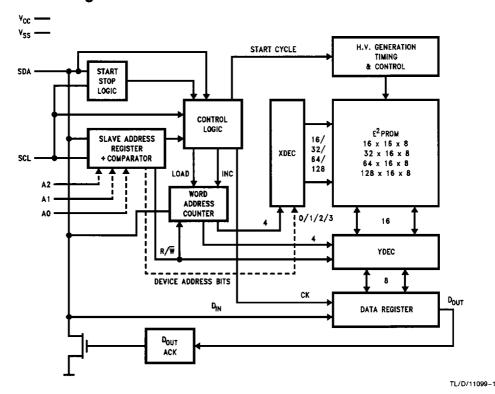
This communication protocol uses CLOCK (SCL) and DATA I/O (SDA) lines to synchronously clock data between the master (for example a microprocessor) and the slave EEPROM device(s). In addition, this bus structure allows for a maximum of 16K of EEPROM memory. This is supported by the NSC family in 2K, 4K, 8K and 16K devices, allowing the user to configure the memory as the application requires with any combination of EEPROMs (not to exceed 16K).

National EEPROMs are designed and tested for applications requiring high endurance, high reliability and low power consumption.

Features

- Low Power CMOS
 - 2 mA active current typical
 - 60 µA standby current typical
- 2-wire I2C serial interface
 - Provides bidirectional data transfer protocol
- Sixteen byte page write mode
 - Minimizes total write time per byte
- Self timed write cycle
 - Typical write cycle time of 5 ms
- Endurance: 106 data changes
- Data retention greater than 40 years
- Packages available: 8 pin mini-DIP or 14 pin SO package

Functional Diagram



TL/D/11099-15

Read Operations (Continued)

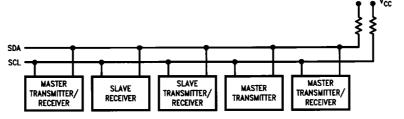


FIGURE 10. Typical System Configuration

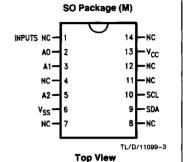
Note: Due to open drain configuration of SDA, a bus-level pull-up resistor is called for, (typical value = 4.7 k Ω)

Connection Diagrams

Dual-In-Line Package (N) A0 1 8 V_{CC} A1 2 NM24C02 7 NC NM24C04 6 SCL V_{SS} 4 NM24C08 6 TL/D/11099-2 Top View

See NS Package Number N08E (N)

See NS Package Number M08A (M8)



See NS Package Number M14B (M)

Pin Names

A0, A1, A2	Device Address Inputs
V _{SS}	Ground
SDA	Data I/O
SCL	Clock Input
NC	No Connection
V _{CC}	+5V

Ordering Information

Commercial Temperature Range (0°C to +70°C)

Order Number NM24C02N/NM24C04N/NM24C08N/NM24C16N NM24C02M/NM24C04M/NM24C08M/NM24C16M NM24C02M8/NM24C04M8

Extended Temperature Range (-40°C to +85°C)

Order Number						
NM24C02EN/NM24C04EN/NM24C08EN/NM24C16EN						
NM24C02EM/NM24C04EM/NM24C08EM/NM24C16EM						
NM24C02EM8/NM24C04EM8						

Military Temperature Range (-55°C to +125°C)

Order Number NM24C02MN/NM24C04MN/NM24C08MN/NM24C16MN NM24C02MM/NM24C04MM/NM24C08MM/NM24C16MM NM24C02MM8/NM24C04MM8

Absolute Maximum Ratings

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/Distributors for availability and specifications.

Ambient Storage Temperature

-65°C to +150°C

All Input or Output Voltages with Respect to Ground

+6.5V to -0.3V

Lead Temperature (Soldering, 10 seconds)

ESD Rating

+300°C

2000V min

Operating Conditions

Ambient Operating Temperature NM24C02/C04/C08/C16 NM24C02E/C04E/C08E/C16E NM24C02M/C04M/C08M/C16M (Mil. Temperature)

0°C to +70°C -40°C to +85°C

-55°C to +125°C 4.5V to 5.5V

Positive Power Supply (V_{CC})

DC and AC Electrical Characteristics $V_{CC} = 5V \pm 10\%$ unless otherwise specified

Symbol	Parameter	Test Conditions	Min	Typ (Note 1)	Max	Units
ICCA	Active Power Supply Current	f _{SCL} = 100 kHz		2.0	3.0	mA
I _{SB}	Standby Current	V _{IN} = GND or V _{CC}		60	100	μΑ
l _U	Input Leakage Current	V _{IN} = GND to V _{CC}		0.1	10	μΑ
lLO	Output Leakage Current	$V_{OUT} = GND \text{ to } V_{CC}$		0.1	10	μА
VIL	Input Low Voltage		-0.3		$V_{CC} \times 0.3$	٧
V _{IH}	Input High Voltage		$V_{CC} \times 0.7$		V _{CC} + 0.5	٧
V _{OL}	Output Low Voltage	I _{OL} = 3 mA			0.4	V

Capacitance $T_A = 25^{\circ}C$, f = 1.0 MHz, $V_{CC} = 5V$

Symbol	Test	Max	Units	
C _{I/O} (Note 2)	Input/Output Capacitance (SDA)	V _{I/O} = 0V	8	pF
C _{IN} (Note 2)	Input Capacitance (A0, A1, A2, SCL)	V _{IN} = 0V	6	pF

AC Conditions of Test

Input Pulse Levels	$V_{CC} \times$ 0.1 to $V_{CC} \times$ 0.9				
Input Rise and Fall Times	10 ns				
Input and Output Timing Levels	V _{CC} × 0.5				
Output Load	1 TTL Gate and $C_L = 100 \text{ pF}$				

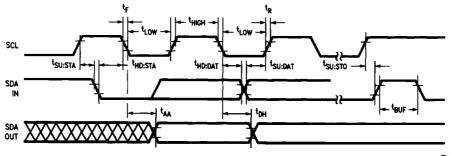
Note 1: Typical values are for $T_A = 25^{\circ}\text{C}$ and nominal supply voltage (5V).

Note 2: This parameter is periodically sampled and not 100% tested.

SCL Clock Frequency Noise Suppression Time Constant at SCL, SDA Inputs SCL Low to SDA Data Out Valid Time the Bus Must Be Free before a New Transmission Can Start Start Condition Hold Time	0.3 4.7	100	kHz ns μs μs
Constant at SCL, SDA Inputs SCL Low to SDA Data Out Valid Time the Bus Must Be Free before a New Transmission Can Start	4.7		μs
Time the Bus Must Be Free before a New Transmission Can Start	4.7	3.5	
before a New Transmission Can Start			μs
Start Condition Hold Time	4.0		
			μs
Clock Low Period	4.7		μs
Clock High Period	4.0		μs
Start Condition Setup Time (for a Repeated Start Condition)	4.7	!	μs
Data in Hold Time	0		μs
Data in Setup Time	250		ns
SDA and SCL Rise Time		1	μs
SDA and SCL Fall Time		300	ns
Stop Condition Setup Time	4.7		μs
Data Out Hold Time	300		ns
	Start Condition Setup Time (for a Repeated Start Condition) Data in Hold Time Data in Setup Time SDA and SCL Rise Time SDA and SCL Fall Time Stop Condition Setup Time	Start Condition Setup Time 4.7 (for a Repeated Start Condition) 4.7 Data in Hold Time 0 Data in Setup Time 250 SDA and SCL Rise Time SDA and SCL Fall Time Stop Condition Setup Time 4.7 Data Out Hold Time 300	Start Condition Setup Time 4.7 (for a Repeated Start Condition) 0 Data in Hold Time 0 Data in Setup Time 250 SDA and SCL Rise Time 1 SDA and SCL Fall Time 300 Stop Condition Setup Time 4.7 Data Out Hold Time 300

Note 3: The write cycle time (twn) is the time from a valid stop condition of a write sequence to the end of the internal erase/program cycle. During the write cycle, the NM24Cxx bus interface circuits are disabled, SDA is allowed to remain high per the bus-level pull-up resistor, and the device does not respond to its slave address.

Bus Timing



BACKGROUND INFORMATION (12C Bus)

As mentioned, the I²C bus allows synchronous bidirectional communication between transmitter/Receiver using the SCL (clock) and SDA (Data I/O) lines. All communication must be started with a valid START condition, concluded with a STOP condition and acknowledged by the Receiver with an ACKNOWLEDGE condition.

In addition, since the I²C bus is designed to support other devices such as RAM, EPROM, etc., the device type identifier string must follow the START condition. For EEPROMs, this 4-bit string is 1010.

As shown below, the EEPROMS on the I²C bus may be configured in any manner required, providing the total memory addressed does not exceed 16K (16,834 bits). EEPROM memory addressing is controlled by two methods:

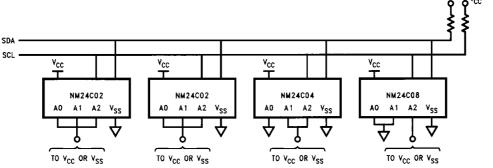
- Hardware configuring the A0, A1 and A2 pins (Device Address pins) with pull-up or pull-down resistors. ALL UNUSED PINS MUST BE GROUNDED (Tied to V_{SS}).
- Software addressing the required PAGE BLOCK within the device memory array (as sent in the Slave Address string).

Addressing an EEPROM memory location involves sending a command string with the following information:

[DEVICE TYPE]—[DEVICE ADDRESS]—[PAGE BLOCK ADDRESS]—[BYTE ADDRESS]

DEFINITIONS						
WORD	8 bits (byte) of data.					
PAGE	16 sequential addresses (one byte each) that may be programmed during a "Page Write" programming cycle.					
PAGE BLOCK	2,048 (2K) bits organized into 16 pages of addressable memory. (8 bits) x (16 bytes) x (16 pages) = 2,048 bits					
MASTER	Any I ² C device CONTROLLING the transfer of data (such as a microprocessor).					
SLAVE	Device being controlled (EEPROMs are always considered Slaves).					
TRANSMITTER	Device currently SENDING data on the bus (may be either a Master OR Slave).					
RECEIVER	Device currently receiving data on the bus (Master or Slave).					

Example of 16K (Maximum Size) of Memory on 2-Wire Bus



TL/D/11099-20

Note: The SDA pull-up resistor is required due to the open-drain/open-collector output of I²C bus devices.

Note: The SCL pull-up resistor is recommended because of the normal SCL line inactive "high" state.

Note: It is recommended that the total line capacitance be less than 400 pF.

Note: Specific timing and addressing considerations are described in greater detail in the following sections.

Device	Α	ddress Pir	IS	Memory Size	Number of	
Bevice	A0	A 1	A2	memory one	Page Blocks	
NM24C02	DA	DA	DA	2048 Bits	1	
NM24C04	V _{SS}	DA	DA	4096 Bits	2	
NM24C08	VSS	V _{SS}	DA	8192 Bits	4	
NM24C16	V _{SS}	V _{SS}	V _{SS}	16,384 Bits	8	

DA: Device Address

Pin Descriptions

SERIAL CLOCK (SCL)

The SCL input is used to clock all data into and out of the device.

SERIAL DATA (SDA)

SDA is a bidirectional pin used to transfer data into and out of the device. It is an open drain output and may be wire-ORed with any number of open drain or open collector outputs.

DEVICE ADDRESS INPUTS (A0. A1. A2)

Device address pins A0, A1 and A2 are connected to V_{CC} or V_{SS} to configure the EEPROM address. The following table (Table A) shows the active pins across the NM24Cxx device family.

TABLE A

Device	AO	A1	A2	Effects of Addresses					
NM24C02	ADR	ADR	ADR	23 = 8	$(8) \times (2K) = 16K$				
NM24C04	Х	ADR	ADR	$2^2 = 4$	$(4) \times (4K) = 16K$				
NM24C08	Х	Х	ADR	21 = 2	$(2) \times (8K) = 16K$				
NM24C16	Х	X	x	20 = 1	$(1) \times (16K) = 16K$				

ADR: Denotes an active pin used for device addressing
X: Not used for addressing (Must be tied to Ground/Vss)

Device Operation

The NM24Cxx supports a bidirectional bus oriented protocol. The protocol defines any device that sends data onto the bus as a transmitter and the receiving device as the receiver. The device controlling the transfer is the master and the device that is controlled is the slave. The master will always initiate data transfers and provide the clock for both transmit and receive operations. Therefore, the NM24Cxx will be considered a slave in all applications.

CLOCK AND DATA CONVENTIONS

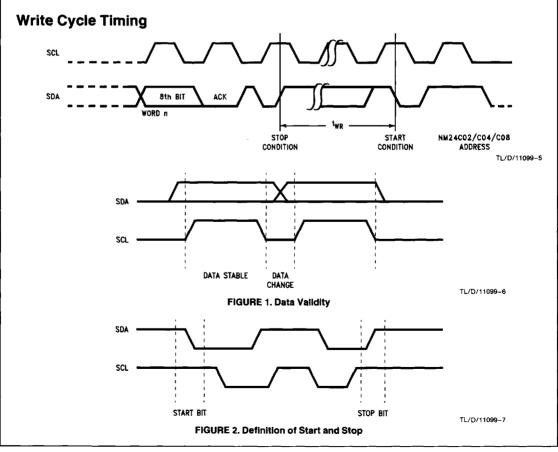
Data states on the SDA line can change only during SCL LOW. SDA state changes during SCL HIGH are reserved for indicating start and stop conditions. Refer to *Figures 1* and 2

START CONDITION

All commands are preceded by the start condition, which is a HIGH to LOW transition of SDA when SCL is HIGH. The NM24Cxx continuously monitors the SDA and SCL lines for the start condition and will not respond to any command until this condition has been met.

STOP CONDITION

All communications are terminated by a stop condition, which is a LOW to HIGH transition of SDA when SCL is HIGH. The stop condition is also used by the NM24Cxx to place the device in the standby power mode.



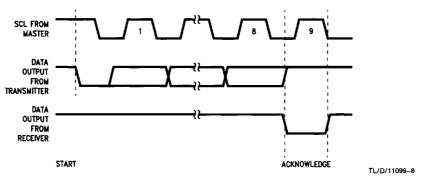


FIGURE 3. Acknowledge Response from Receiver

ACKNOWLEDGE

Acknowledge is a software convention used to indicate successful data transfers. The transmitting device, either master or slave, will release the bus after transmitting eight bits. During the ninth clock cycle the receiver will pull the SDA line LOW to acknowledge that it received the eight bits of data. Refer to Figure 3.

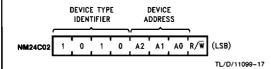
The NM24Cxx device will always respond with an acknowledge after recognition of a start condition and its slave address. If both the device and a write operation have been

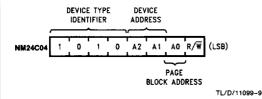
selected, the NM24Cxx will respond with an acknowledge after the receipt of each subsequent eight bit word.

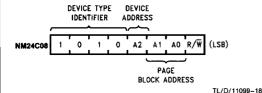
In the read mode the NM24Cxx slave will transmit eight bits of data, release the SDA line and monitor the line for an acknowledge. If an acknowledge is detected and no stop condition is generated by the master, the slave will continue to transmit data. If an acknowledge is not detected, the slave will terminate further data transmissions and await the stop condition to return to the standby power mode.

Device Addressing

Following a start condition the master must output the address of the slave it is accessing. The most significant four bits of the slave address are those of the device type identifier (see *Figure 4*). This is fixed as 1010 for all four devices: NM24C02, NM24C04, NM24C08 and NM24C16.







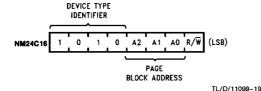


FIGURE 4. Slave Addresses

DEVICE ADDRESSING

Refer to the following table for Slave Addresss string details:

D	evice	ΑO	A1	A2		nber of Blocks	Page Block Addresses					808
NM	124C02	Α	Α	Α	1	(2K)			(N	ONE)		
NM	124C04	P	Α	Α	2	(4K)	0	1				
NM	124C08	Р	Р	Α	4	(8K)	00	01	10	11		
NM	124C16	Р	Р	Р	8	(16K)	000	001	010	011		111

A: Refers to a hardware configured Device Address pin P: Refers to an internal PAGE BLOCK memory segment

All I²C EEPROMs use an internal protocol that defines a PAGE BLOCK size of 2K bits (for Word addresses 0000 through 1111). Therefore, address bits A0, A1 or A2 (if designated "P") are used to access a PAGE BLOCK in conjunction with the Word address used to access any individual data byte (Word).

The last bit of the slave address defines whether a write or read condition is requested by the master. A "1" indicates that a read operation is to be executed, and a "0" initiates the write mode.

A simple review: After the NM24C02/C04/C08/C16 recognizes the start condition, the devices interfaced to the I²C bus wait for a slave address to be transmitted over the SDA line. If the transmitted slave address matches an address of one of the devices, the designated slave pulls the line LOW with an acknowledge signal and awaits further transmissions

Write Operations

BYTE WRITE

For a write operation a second address field is required which is a word address that is comprised of eight bits and provides access to any one of the 256 words in the selected page of memory. Upon receipt of the word address the NM24Cxx responds with an acknowledge and waits for the next eight bits of data, again, responding with an acknowledge. The master then terminates the transfer by generating a stop condition, at which time the NM24Cxx begins the internal write cycle to the nonvolatile memory. While the internal write cycle is in progress the NM24Cxx inputs are disabled, and the device will not respond to any requests from the master. Refer to Figure 5 for the address, acknowledge and data transfer sequence.

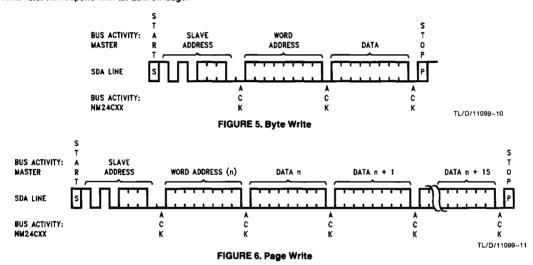
PAGE WRITE

The NM24Cxx is capable of a sixteen byte page write operation. It is initiated in the same manner as the byte write operation; but instead of terminating the write cycle after the first data word is transferred, the master can transmit up to fifteen more words. After the receipt of each word, the NM24Cxx will respond with an acknowledge.

After the receipt of each word, the internal address counter increments to the next address and the next SDA data is accepted. If the master should transmit more than sixteen words prior to generating the stop condition, the address counter will "roll over" and the previously written data will be overwritten. As with the byte write operation, all inputs are disabled until completion of the internal write cycle. Refer to Figure 6 for the address, acknowledge and data transfer sequence.

ACKNOWLEDGE POLLING

Once the stop condition is issued to indicate the end of the host's write operation the NM24Cxx initiates the internal write cycle. ACK polling can be initiated immediately. This involves issuing the start condition followed by the slave address for a write operation. If the NM24Cxx is still busy with the write operation no ACK will be returned. If the NM24Cxx has completed the write operation an ACK will be returned and the host can then proceed with the next read or write operation.



Read Operations

Read operations are initiated in the same manner as write operations, with the exception that the R/\overline{W} bit of the slave address is set to a one. There are three basic read operations: current address read, random read and sequential read.

CURRENT ADDRESS READ

Internally the NM24Cxx contains an address counter that maintains the address of the last word accessed, incremented by one. Therefore, if the last access (either a read or write) was to address n, the next read operation would access data from address n \pm 1. Upon receipt of the slave address with R/\overline{W} set to one, the NM24Cxx issues an acknowledge and transmits the eight bit word. The master will not acknowledge the transfer but does generate a stop condition, and therefore the NM24Cxx discontinues tranmission. Refer to Figure 7 for the sequence of address, acknowledge and data transfer.

RANDOM READ

Random read operations allow the master to access any memory location in a random manner. Prior to issuing the slave address with the R/\overline{W} bit set to one, the master must first perform a "dummy" write operation. The master issues the start condition, slave address and then the word ad-

dress it is to read. After the word address acknowledge, the master immediately reissues the start condition and the slave address with the R/\overline{W} bit set to one. This will be followed by an acknowledge from the NM24Cxx and then by the eight bit word. The master will not acknowledge the transfer but does generate the stop condition, and therefore the NM24Cxx discontinues transmission. Refer to Figure 8 for the address, acknowledge and data transfer sequence.

SEQUENTIAL READ

Sequential reads can be initiated as either a current address read or random access read. The first word is transmitted in the same manner as the other read modes; however, the master now responds with an acknowledge, indicating it requires additional data. The NM24Cxx continues to output data for each acknowledge received. The read operation is terminated by the master not responding with an acknowledge or by generating a stop condition.

The data output is sequential, with the data from address n followed by the data from n+1. The address counter for read operations increments all word address bits, allowing the entire memory contents to be serially read during one operation. After the entire memory has been read, the counter "rolls over" and the NM24Cxx continues to output data for each acknowledge received. Refer to Figure 9 for the address, acknowledge and data transfer sequence.

