



Dear customers,

**About the change in the name such as "Oki Electric Industry Co. Ltd." and "OKI" in documents to OKI Semiconductor Co., Ltd.**

The semiconductor business of Oki Electric Industry Co., Ltd. was succeeded to OKI Semiconductor Co., Ltd. on October 1, 2008. Therefore, please accept that although the terms and marks of "Oki Electric Industry Co., Ltd.", "Oki Electric", and "OKI" remain in the documents, they all have been changed to "OKI Semiconductor Co., Ltd.". It is a change of the company name, the company trademark, and the logo, etc. , and NOT a content change in documents.

October 1, 2008  
OKI Semiconductor Co., Ltd.

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**OKI Semiconductor****FEDD51V16165F-03**  
Issue Date: Aug. 16, 2002**MSM51V16165F****1,048,576-Word × 16-Bit DYNAMIC RAM : FAST PAGE MODE TYPE WITH EDO****DESCRIPTION**

The MSM51V16165F is a 1,048,576-word × 16-bit dynamic RAM fabricated in Oki's silicon-gate CMOS technology. The MSM51V16165F achieves high integration, high-speed operation, and low-power consumption because Oki manufactures the device in a quadruple-layer polysilicon/double-layer metal CMOS process. The MSM51V16165F is available in a 50/44-pin plastic TSOP.

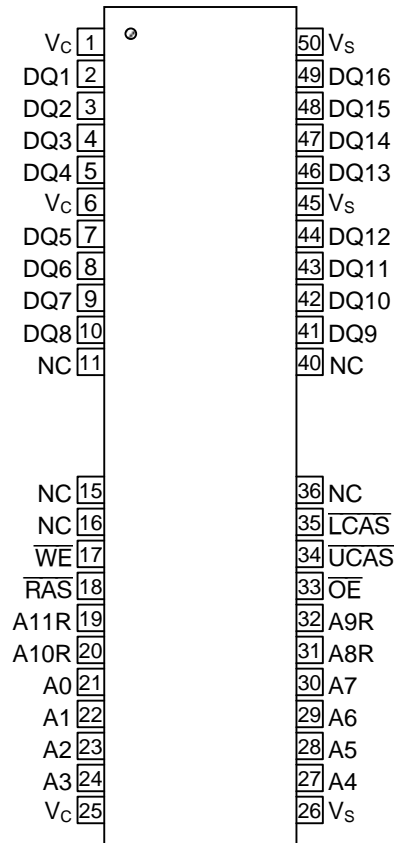
**FEATURES**

- 1,048,576-word × 16-bit configuration
- Single 3.3V power supply, ±0.3V tolerance
- Input : LVTTL compatible, low input capacitance
- Output : LVTTL compatible, 3-state
- Refresh : 4096 cycles/64ms
- Fast page mode with EDO, read modify write capability
- CAS before  $\overline{\text{RAS}}$  refresh, hidden refresh,  $\overline{\text{RAS}}$ -only refresh capability
- Packages  
50/44-pin 400mil plastic TSOP (TSOPII50/44-P-400-0.80-K) (Product : MSM51V16165F-xxTS-K)  
xx indicates speed rank.

**PRODUCT FAMILY**

Family	Access Time (Max.)				Cycle Time (Min.)	Power Dissipation	
	t <sub>RAC</sub>	t <sub>AA</sub>	t <sub>CAC</sub>	t <sub>OEA</sub>		Operating (Max.)	Standby (Max.)
MSM51V16165F	50ns	25ns	13ns	13ns	84ns	270mW	1.8mW
	60ns	30ns	15ns	15ns	104ns	252mW	
	70ns	35ns	20ns	20ns	124ns	234mW	

**PIN CONFIGURATION (TOP VIEW)**

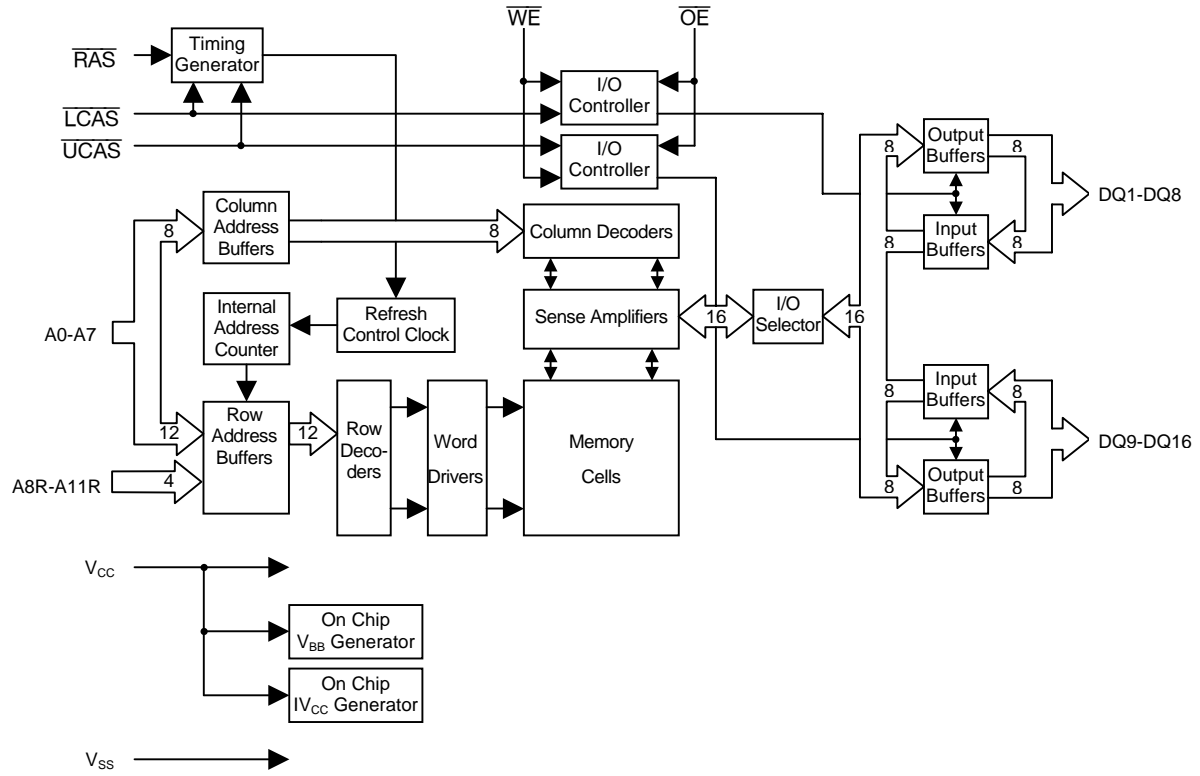


50/44-Pin Plastic TSOP  
(K Type)

Pin Name	Function
A0–A7, A8R–A11R	Address Input
$\overline{\text{RAS}}$	Row Address Strobe
$\overline{\text{LCAS}}$	Lower Byte Column Address Strobe
$\overline{\text{UCAS}}$	Upper Byte Column Address Strobe
DQ1–DQ16	Data Input/Data Output
$\overline{\text{OE}}$	Output Enable
$\overline{\text{WE}}$	Write Enable
$V_{\text{CC}}$	Power Supply (3.3V)
$V_{\text{SS}}$	Ground (0V)
NC	No Connection

Note : The same power supply voltage must be provided to every  $V_{\text{CC}}$  pin, and the same GND voltage level must be provided to every  $V_{\text{SS}}$  pin.

**BLOCK DIAGRAM**



**FUNCTION TABLE**

Input Pin					DQ Pin		Function Mode
$\overline{\text{RAS}}$	$\overline{\text{LCAS}}$	$\overline{\text{UCAS}}$	$\overline{\text{WE}}$	$\overline{\text{OE}}$	DQ1-DQ8	DQ9-DQ16	
H	*	*	*	*	High-Z	High-Z	Standby
L	H	H	*	*	High-Z	High-Z	Refresh
L	L	H	H	L	D <sub>OUT</sub>	High-Z	Lower Byte Read
L	H	L	H	L	High-Z	D <sub>OUT</sub>	Upper Byte Read
L	L	L	H	L	D <sub>OUT</sub>	D <sub>OUT</sub>	Word Read
L	L	H	L	H	D <sub>IN</sub>	Don't Care	Lower Byte Write
L	H	L	L	H	Don't Care	D <sub>IN</sub>	Upper Byte Write
L	L	L	L	H	D <sub>IN</sub>	D <sub>IN</sub>	Word Write
L	L	L	H	H	High-Z	High-Z	—

\* : "H" or "L"

**ELECTRICAL CHARACTERISTICS****ABSOLUTE MAXIMUM RATINGS**

Parameter	Symbol	Value	Unit
Voltage on Any Pin Relative to $V_{SS}$	$V_{IN}, V_{OUT}$	-0.5 to $V_{CC}+0.5$	V
Voltage $V_{CC}$ Supply relative to $V_{SS}$	$V_{CC}$	-0.5 to 4.6	V
Short Circuit Output Current	$I_{OS}$	50	mA
Power Dissipation	$P_{D^*}$	1	W
Operating Temperature	$T_{opr}$	0 to 70	°C
Storage Temperature	$T_{stg}$	-55 to 150	°C

\*:  $T_a = 25^{\circ}\text{C}$ **RECOMMENDED OPERATING CONDITIONS**

(Ta = 0 to 70°C)

Parameter	Symbol	Min.	Typ.	Max.	Unit
Power Supply Voltage	$V_{CC}$	3.0	3.3	3.6	V
	$V_{SS}$	0	0	0	V
Input High Voltage	$V_{IH}$	2.0	—	$V_{CC} + 0.3^{*1}$	V
Input Low Voltage	$V_{IL}$	$-0.3^{*2}$	—	0.8	V

Notes: \*1. The input voltage is  $V_{CC} + 1.0\text{V}$  when the pulse width is less than 20ns (the pulse width is with respect to the point at which  $V_{CC}$  is applied).

\*2. The input voltage is  $V_{SS} - 1.0\text{V}$  when the pulse width is less than 20ns (the pulse width respect to the point at which  $V_{SS}$  is applied).

**PIN CAPACITANCE**

(Vcc = 3.3V ± 0.3V, Ta = 25°C, f = 1 MHz)

Parameter	Symbol	Min.	Max.	Unit
Input Capacitance (A0 – A7, A8R – A11R)	$C_{IN1}$	—	5	pF
Input Capacitance ( $\overline{\text{RAS}}$ , $\overline{\text{LCAS}}$ , $\overline{\text{UCAS}}$ , $\overline{\text{WE}}$ , $\overline{\text{OE}}$ )	$C_{IN2}$	—	7	pF
Output Capacitance (DQ1 - DQ16)	$C_{I/O}$	—	7	pF

## DC CHARACTERISTICS

(V<sub>CC</sub> = 3.3V ± 0.3V, T<sub>a</sub> = 0 to 70°C)

Parameter	Symbol	Condition	MSM51V16165 F-50		MSM51V16165 F-60		MSM51V16165 F-70		Unit	Note
			Min.	Max.	Min.	Max.	Min.	Max.		
Output High Voltage	V <sub>OH</sub>	I <sub>OH</sub> = -2.0mA	2.4	V <sub>CC</sub>	2.4	V <sub>CC</sub>	2.4	V <sub>CC</sub>	V	
Output Low Voltage	V <sub>OL</sub>	I <sub>OL</sub> = 2mA	0	0.4	0	0.4	0	0.4	V	
Input Leakage Current	I <sub>LI</sub>	0V ≤ V <sub>I</sub> ≤ V <sub>CC</sub> +0.3V; All other pins not under test = 0V	- 10	10	- 10	10	- 10	10	μA	
Output Leakage Current	I <sub>LO</sub>	DQ disable 0V ≤ V <sub>O</sub> ≤ V <sub>CC</sub>	- 10	10	- 10	10	- 10	10	μA	
Average Power Supply Current (Operating)	I <sub>CC1</sub>	$\overline{\text{RAS}}$ , $\overline{\text{CAS}}$ cycling, t <sub>RC</sub> = Min.	—	75	—	70	—	65	mA	1,2
Power Supply Current (Standby)	I <sub>CC2</sub>	$\overline{\text{RAS}}$ , $\overline{\text{CAS}} = V_{IH}$	—	2	—	2	—	2	mA	1
		$\overline{\text{RAS}}$ , $\overline{\text{CAS}} \geq V_{CC} - 0.2V$	—	0.5	—	0.5	—	0.5		
Average Power Supply Current ( $\overline{\text{RAS}}$ -only Refresh)	I <sub>CC3</sub>	$\overline{\text{RAS}}$ cycling, $\overline{\text{CAS}} = V_{IH}$ , t <sub>RC</sub> = Min.	—	75	—	70	—	65	mA	1,2
Power Supply Current (Standby)	I <sub>CC5</sub>	$\overline{\text{RAS}} = V_{IH}$ , $\overline{\text{CAS}} = V_{IL}$ , DQ = enable	—	5	—	5	—	5	mA	1
Average Power Supply Current ( $\overline{\text{CAS}}$ before $\overline{\text{RAS}}$ Refresh)	I <sub>CC6</sub>	$\overline{\text{RAS}} = \text{cycling}$ , $\overline{\text{CAS}}$ before $\overline{\text{RAS}}$	—	75	—	70	—	65	mA	1,2
Average Power Supply Current (Fast Page Mode)	I <sub>CC7</sub>	$\overline{\text{RAS}} = V_{IL}$ , $\overline{\text{CAS}}$ cycling, t <sub>HPC</sub> = Min.	—	75	—	70	—	65	mA	1,3

- Notes: 1. I<sub>CC</sub> Max. is specified as I<sub>CC</sub> for output open condition.  
2. The address can be changed once or less while  $\overline{\text{RAS}} = V_{IL}$ .  
3. The address can be changed once or less while  $\overline{\text{CAS}} = V_{IH}$ .

## AC CHARACTERISTICS (1/2)

(V<sub>CC</sub> = 3.3V ± 0.3V, T<sub>a</sub> = 0 to 70°C) Note1,2,3

Parameter	Symbol	MSM51V16165 F-50		MSM51V16165 F-60		MSM51V16165 F-70		Unit	Note
		Min.	Max.	Min.	Max.	Min.	Max.		
Random Read or Write Cycle Time	t <sub>RC</sub>	84	—	104	—	124	—	ns	
Read Modify Write Cycle Time	t <sub>RWC</sub>	110	—	135	—	160	—	ns	
Fast Page Mode Cycle Time	t <sub>HPC</sub>	20	—	25	—	30	—	ns	
Fast Page Mode Read Modify Write Cycle Time	t <sub>HPRWC</sub>	58	—	68	—	78	—	ns	
Access Time from RAS	t <sub>RAC</sub>	—	50	—	60	—	70	ns	4, 5, 6
Access Time from CAS	t <sub>CAC</sub>	—	13	—	15	—	20	ns	4,5
Access Time from Column Address	t <sub>AA</sub>	—	25	—	30	—	35	ns	4,6
Access Time from CAS Precharge	t <sub>CPA</sub>	—	30	—	35	—	40	ns	4,13
Access Time from OE	t <sub>OEA</sub>	—	13	—	15	—	20	ns	4
Output Low Impedance Time from CAS	t <sub>CLZ</sub>	0	—	0	—	0	—	ns	4
Data Output Hold After CAS Low	t <sub>DOH</sub>	5	—	5	—	5	—	ns	
CAS to Data Output Buffer Turn-off Delay Time	t <sub>CEZ</sub>	0	13	0	15	0	20	ns	7,8
RAS to Data Output Buffer Turn-off Delay Time	t <sub>REZ</sub>	0	13	0	15	0	20	ns	7,8
OE to Data Output Buffer Turn-off Delay Time	t <sub>OEZ</sub>	0	13	0	15	0	20	ns	7
WE to Data Output Buffer Turn-off Delay Time	t <sub>WEZ</sub>	0	13	0	15	0	20	ns	7
Transition Time	t <sub>T</sub>	1	50	1	50	1	50	ns	3
Refresh Period	t <sub>REF</sub>	—	64	—	64	—	64	ms	
RAS Precharge Time	t <sub>RP</sub>	30	—	40	—	50	—	ns	
RAS Pulse Width	t <sub>RAS</sub>	50	10,000	60	10,000	70	10,000	ns	
RAS Pulse Width (Fast Page Mode with EDO)	t <sub>RASP</sub>	50	100,000	60	100,000	70	100,000	ns	
RAS Hold Time	t <sub>RSH</sub>	7	—	10	—	13	—	ns	
RAS Hold Time referenced to OE	t <sub>ROH</sub>	7	—	10	—	13	—	ns	
CAS Precharge Time (Fast Page Mode with EDO)	t <sub>CP</sub>	7	—	10	—	10	—	ns	15
CAS Pulse Width	t <sub>CAS</sub>	7	10,000	10	10,000	13	10,000	ns	
CAS Hold Time	t <sub>CSH</sub>	35	—	40	—	45	—	ns	
CAS to RAS Precharge Time	t <sub>CRP</sub>	5	—	5	—	5	—	ns	13
RAS Hold Time from CAS Precharge	t <sub>RHCP</sub>	30	—	35	—	40	—	ns	13

## AC CHARACTERISTICS (2/2)

(V<sub>CC</sub> = 3.3V ± 0.3V, T<sub>a</sub> = 0 to 70°C) Note1,2,3

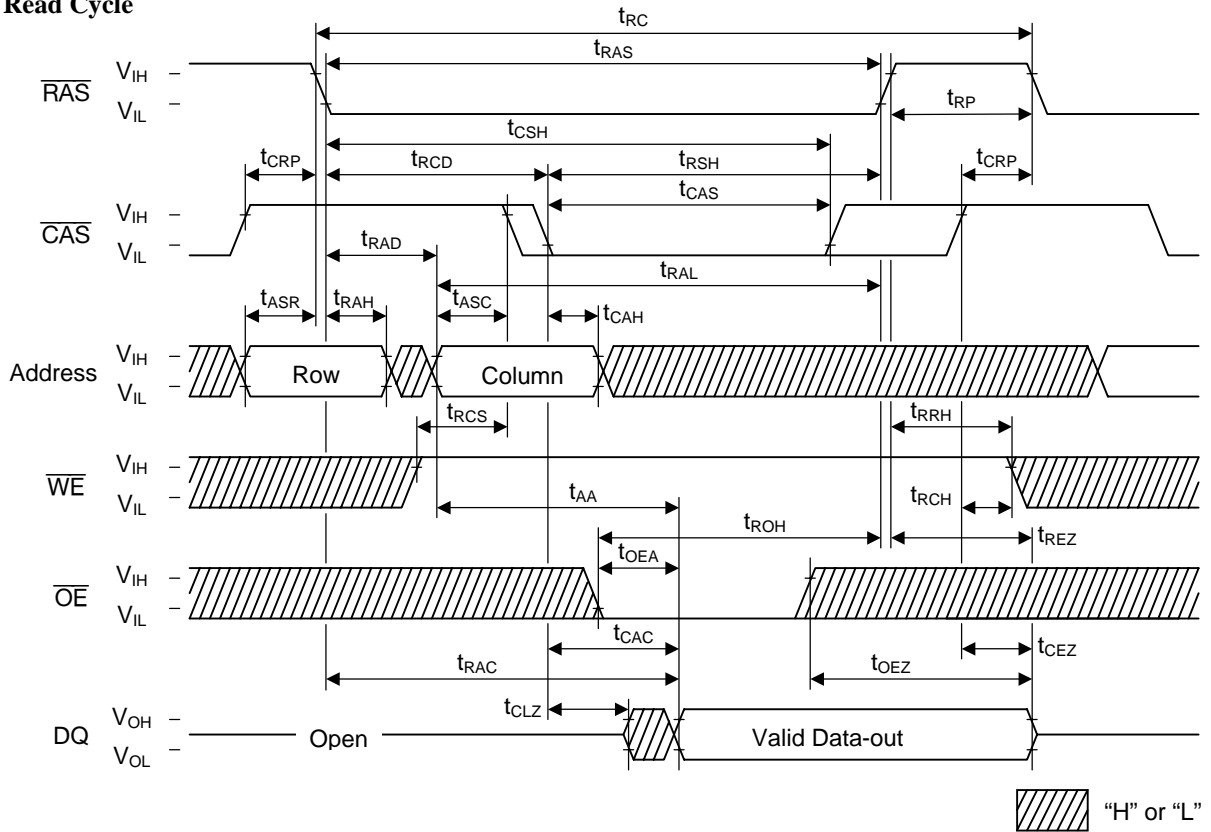
Parameter	Symbol	MSM51V16165 F-50		MSM51V16165 F-60		MSM51V16165 F-70		Unit	Note
		Min.	Max.	Min.	Max.	Min.	Max.		
$\overline{OE}$ Hold Time from $\overline{CAS}$ (DQ Disable)	t <sub>CHO</sub>	5	—	5	—	5	—	ns	
$\overline{RAS}$ to $\overline{CAS}$ Delay Time	t <sub>RCD</sub>	11	37	14	45	14	50	ns	5
$\overline{RAS}$ to Column Address Delay Time	t <sub>RAD</sub>	9	25	12	30	12	35	ns	6
Row Address Set-up Time	t <sub>ASR</sub>	0	—	0	—	0	—	ns	
Row Address Hold Time	t <sub>RAH</sub>	7	—	10	—	10	—	ns	
Column Address Set-up Time	t <sub>ASC</sub>	0	—	0	—	0	—	ns	12
Column Address Hold Time	t <sub>CAH</sub>	7	—	10	—	13	—	ns	12
Column Address to $\overline{RAS}$ Lead Time	t <sub>RAL</sub>	25	—	30	—	35	—	ns	
Read Command Set-up Time	t <sub>RCS</sub>	0	—	0	—	0	—	ns	12
Read Command Hold Time	t <sub>RCH</sub>	0	—	0	—	0	—	ns	9,12
Read Command Hold Time referenced to $\overline{RAS}$	t <sub>RRH</sub>	0	—	0	—	0	—	ns	9
Write Command Set-up Time	t <sub>WCS</sub>	0	—	0	—	0	—	ns	10,12
Write Command Hold Time	t <sub>WCH</sub>	7	—	10	—	13	—	ns	12
Write Command Pulse Width	t <sub>WP</sub>	7	—	10	—	10	—	ns	
$\overline{WE}$ Pulse Width (DQ Disable)	t <sub>WPE</sub>	7	—	10	—	10	—	ns	
$\overline{OE}$ Command Hold Time	t <sub>OEH</sub>	7	—	10	—	13	—	ns	
$\overline{OE}$ Precharge Time	t <sub>OEP</sub>	7	—	10	—	10	—	ns	
$\overline{OE}$ Command Hold Time	t <sub>OCH</sub>	7	—	10	—	10	—	ns	
Write Command to $\overline{RAS}$ Lead Time	t <sub>RWL</sub>	7	—	10	—	13	—	ns	
Write Command to $\overline{CAS}$ Lead Time	t <sub>CWL</sub>	7	—	10	—	13	—	ns	14
Data-in Set-up Time	t <sub>DS</sub>	0	—	0	—	0	—	ns	11,12
Data-in Hold Time	t <sub>DH</sub>	7	—	10	—	13	—	ns	11,12
$\overline{OE}$ to Data-in Delay Time	t <sub>OED</sub>	13	—	15	—	20	—	ns	
$\overline{CAS}$ to $\overline{WE}$ Delay Time	t <sub>CWD</sub>	30	—	34	—	44	—	ns	10
Column Address to $\overline{WE}$ Delay Time	t <sub>AWD</sub>	42	—	49	—	59	—	ns	10
$\overline{RAS}$ to $\overline{WE}$ Delay Time	t <sub>RWD</sub>	67	—	79	—	94	—	ns	10
$\overline{CAS}$ Precharge $\overline{WE}$ Delay Time	t <sub>CPWD</sub>	47	—	54	—	64	—	ns	10
$\overline{CAS}$ Active Delay Time from $\overline{RAS}$ Precharge	t <sub>RPC</sub>	5	—	5	—	5	—	ns	12
$\overline{RAS}$ to $\overline{CAS}$ Set-up Time ( $\overline{CAS}$ before $\overline{RAS}$ )	t <sub>CSR</sub>	5	—	5	—	5	—	ns	12
$\overline{RAS}$ to $\overline{CAS}$ Hold Time ( $\overline{CAS}$ before $\overline{RAS}$ )	t <sub>CHR</sub>	10	—	10	—	10	—	ns	13



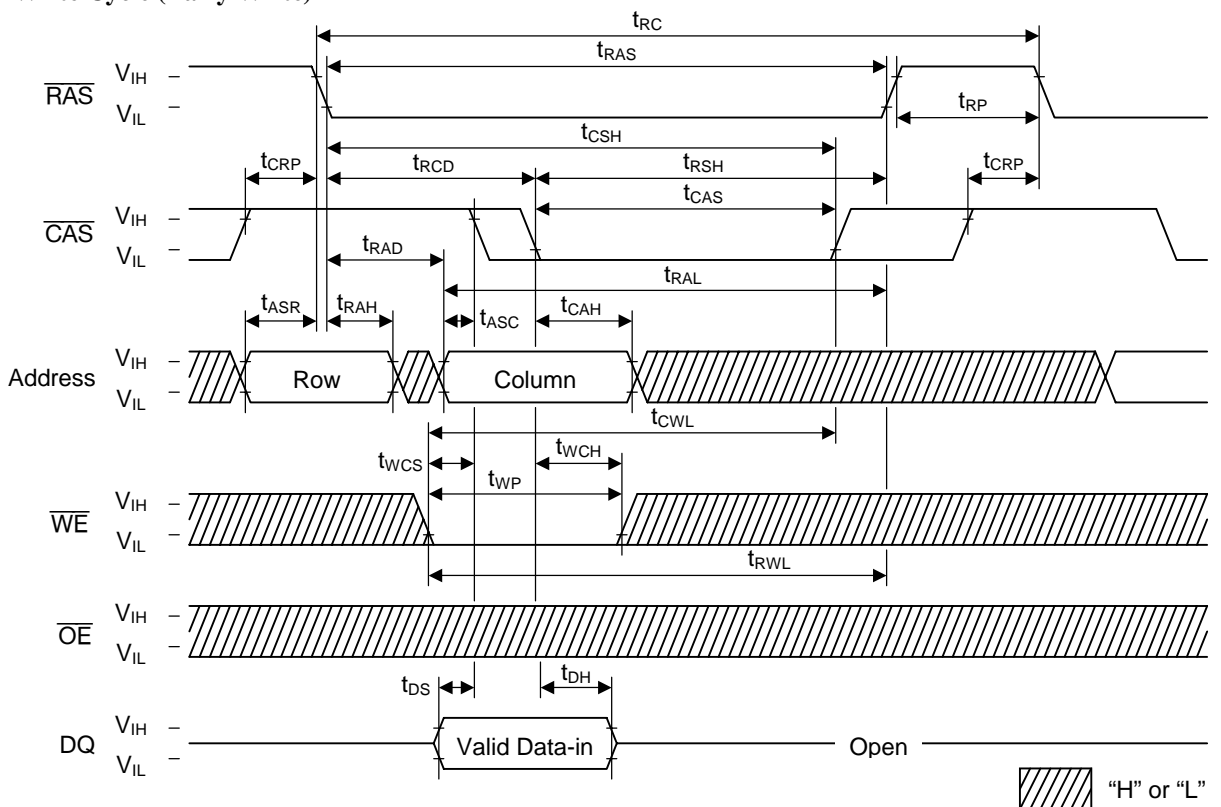
- Notes:
1. A start-up delay of 200 $\mu$ s is required after power-up, followed by a minimum of eight initialization cycles ( $\overline{\text{RAS}}$ -only refresh or  $\overline{\text{CAS}}$  before  $\overline{\text{RAS}}$  refresh) before proper device operation is achieved.
  2. The AC characteristics assume  $t_T = 2\text{ns}$ .
  3.  $V_{IH}$  (Min.) and  $V_{IL}$  (Max.) are reference levels for measuring input timing signals. Transition times ( $t_T$ ) are measured between  $V_{IH}$  and  $V_{IL}$ .
  4. -50 is measured with a load circuit equivalent to 1 TTL load and 50pF, and -60/-70 is measured with a load circuit equivalent to 1 TTL load and 100pF.  
The output timing reference levels are  $V_{OH}=2.0$  and  $V_{OL}=0.8\text{V}$ .
  5. Operation within the  $t_{RCD}$  (Max.) limit ensures that  $t_{RAC}$  (Max.) can be met.  
 $t_{RCD}$  (Max.) is specified as a reference point only. If  $t_{RCD}$  is greater than the specified  $t_{RCD}$  (Max.) limit, then the access time is controlled by  $t_{CAC}$ .
  6. Operation within the  $t_{RAD}$  (Max.) limit ensures that  $t_{RAC}$  (Max.) can be met.  
 $t_{RAD}$  (Max.) is specified as a reference point only. If  $t_{RAD}$  is greater than the specified  $t_{RAD}$  (Max.) limit, then the access time is controlled by  $t_{AA}$ .
  7.  $t_{CEZ}$  (Max.),  $t_{REZ}$  (Max.),  $t_{WEZ}$  (Max.), and  $t_{OEZ}$  (Max.) define the time at which the output achieved the open circuit condition and are not referenced to output voltage levels.
  8.  $t_{CEZ}$ , and  $t_{REZ}$  must be satisfied for open circuit condition.
  9.  $t_{RCH}$  or  $t_{RRH}$  must be satisfied for a read cycle.
  10.  $t_{WCS}$ ,  $t_{CWD}$ ,  $t_{RWD}$ ,  $t_{AWD}$  and  $t_{CPWD}$  are not restrictive operating parameters. They are included in the data sheet as electrical characteristics only. If  $t_{WCS} \geq t_{WCS}$  (Min.), then the cycle is an early write cycle and the data out will remain open circuit (high impedance) throughout the entire cycle. If  $t_{CWD} \geq t_{CWD}$  (Min.),  $t_{RWD} \geq t_{RWD}$  (Min.),  $t_{AWD} \geq t_{AWD}$  (Min.) and  $t_{CPWD} \geq t_{CPWD}$  (Min.), then the cycle is a read modify write cycle and data out will contain data read from the selected cell; if neither of the above sets of conditions is satisfied, then the condition of the data out (at access time) is indeterminate.
  11. These parameters are referenced to the  $\overline{\text{UCAS}}$  and  $\overline{\text{LCAS}}$ , leading edges in an early write cycle, and to the  $\overline{\text{WE}}$  leading edge in an  $\overline{\text{OE}}$  control write cycle, or a read modify write cycle.
  12. These parameters are determined by the falling edge of either  $\overline{\text{UCAS}}$  or  $\overline{\text{LCAS}}$ , whichever is earlier.
  13. These parameters are determined by the rising edge of either  $\overline{\text{UCAS}}$  or  $\overline{\text{LCAS}}$ , whichever is later.
  14.  $t_{CWL}$  should be satisfied by both  $\overline{\text{UCAS}}$  and  $\overline{\text{LCAS}}$ .
  15.  $t_{CP}$  is determined by the time both  $\overline{\text{UCAS}}$  and  $\overline{\text{LCAS}}$  are high.

**TIMING CHART**

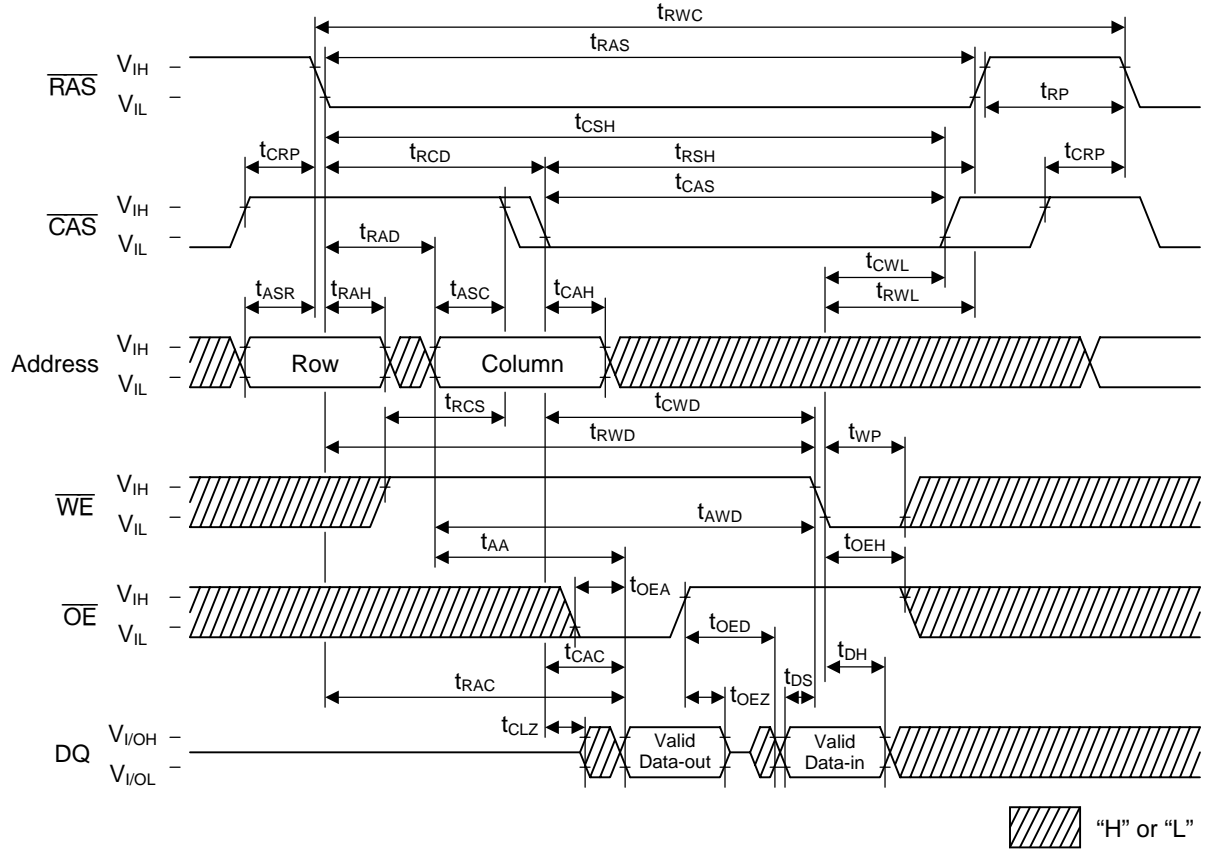
**Read Cycle**



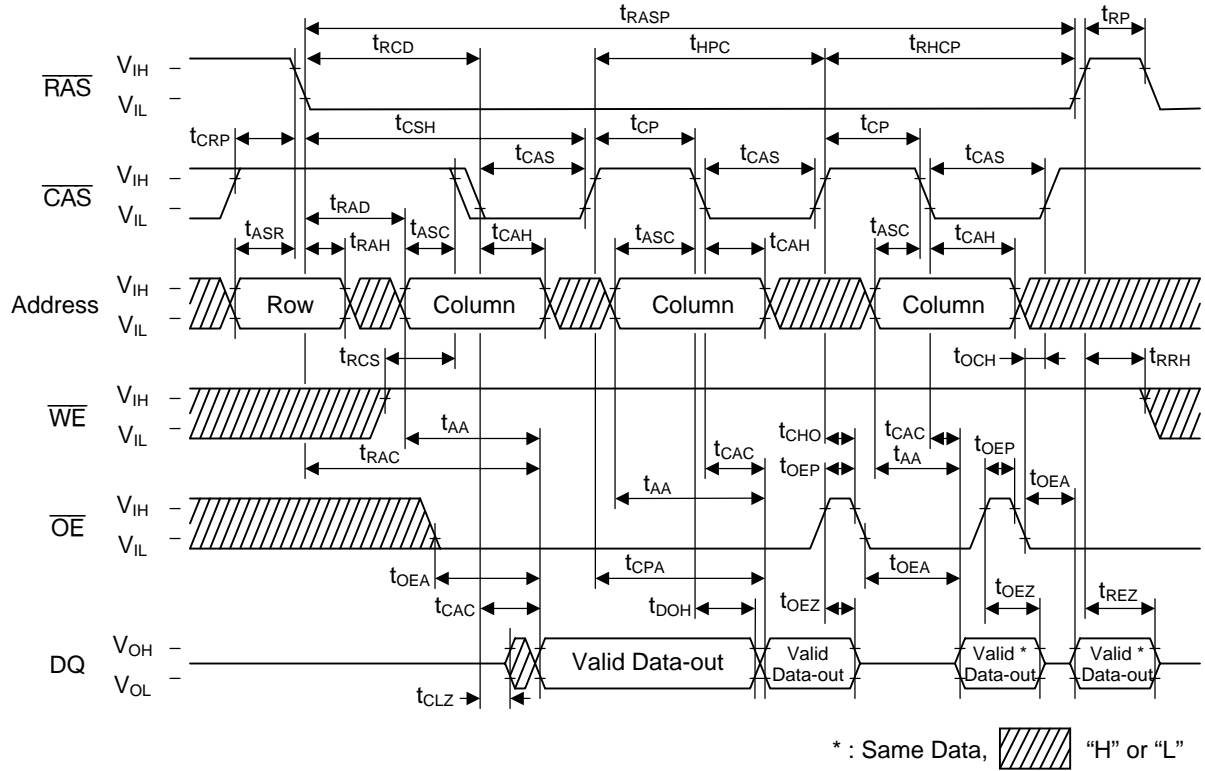
**Write Cycle (Early Write)**



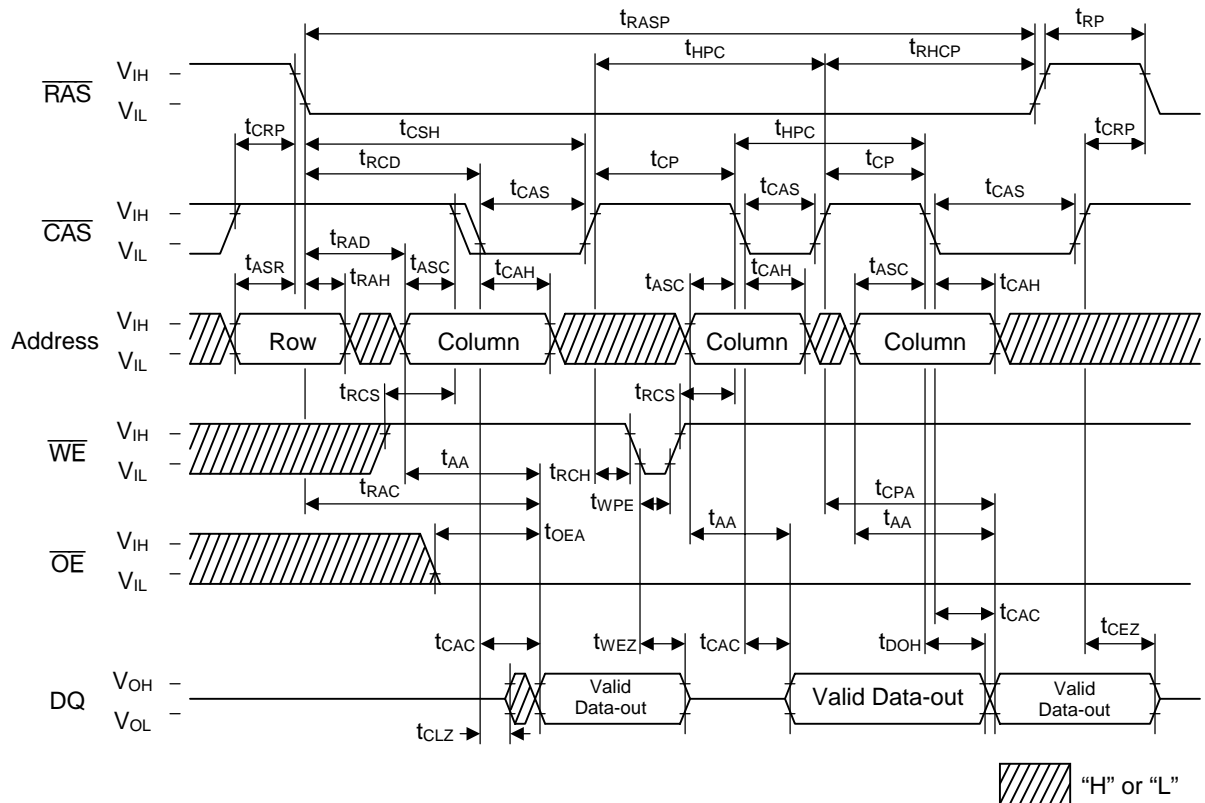
**Read Modify Write Cycle**



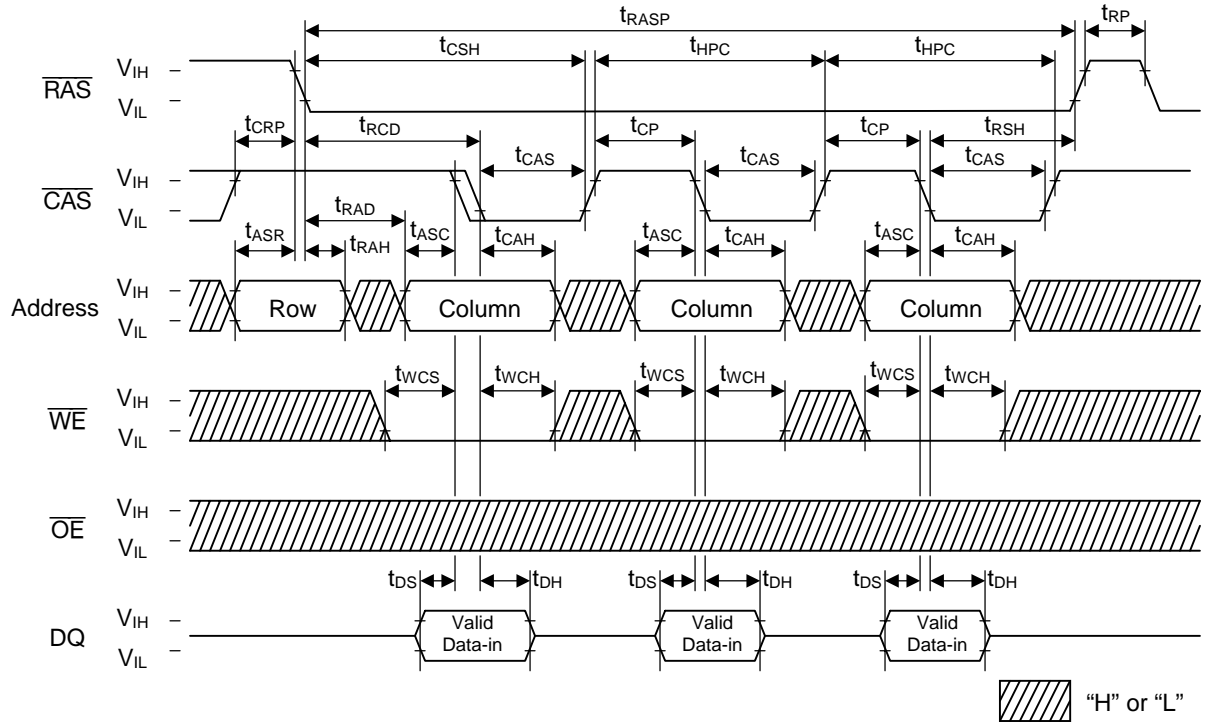
Fast Page Mode Read Cycle (Part-1)



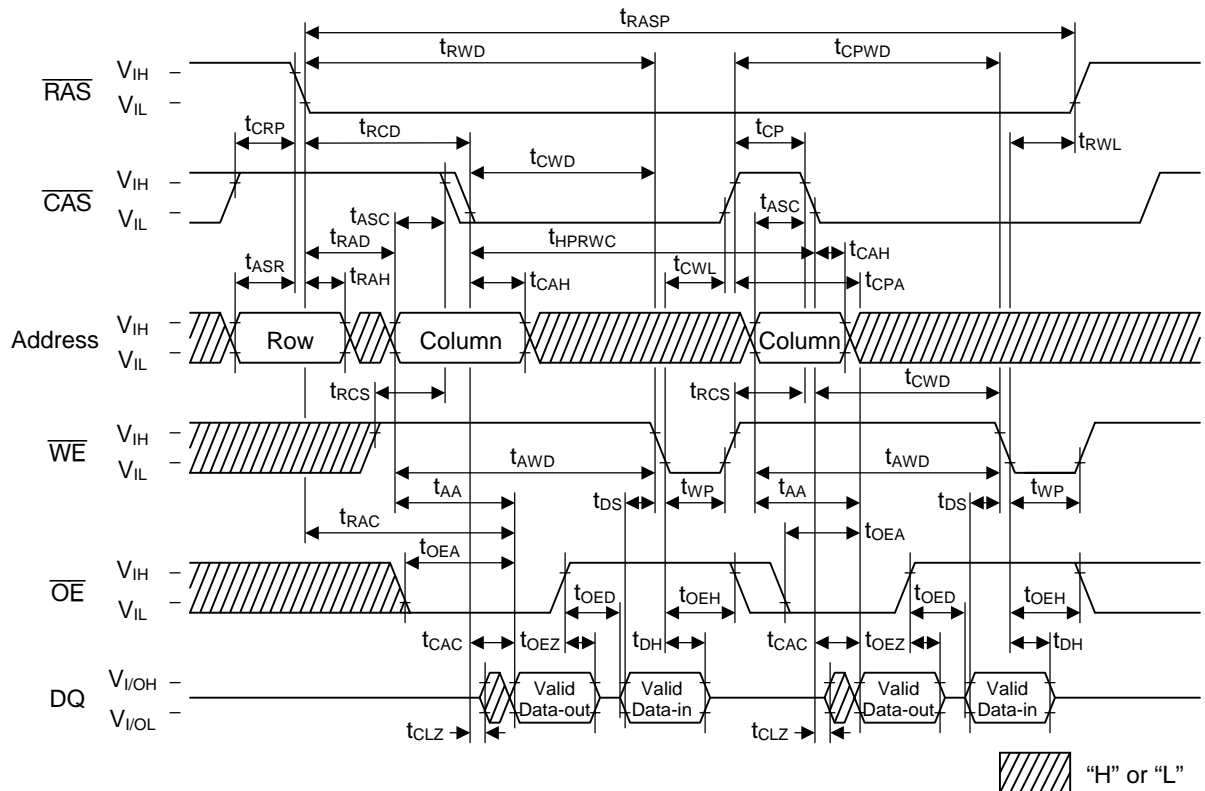
Fast Page Mode Read Cycle (Part-2)



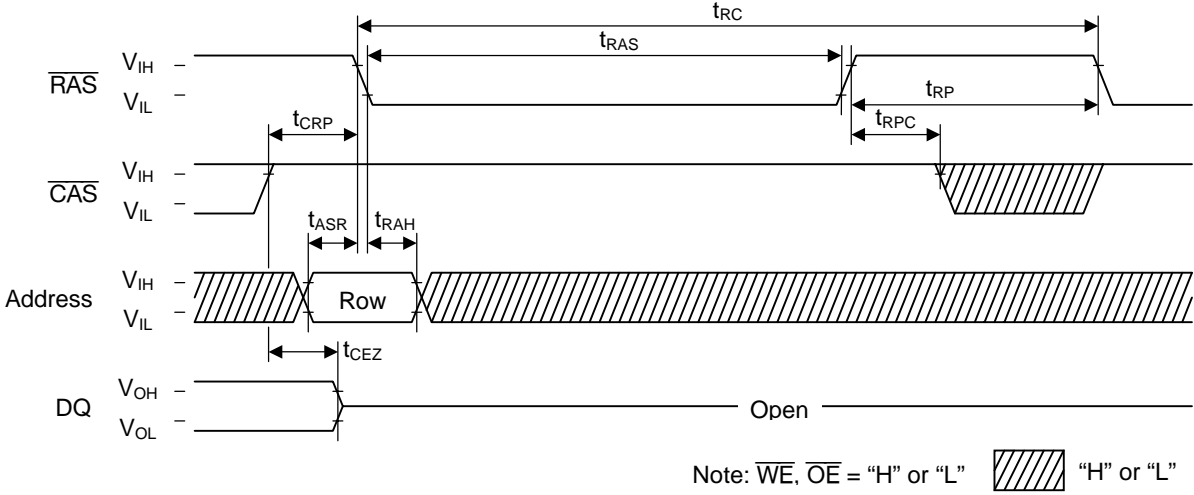
**Fast Page Mode Write Cycle (Early Write)**



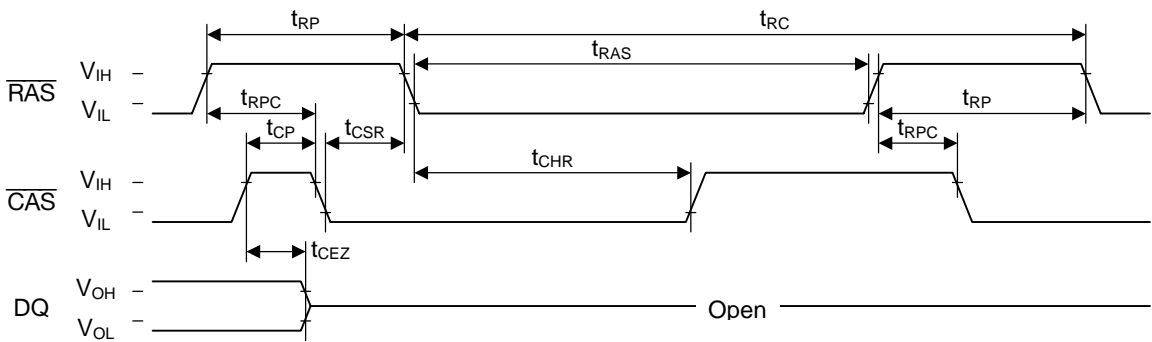
**Fast Page Mode Read Modify Write Cycle**



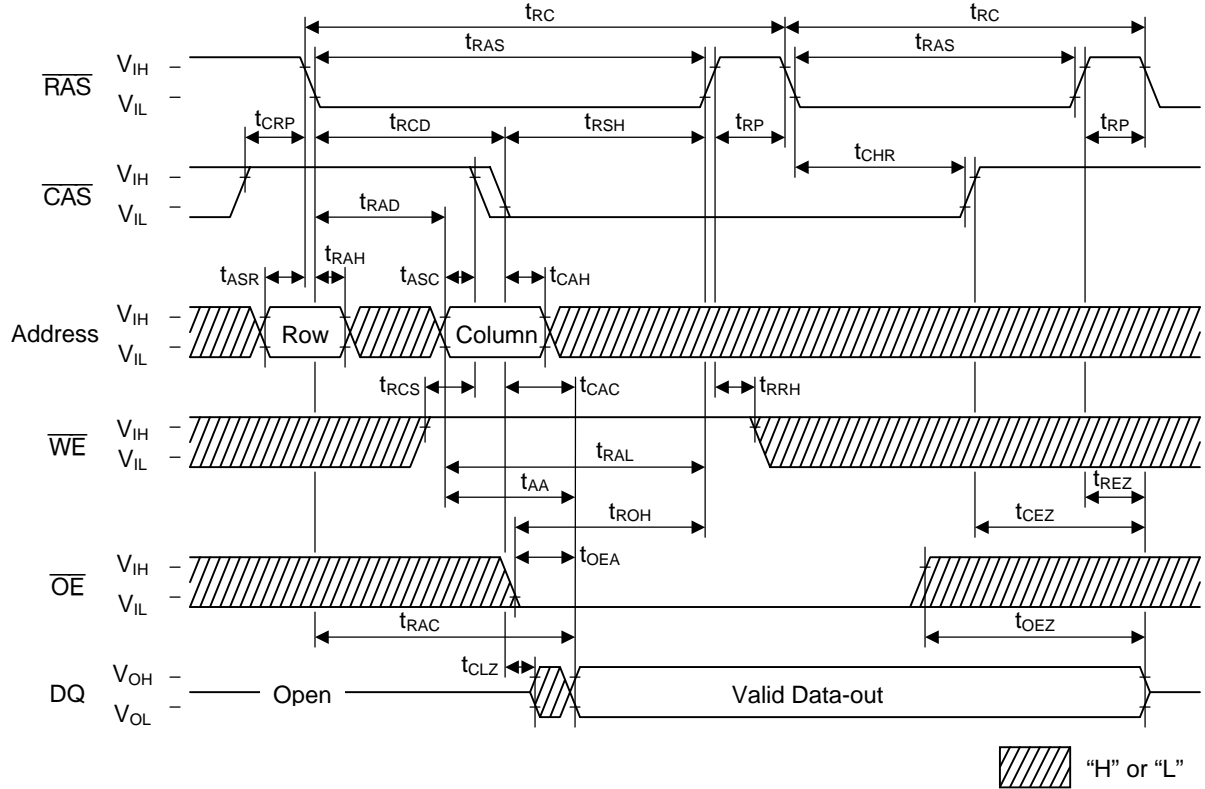
**RAS-only Refresh Cycle**



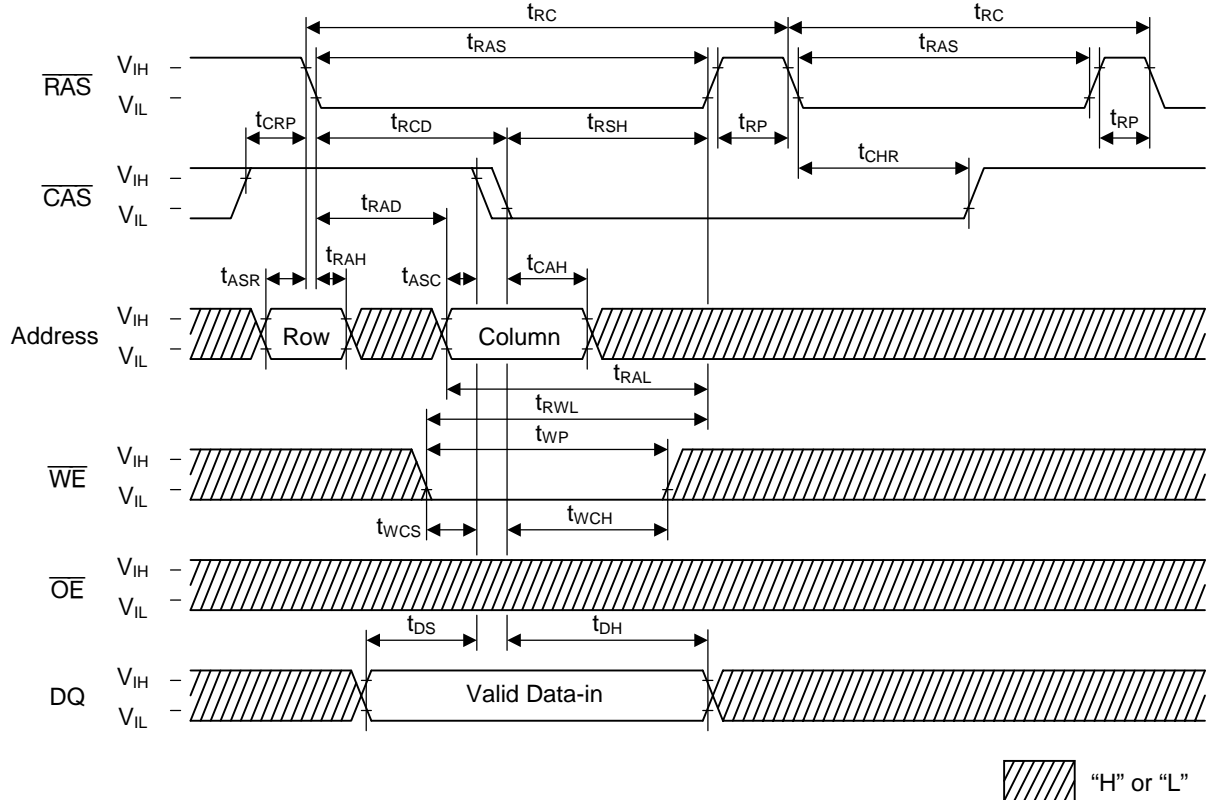
**CAS before RAS Refresh Cycle**



**Hidden Refresh Read Cycle**



**Hidden Refresh Write Cycle**



**REVISION HISTORY**

Document No.	Date	Page		Description
		Previous Edition	Current Edition	
FEDD51V16165F-01	Nov., 2000	–	–	Final edition 1
FEDD51V16165F-02	May., 2001	5	5	Changed Operating current specifications
FEDD51V16165F-03	Aug., 2002	1, 2	1, 2	Deleted SOJ package



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1. The information contained herein can change without notice owing to product and/or technical improvements. Before using the product, please make sure that the information being referred to is up-to-date.
2. The outline of action and examples for application circuits described herein have been chosen as an explanation for the standard action and performance of the product. When planning to use the product, please ensure that the external conditions are reflected in the actual circuit, assembly, and program designs.
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