T-51-09-08 **MP7524A**

CMOS
Buffered Multiplying 8-Bit
Digital-to-Analog Converter

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FEATURES

- I_{OUT} Pin Voltages are User Definable
- **Improved Isolation of Analog from Digital Ground**
- **Full Four-Quadrant Multiplication**
- **On-chip Bus Interface Logic**
- **+5 V to +15 V V_{DD} Operation**
- **Low Power Consumption**
- **Monotonicity Guaranteed
  (Full Temperature Range)**
- **PDIP & SOIC Packages Available**
- **Use in Unipolar Supplies**

APPLICATIONS

- **Microprocessor Controlled Gain Circuits**
- **Microprocessor Controlled Attenuator Circuits**
- **Microprocessor Controlled Function Generation**
- **Precision AGC Circuits**
- **Bus Structured Instruments**
- **Disk Drives**

GENERAL DESCRIPTION

The MP7524A is a low cost, 8-bit CMOS D/A Converter designed for direct interface to most microprocessors.

The MP7524A is pin-to-pin compatible to the MP7524. In addition, the $I_{OUT1,2}$ pins may be taken to a non-ground voltage. This allows its use in single supply circuits. The I_{OUT2} current is 1 LSB higher than that of the MP7524.

Basically an 8-bit DAC with input latches, the MP7524A's load cycle is similar to the "write" cycle of a random access memory. Using an advanced thin-film on CMOS fabrication process, the

MP7524A provides accuracy to 1/8 LSB with power dissipation of only 10mW.

Featuring operation from +5 V to +15 V, the MP7524A interfaces directly to most microprocessor buses or output ports. Excellent multiplying characteristics (2- or 4-quadrant) make the MP7524A an ideal choice for many microprocessor controlled gain setting and signal control applications.

Specified for operation over the commercial / industrial (−40 to +85°C) temperature range, the MP7524A is available in Plastic dual-in-line (PDIP) and Small Outline (SOIC) packages.

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SIMPLIFIED BLOCK DIAGRAM
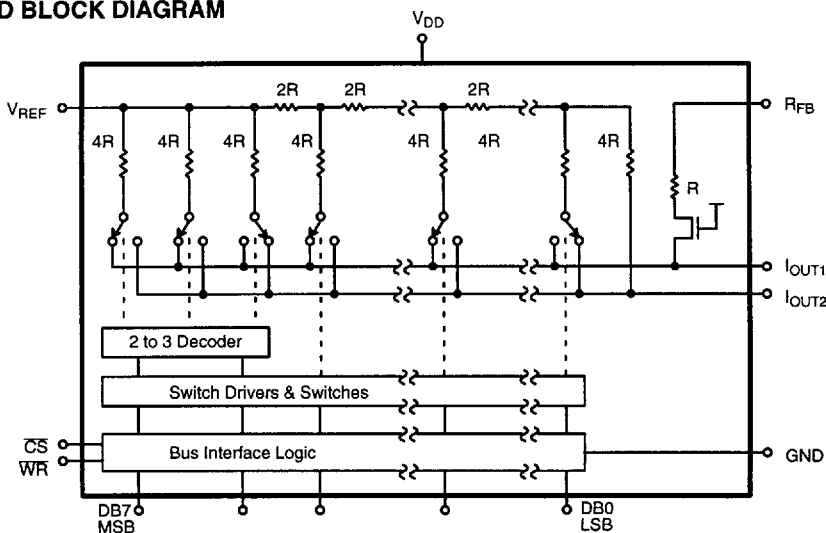
**3 Segment D/A Converter with Termination to GND
Logical "1" at Digital Input Steers Current to IOUT1**

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ORDERING INFORMATION

Package Type	Temperature Range	Part No.	INL (LSB)	DNL (LSB)	Gain Error (% FSR)
Plastic Dip	−40 to +85°C	MP7524AAN	±1/2	±1	±0.6
Plastic Dip	−40 to +85°C	MP7524ABN	±1/4	±1	±0.6
Plastic Dip	−40 to +85°C	MP7524ACN	±1/8	±1	±0.6
SOIC	−40 to +85°C	MP7524AAR	±1/2	±1	±0.6
SOIC	−40 to +85°C	MP7524ABR	±1/4	±1	±0.6
SOIC	−40 to +85°C	MP7524ACR	±1/8	±1	±0.6

PIN CONFIGURATIONS
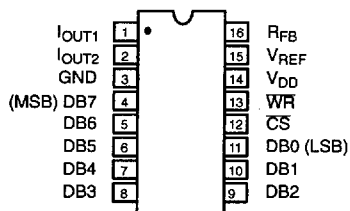
16 Pin PDIP (0.300")
N16
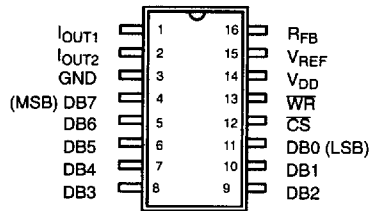
16 Pin SOIC (Jedec, 0.150")
SN16

PIN OUT DEFINITIONS

PIN NO.	NAME	DESCRIPTION
1	I_{OUT1}	Current Output 1
2	I_{OUT2}	Current Output 2
3	GND	Ground
4	DB7	Data Bit 7 (MSB)
5	DB6	Data Bit 6
6	DB5	Data Bit 5
7	DB4	Data Bit 4
8	DB3	Data Bit 3

PIN NO.	NAME	DESCRIPTION
9	DB2	Data Bit 2
10	DB1	Data Bit 1
11	DB0	Data Bit 0 (LSB)
12	$\overline{CS}$	Chip Select
13	$\overline{WR}$	Write
14	V_{DD}	Power Supply
15	V_{REF}	Reference Input
16	R_{FB}	Feedback Resistance

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ELECTRICAL CHARACTERISTICS
(V$_{DD}$ = + 5 V, V$_{REF}$ = +10 V unless otherwise noted)

Parameter	Symbol	25°C Min	25°C Typ	25°C Max	Tmin to Tmax Min	Tmin to Tmax Max	Units	Test Conditions/Comments
STATIC PERFORMANCE (1)								FSR = Full Scale Range
Resolution (All Grades)	N	8			8		Bits	
Integral Non-Linearity (Relative Accuracy)	INL						LSB	End Point Linearity
A				±1/2		±1/2		
B				±1/2		±1/2		
C				±1/2		±1/2		
Differential Non-Linearity	DNL						LSB	All grades monotonic over full
A				±1		±1		temperature range.
B				±1		±1		
C				±1		±1		
Gain Error	GE			±1.0		±1.4	% FSR	Using Internal R$_{FB}$ Digital Inputs = V$_{INH}$
Power Supply Rejection Ratio	PSRR			±800		±1600	ppm/%	|ΔGain/ΔV$_{DD}$| ΔV$_{DD}$ = ± 10% Digital Inputs = V$_{INH}$
Output Leakage Current (Pin 1)	I$_{OUT1}$			±50nA		±400nA	nA	Digital Inputs = V$_{INL}$
DYNAMIC PERFORMANCE								RL = 100Ω, C$_L$ = 10pF
Current Settling Time (2)	t$_S$			100		150	ns	Full Scale Change to 1/2 LSB
AC Feedthrough at I$_{OUT1}$ (2)	F$_T$			±1/2		±1	LSB	V$_{REF}$=100kHz, 20 Vp-p, sinewave
at I$_{OUT2}$				±1/2		±1	LSB	DB0-DB7 = 0 V, $\overline{CS}$ = $\overline{WR}$ = 0 V
REFERENCE INPUT								
Input Resistance	R$_{IN}$	5		20	5	20	kΩ	
DIGITAL INPUTS (3)								
Logical "1" Voltage	V$_{IH}$	+2.4			+2.4		V	
Logical "0" Voltage	V$_{IL}$			+0.8		+0.8	V	
Input Leakage Current	I$_{LKG}$			±1		±10	μA	
Input Capacitance (2)	C$_{IN}$			20		20	pF	V$_{IN}$ = 0 V
ANALOG OUTPUTS (2)								
Output Capacitance								
	C$_{OUT1}$			70		70	pF	DAC Inputs all 1's
	C$_{OUT1}$			30		30	pF	DAC Inputs all 0's
	C$_{OUT2}$			20		20	pF	DAC Inputs all 1's
	C$_{OUT2}$			60		60	pF	DAC Inputs all 0's
POWER SUPPLY (5)								
Supply Current	I$_{DD}$	1		2		2	mA	All digital inputs = 0 V or all = 5 V
		1		2		2	mA	All digital inputs = V$_{IL}$ or all = V$_{IH}$

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ELECTRICAL CHARACTERISTICS (CONT'D)

Parameter	Symbol	25°C Min	Typ	Max	Tmin to Tmax Min	Max	Units	Test Conditions/Comments
SWITCHING CHARACTERISTICS (2, 4)								
Chip Select to Write Set-Up Time	t_{CS}						ns	
A, B, C		170			220			
Chip Select to Write Hold Time	t_{CH}	0			0		ns	
Data Valid to Write Set-Up Time	t_{DS}	135			170		ns	
Data Valid to Write Hold Time	t_{DH}	10			10		ns	
Write Pulse Width	t_{WR}						ns	
A, B, C		170			220			
VOLTAGE MODE OPERATION (2, 6)								
Integral Nonlinearity Error @ V_{REF}	INL			1			LSB	$I_{OUT1} = 2.5$ V $I_{OUT2} = 0$ V

NOTES:

(1) Full Scale Range (FSR) is 10V for unipolar mode and ±10V for bipolar.
(2) Guaranteed but not production tested .
(3) Digital input levels should not go below ground or exceed the positive supply voltage, otherwise damage may occur.
(4) See timing diagram.
(5) Specified values guarantee functionality. Refer to other parameters for accuracy.
(6) Refer to *Figure 7*.

Specifications are subject to change without notice

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ELECTRICAL CHARACTERISTICS
(VDD = + 15 V, VREF = +10 V unless otherwise noted)

Parameter	Symbol	25°C Min	25°C Typ	25°C Max	Tmin to Tmax Min	Tmin to Tmax Max	Units	Test Conditions/Comments
STATIC PERFORMANCE (1)								FSR = Full Scale Range
Resolution (All Grades)	N	8			8		Bits	
Integral Non-Linearity (Relative Accuracy)	INL						LSB	.End Point Linearity
J, A, S				±1/2		±1/2		
K, B, T				±1/4		±1/4		
L, C, U				±1/8		±1/8		
Differential Non-Linearity	DNL						LSB	All grades monotonic over full temperature range.
J, A, S				±1		±1		
K, B, T				±1		±1		
L, C, U				±1		±1		
Gain Error	GE			±0.5		±0.6	% FSR	Using Internal RFB, Digital Inputs = VINH
Power Supply Rejection Ratio	PSRR			±200		±400	ppm/%	|ΔGain/ΔVDD| ΔVDD = ± 10% Digital Inputs = VINH
Output Leakage Current (Pin 1)	IOUT1			±50nA		±400nA	nA	Digital Inputs = VINL
DYNAMIC PERFORMANCE								RL=100Ω, CL=13pF
Current Settling Time (2)	ts			50		100	ns	Full Scale Change to 1/2 LSB
AC Feedthrough at IOUT1 (2)	FT			±0.50		±1.00	LSB	VREF = 10kHz, 20 Vp-p, sinewave
at IOUT2				±0.50		±1.00	LSB	DB0 - DB7 = 0 V, C̄S̄ = W̄R̄ = 0 V
REFERENCE INPUT								
Input Resistance	RIN	5		20	5	20	kΩ	
DIGITAL INPUTS (3)								
Logical "1" Voltage	VIH	+13.5			+13.5		V	
Logical "0" Voltage	VIL			+1.5		+1.5	V	
Input Leakage Current	ILKG			±1		±10	μA	
Input Capacitance (2)	CIN			20		20	pF	
ANALOG OUTPUTS (2)								
Output Capacitance								
	COUT1			70		70	pF	DAC Inputs all 1's
	COUT1			30		30	pF	DAC Inputs all 0's
	COUT2			20		20	pF	DAC Inputs all 1's
	COUT2			60		60	pF	DAC Inputs all 0's
POWER SUPPLY								
Supply Current	IDD		1	2		2	mA	All digital inputs = 0 V or all = 15 V
			1	2		2	mA	All digital inputs = VIL or all = VIH

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ELECTRICAL CHARACTERISTICS (CONT'D)

Parameter	Symbol	25°C Min	25°C Typ	25°C Max	Tmin to Tmax Min	Tmin to Tmax Max	Units	Test Conditions/Comments
SWITCHING CHARACTERISTICS (2, 4)								
Chip Select to Write Set-Up Time	t_{CS}						ns	
A, B, C		100			130			
Chip Select to Write Hold Time	t_{CH}	0			0		ns	
Data Valid to Write Set-Up Time	t_{DS}						ns	
A, B, C		60			80			
Data Valid to Write Hold Time	t_{DH}	10			10		ns	
Write Pulse Width	t_{WR}						ns	
A, B, C		100			130			
VOLTAGE MODE OPERATION (2, 6)								
Integral Nonlinearity Error @ V_{REF}	INL			1			LSB	$I_{OUT1} = 5$ V $I_{OUT2} = 0$ V

NOTES:
(1) Full Scale Range (FSR) is 10V for unipolar mode and ±10V for bipolar.
(2) Guaranteed but not production tested.
(3) Digital input levels should not go below ground or exceed the positive supply voltage, otherwise damage may occur.
(4) See timing diagram.
(5) Specified values guarantee functionality. Refer to other parameters for accuracy.
(6) Refer to *Figure 7*.

Specifications are subject to change without notice

ABSOLUTE MAXIMUM RATINGS (1, 2) (TA = +25°C unless otherwise noted)

V_{DD} to GND .... −0.5, +17 V
Digital Input Voltage to GND (2) . GND −0.5 to V_{DD} +0.5 V
I_{OUT1}, I_{OUT2} to GND .... −0.5 to 7 V
V_{REF} to GND .... ±25 V
V_{RFB} to GND .... ±25 V

Storage Temperature .... −65°C to +150°C
Lead Temperature (Soldering, 10 seconds) ...... +300°C
Package Power Dissipation Rating to 75°C
    PDIP, SOIC 700mW
    Derates above 75°C .... 10mW/°C

NOTES:
(1) Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation at or above this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.
(2) Any input pin which can see a value outside the absolute maximum ratings should be protected by Schottky diode clamps (HP5082-2835) from input pin to the supplies.

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APPLICATION NOTES
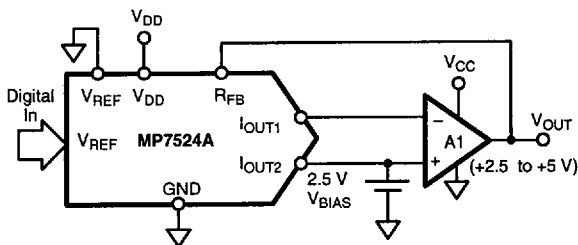### *Refer to Section 8 for Applications Information*

**Figure 1. Single Supply Operation
with 2.5 V to 5 V Swing**

The R-2R ladder termination resistor on the MP7524A is internally connected to I_{OUT2} instead of ground as in the MP7524. This configuration allows the use of the DAC in the single supply current steering mode, where I_{OUT2} is biased above ground level.
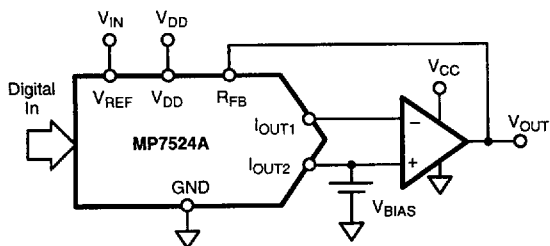
Figure 2. shows the generalized configuration.

**Figure 2. Single Supply Operation
in Current Switching Mode**

The advantage of this single supply configuration over the voltage switching mode is the greater flexibility with which the output voltage swing can be defined. A low impedance reference bias voltage is needed. Unlike the voltage switching mode which has a minimum output voltage of 0V, the current steering mode allows for output swings that do not have to approach the rail voltages. The describing equation for this configuration is:

$$V_{OUT} = \frac{D}{256} (V_{BIAS} - V_{IN}) + V_{BIAS}$$

where D=decimal equivalent of the DAC digital input code
V_{BIAS} is a voltage reference: $0\ V \leq V_{BIAS} \leq 2.5V$ for best linearity.
V_{IN} is a bipolar input voltage

By choosing the proper V_{BIAS} and V_{IN}, the output voltage can be set in the range between V_{BIAS} and $2V_{BIAS} - V_{IN}$. For example, for $V_{DD} = 5\ V$ & $V_{CC} = 15\ V$, select $V_{IN} = 0\ V$ and $V_{BIAS} = 2.5$ V. This will result in a swing of 2.5 V to 5 V.
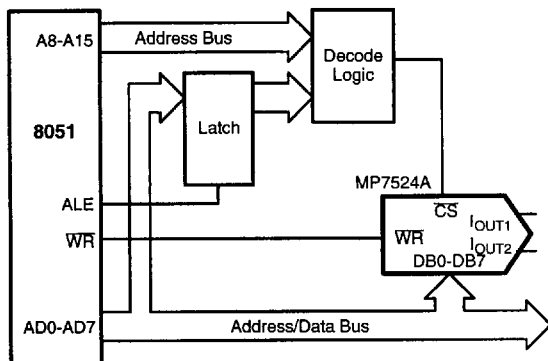
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Figure 3. Microcontroller Interface

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INTERFACE LOGIC INFORMATION

Mode Selection

MP7524A mode selection is controlled by the $\overline{CS}$ and $\overline{WR}$ inputs.

Write Mode

When $\overline{CS}$ and $\overline{WR}$ are both LOW, the MP7524A is in the WRITE mode, and the MP7524A analog circuit responds to data activity at the DB0-DB7 data bus inputs. In this mode, the MP7524A acts like a non-latched input D/A converter.

Hold Mode

When either $\overline{CS}$ or $\overline{WR}$ is HIGH, the MP7524A is in the HOLD mode. The MP7524A analog output holds the value corresponding to the last digital input present at DB0-DB7 prior to $\overline{WR}$ or $\overline{CS}$ assuming the high state.

$\overline{CS}$	$\overline{WR}$	Mode	DAC Response
L	L	Write	DAC responds to data bus (DB0-DB7) inputs
H	X	Hold	Data Bus (DB0-DB7) is locked out
X	H	Hold	DAC holds last data present when $\overline{WR}$ assumed HIGH state

L = LOW state, H = HIGH state, X = Don't care state
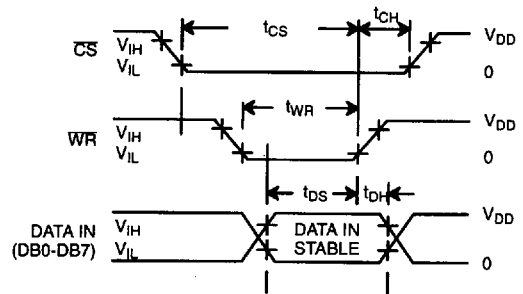
Table 1. Mode Selection Table

Figure 4. Write Cycle Timing Diagram

MICROPROCESSOR INTERFACE

MP7524A/8080A Interface

Figure 3. shows the MP7524A used in the MCS-80 microcomputer system as a Memory Mapped Output Device. The basic CPU group consists of the 8080A CPU, 8224 clock generator and 8228 system controller/bus driver. The MP7524A $\overline{WR}$ input is connected to the 8228 system data bus outputs. The $\overline{CS}$ input is connected to the system address decoding logic. Note that pull-up resistors R3 and R4 are required to ensure that the $\overline{CS}$ and $\overline{WR}$ input HIGH states reach 3.0V min. Pull-ups are not required on the system data bus since the 8228 VOH is 3.6 V min for DB0-DB7.

System timing is shown in *Figure 4*. Data is loaded into the MP7524A when the $\overline{WR}$ and $\overline{CS}$ inputs are both LOW. The data is latched into the MP7524A when $\overline{WR}$ returns HIGH. MP7524A updating is accomplished by using any of the 8080A memory write instructions.

The MP7524A can also be addressed and loaded as an isolated Output Device by connecting the MP7524A $\overline{WR}$ input to the 8228 $\overline{I/O}$ W terminal (instead of $\overline{MEMW}$).
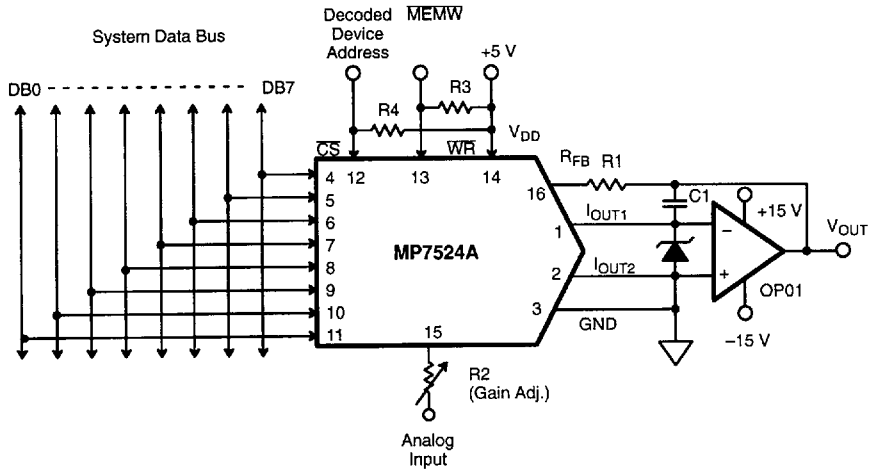
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Figure 5.   MP7524A/8080A Interface
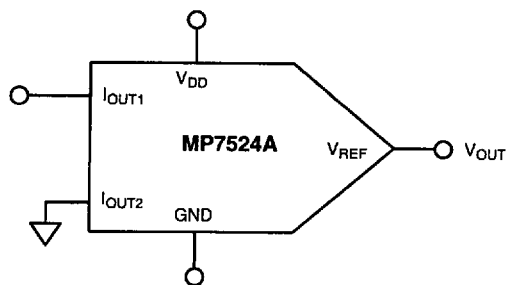
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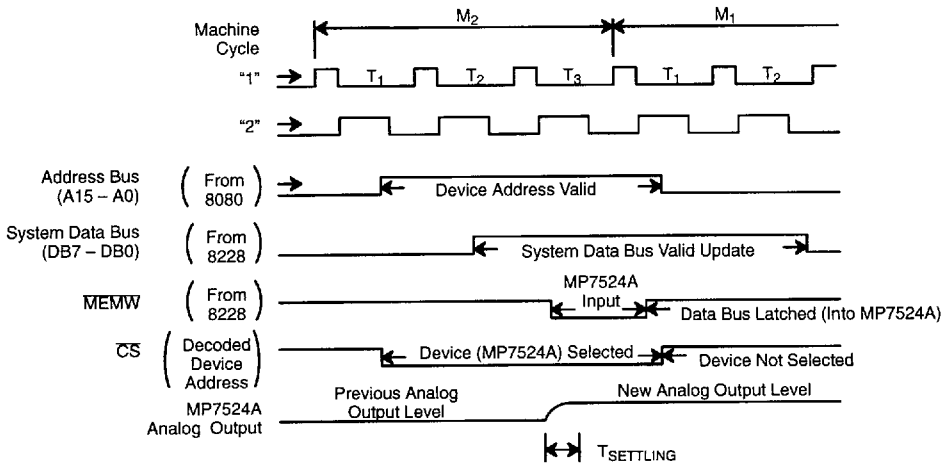
Figure 6.   Timing Diagram

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Figure 7.   Voltage Mode Operation