

T-51.09-12



# DAC7541A

AVAILABLE IN  
DIE FORM

## Low Cost 12-Bit CMOS Four-Quadrant Multiplying DIGITAL-TO-ANALOG CONVERTER

### FEATURES

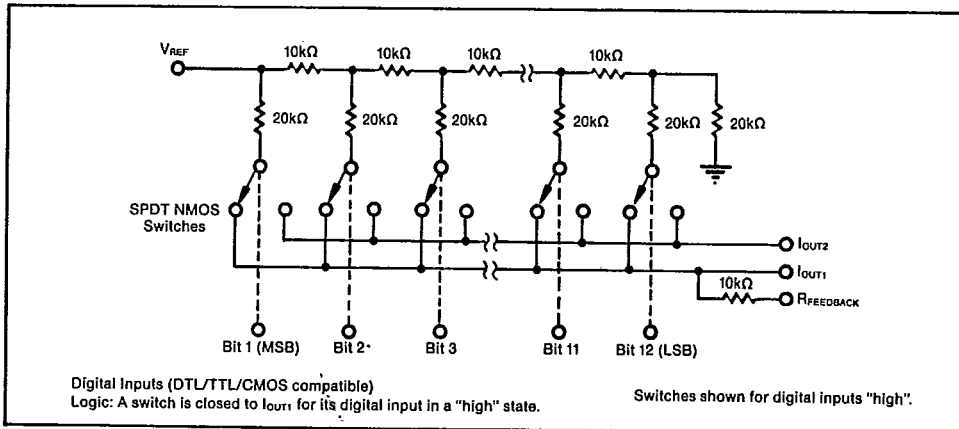
- FULL FOUR-QUADRANT MULTIPLICATION
- 12-BIT END-POINT LINEARITY
- DIFFERENTIAL LINEARITY  $\pm 1/2\text{LSB}$  MAX OVER TEMPERATURE (K/B/T GRADES)
- MONOTONICITY GUARANTEED OVER TEMPERATURE
- TTL-/CMOS-COMPATIBLE
- SINGLE +5V TO +15V SUPPLY
- LATCH-UP RESISTANT
- 7521/7541/7541A REPLACEMENT
- PACKAGES: HERMETIC DIP, PLASTIC DIP, PLASTIC SOIC
- LOW COST

### DESCRIPTION

The Burr-Brown DAC7541A is a low cost 12-bit, four-quadrant multiplying digital-to-analog converter. Laser-trimmed thin-film resistors on a monolithic CMOS circuit provide true 12-bit integral and differential linearity over the full specified temperature ranges.

The DAC7541A is a direct, improved pin-for-pin replacement for 7521, 7541, and 7541A industry standard parts. In addition to standard 18-pin plastic and hermetic ceramic packages, the DAC7541A is also available in a surface-mount plastic 18-pin SOIC.

### FUNCTIONAL DIAGRAM



International Airport Industrial Park • P.O. Box 11400 • Tucson, Arizona 85734 • Tel.: (602) 746-1111 • Twx: 910-952-1111 • Cable: BBRCORP • Telex: 66-6491

PDS-639A

**SPECIFICATIONS**

**ELECTRICAL**

At +25°C, +V<sub>DD</sub> = +12V or +15V, V<sub>REF</sub> = +10V, V<sub>PIN 1</sub> = V<sub>PIN 2</sub> = 0V unless otherwise specified.

MODEL	DAC7541A			UNITS	TEST CONDITIONS/COMMENTS
	GRADE	T <sub>A</sub> = +25°C	T <sub>A</sub> = T <sub>MIN</sub> , T <sub>MAX</sub> <sup>(1)</sup>		
<b>ACCURACY</b>					
Resolution	All	12	12	Bits	±1LSB = ±0.024% of FSR.
Relative Accuracy	J, A, S K, B, T	±1 ±1/2	±1 ±1/2	LSB max	±1/2LSB = ±0.012% of FSR.
Differential Non-linearity	J, A, S K, B, T	±1 ±1/2	±1 ±1/2	LSB max	All grades guaranteed monotonic to 12 bits, T <sub>MIN</sub> to T <sub>MAX</sub> .
Gain Error	J, A, S K, B, T	±6 ±1	±8 ±3	LSB max	Measured using internal R <sub>FB</sub> and includes effect of leakage current and gain T.C. Gain error can be trimmed to zero.
Gain Temperature Coefficient (ΔGain/ΔTemperature)	All		5	ppm/°C max	Typical value is 2ppm/°C.
Output Leakage Current: Out <sub>1</sub> (Pin 1)	J, K A, B S, T	±5 ±5 ±5	±10 ±10 ±200	nA max	All digital inputs = 0V.
Output Leakage Current: Out <sub>2</sub> (Pin 2)	J, K A, B S, T	±5 ±5 ±5	±10 ±10 ±200	nA max	All digital inputs = V <sub>DD</sub> .
<b>REFERENCE INPUT</b>					
Voltage (Pin 17 to GND)	All	-10/+10	-10/+10	V min/max	Typical input resistance = 11kΩ.
Input Resistance (Pin 17 to GND)	All	7-18	7-18	kΩ min/max	Typical input resistance temperature coefficient is -50ppm/°C.
<b>DIGITAL INPUTS</b>					
V <sub>IH</sub> (Input High Voltage)	All	2.4	2.4	V min	Logic inputs are MOS gates. I <sub>IN</sub> typ (25°C) = 1nA. V <sub>IN</sub> = 0V
V <sub>IL</sub> (Input Low Voltage)	All	0.8	0.8	V max	
I <sub>IN</sub> (Input Current)	All	±1	±1	μA max	
C <sub>IN</sub> (Input Capacitance) <sup>(2)</sup>	All	8	8	pF max	
<b>POWER SUPPLY REJECTION</b>					
ΔGain/ΔV <sub>DD</sub>	All	±0.01	±0.02	% per % max	V <sub>DD</sub> = +11.4V to +16V
<b>POWER SUPPLY</b>					
V <sub>DD</sub> Range	All	+5 to +16	+5 to +16	V min to V max	Accuracy is not guaranteed over this range.
I <sub>DD</sub>	All	2 100	2 500	mA max μA max	All digital inputs V <sub>IL</sub> or V <sub>IH</sub> . All digital inputs 0V or V <sub>DD</sub> .

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**AC PERFORMANCE CHARACTERISTICS**

These characteristics are included for design guidance only and are not production tested. V<sub>DD</sub> = +15V, V<sub>REF</sub> = +10V except where stated, V<sub>PIN 1</sub> = V<sub>PIN 2</sub> = 0V, output amp is OPA606 except where stated.

<b>PROPAGATION DELAY</b> (from Digital Input change to 90% of Final Analog Output)	All	100	—	ns typ	Out <sub>1</sub> Load = 100Ω, C <sub>EXT</sub> = 13pF. Digital Inputs = 0V to V <sub>DD</sub> or V <sub>DD</sub> to 0V.
<b>DIGITAL-TO-ANALOG GLITCH IMPULSE</b>	All	1000	—	nV-s typ	V <sub>REF</sub> = 0V, all digital inputs 0V to V <sub>DD</sub> or V <sub>DD</sub> to 0V. Measured using OPA606 as output amplifier.
<b>MULTIPLYING FEEDTHROUGH ERROR</b> (V <sub>REF</sub> to Out <sub>1</sub> )	All	1.0	—	mVp-p max	V <sub>REF</sub> = ±10V, 10kHz sine wave.
<b>OUTPUT CURRENT SETTLING TIME</b>	All	0.6	—	μs typ	To 0.01% of Full Scale Range.
	All	1.0	—	μs max	Out <sub>1</sub> load = 100Ω, C <sub>EXT</sub> = 13pF. Digital inputs: 0V to V <sub>DD</sub> or V <sub>DD</sub> to 0V.
<b>OUTPUT CAPACITANCE</b>					
C <sub>OUT 1</sub> (Pin 1)	All	100	100	pF max	Digital Inputs = V <sub>IH</sub>
C <sub>OUT 2</sub> (Pin 2)	All	60	60	pF max	Digital Inputs = V <sub>IH</sub>
C <sub>OUT 1</sub> (Pin 1)	All	70	70	pF max	Digital Inputs = V <sub>IL</sub>
C <sub>OUT 2</sub> (Pin 2)	All	100	100	pF max	Digital Inputs = V <sub>IL</sub>

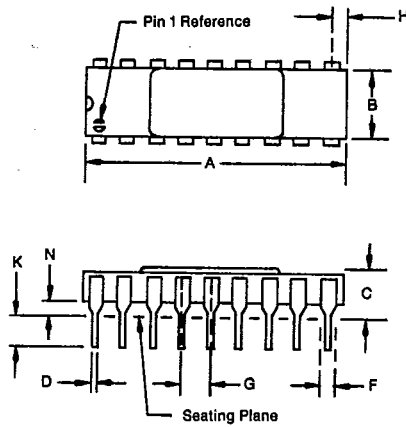
NOTES: (1) Temperature ranges are: 0 to +70°C for JP, KP, JU and KU versions; -25°C to +85°C for AH, BH versions; -55°C to +125°C for SH, TH versions. (2) Guaranteed by design but not production tested.

MECHANICAL

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H Package-18-Pin Hermetic DIP

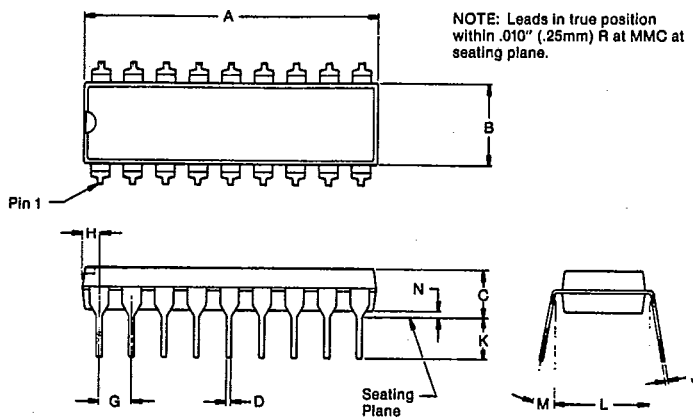
DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	—	.960	—	24.38
B	.220	.310	5.59	7.87
C	—	.200	—	5.08
D	.014	.023	0.36	0.58
F	.030	.070	0.76	1.78
G	.100 BASIC		2.54 BASIC	
H	—	.098	—	2.49
J	.008	.015	0.20	0.38
K	.125	.200	3.18	5.08
L	.290	.320	7.37	8.13
N	.015	.060	0.38	2.03



NOTE: Leads in true position within .010" (.25mm) R at MMC at seating plane.

P Package-18-Pin Plastic DIP

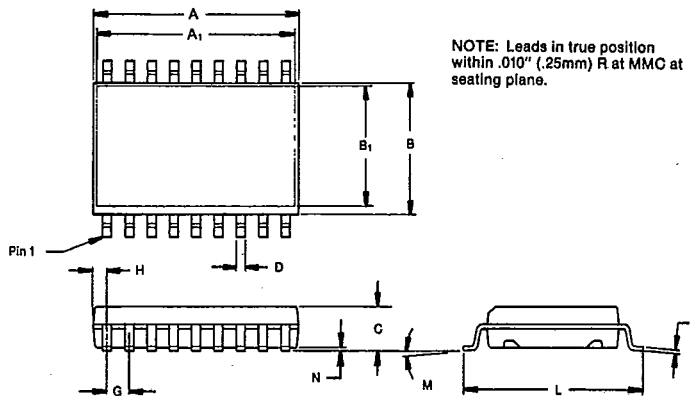
DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	.840	.940	21.34	23.88
B	.240	.280	6.10	7.11
C	—	.210	—	5.33
D	.014	.022	0.36	0.56
G	.100 BASIC		2.54 BASIC	
H	.040	.060	1.02	1.52
J	.008	.015	0.20	0.38
K	.115	.150	2.92	3.81
L	.290	.300	7.11	7.62
M	0°	10°	0°	10°
N	0.020	0.050	0.51	1.27



NOTE: Leads in true position within .010" (.25mm) R at MMC at seating plane.

U Package-18-Pin Plastic SOIC

DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	.450	.466	11.43	11.84
A <sub>1</sub>	.443	.446	11.25	11.33
B	.288	.302	7.26	7.67
B <sub>1</sub>	.270	.285	6.86	7.24
C	.093	.108	2.36	2.74
D	.015	.019	0.38	0.48
G	.050 BASIC		1.27 BASIC	
H	.026	.034	0.66	0.86
J	.008	.012	0.20	0.30
L	.390	.422	9.91	10.72
M	0°	10°	0°	10°
N	.000	.012	0.00	0.30



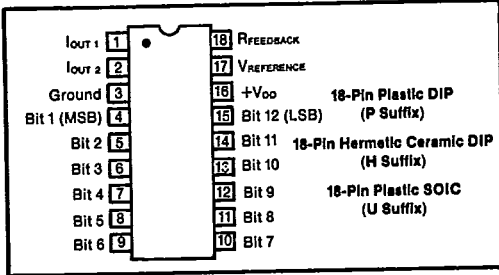
NOTE: Leads in true position within .010" (.25mm) R at MMC at seating plane.

**ABSOLUTE MAXIMUM RATINGS\***

V <sub>DD</sub> (pin 16) to Ground .....	+17V
V <sub>REF</sub> (pin 17) to Ground .....	±25V
V <sub>RFB</sub> (pin 18) to Ground .....	±25V
Digital Input Voltage (pins 4-15) to Ground ...	-0.4V, V <sub>DD</sub>
V <sub>PIN 1</sub> , V <sub>PIN 2</sub> to Ground .....	-0.4V, V <sub>DD</sub>
Power Dissipation (any package):	
To +75°C .....	450mW
Derates above +75°C .....	-6mW/°C
Lead Temperature (soldering, 10s) .....	+300°C
Storage Temperature: Ceramic Package .....	+150°C
Plastic Package .....	+125°C

\*Stresses above those listed above may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other condition above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

**PIN CONNECTIONS**



**ORDERING INFORMATION**

Model	Package	Temperature Range	Relative Accuracy (LSB)	Gain Error (LSB)
DAC7541AJP	Plastic DIP	0°C to +70°C	±1	±8
DAC7541AKP	Plastic DIP	0°C to +70°C	±1/2	±1
DAC7541AJU	Plastic SOIC	0°C to +70°C	±1	±8
DAC7541AKU	Plastic SOIC	0°C to +70°C	±1/2	±1
DAC7541AAH	Hermetic DIP	-25°C to +85°C	±1	±8
DAC7541ABH	Hermetic DIP	-25°C to +85°C	±1/2	±1
DAC7541ASH	Hermetic DIP	-55°C to +125°C	±1	±8
DAC7541ATH	Hermetic DIP	-55°C to +125°C	±1/2	±1

**BURN-IN SCREENING OPTION**  
See text for details.

Model	Package	Temperature Range	Relative Accuracy (LSB)	Burn-In Temp. (160 Hours) <sup>(1)</sup>
DAC7541AJP-BI	Plastic DIP	0°C to +70°C	±1	+85°C
DAC7541AKP-BI	Plastic DIP	0°C to +70°C	±1/2	+85°C
DAC7541AJU-BI	Plastic SOIC	0°C to +70°C	±1	+85°C
DAC7541AKU-BI	Plastic SOIC	0°C to +70°C	±1/2	+85°C
DAC7541AAH-BI	Hermetic DIP	-25°C to +85°C	±1	+125°C
DAC7541ABH-BI	Hermetic DIP	-25°C to +85°C	±1/2	+125°C
DAC7541ASH-BI	Hermetic DIP	-55°C to +125°C	±1	+125°C
DAC7541ATH-BI	Hermetic DIP	-55°C to +125°C	±1/2	+125°C

NOTE: (1) Or equivalent combination of time and temperature.

**CAUTION**

The DAC7541A is an ESD (electrostatic discharge) sensitive device. The digital control inputs have a special FET structure, which turns on when the input exceeds the supply by 18V, to minimize ESD damage. However, permanent damage may occur on unconnected devices subject to high energy electrostatic fields. When not in use, devices must be stored in conductive foam or shunts. The protective foam should be discharged to the destination socket before devices are removed.

**BURN-IN SCREENING**

Burn-in screening is an option available for the models in the Ordering Information table. Burn-in duration is 160 hours at the indicated temperature (or equivalent combination of time and temperature).

All units are tested after burn-in to ensure that grade specifications are met. To order burn-in, add "-BI" to the base model number.

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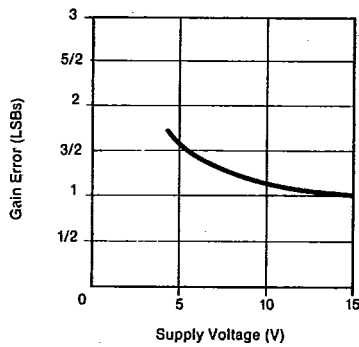
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## TYPICAL PERFORMANCE CURVES

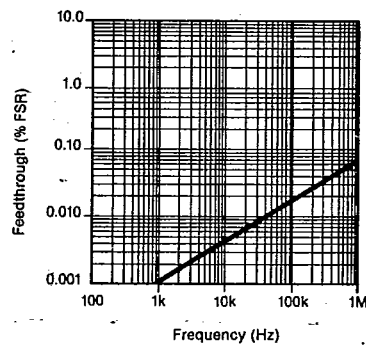
$T_A = +25^\circ\text{C}$ ,  $V_{DD} = +15\text{V}$  unless otherwise noted.

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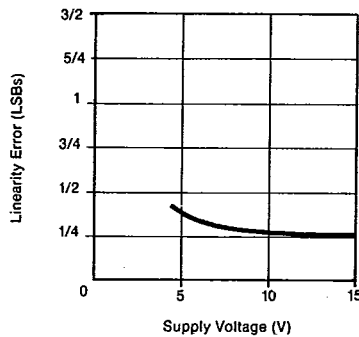
GAIN ERROR VS SUPPLY VOLTAGE



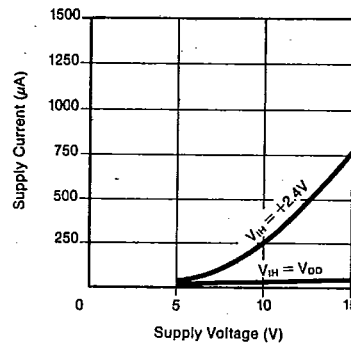
FEEDTHROUGH ERROR VS FREQUENCY



LINEARITY VS SUPPLY VOLTAGE



SUPPLY CURRENT VS SUPPLY VOLTAGE



## DISCUSSION OF SPECIFICATIONS

**Relative Accuracy**

This term (also known as linearity) describes the transfer function of analog output to digital input code. The linearity error describes the deviation from a straight line between zero and full scale.

**Differential Nonlinearity**

Differential Nonlinearity is the deviation from an ideal 1LSB change in the output, from one adjacent output state to the next. A differential nonlinearity specification of  $\pm 1.0\text{LSB}$  guarantees monotonicity.

**Gain Error**

Gain error is the difference in measure of full-scale output versus the ideal DAC output. The ideal output for the DAC7541A is  $-(4095/4096) \times (V_{REF})$ . Gain error may be adjusted to zero using external trims.

**Output Leakage Current**

The measure of current which appears at  $Out_1$  with the DAC loaded with all zeros, or at  $Out_2$  with the DAC loaded to all ones.

**Multiplying Feedthrough Error**

This is the AC error output due to capacitive feedthrough from  $V_{REFERENCE}$  to  $Out_i$  with the DAC loaded to all zeros. This test is performed at 10kHz.

**Output Current Settling Time**

This is the time required for the output to settle to a tolerance of  $\pm 0.5\text{LSB}$  of final value from a change in code of all zeros to all ones, or all ones to all zeros.

**Propagation Delay**

This is the measure of the delay of the internal circuitry and is measured as the time from a digital code change to the point at which the output reaches 90% of final value.

**Digital-to-Analog Glitch Impulse**

This is the measure of the area of the glitch energy measured in nV-seconds. Key contributions to glitch energy are digital word-bit timing differences, internal circuitry timing differences, and charge injected from digital logic.

The measurement is performed with  $V_{REFERENCE} = \text{Ground}$ , an OPA606 as the output op amp, and  $C_1$  (phase compensation) = 0pF.

**Monotonicity**

Monotonicity assures that the analog output will increase or stay the same for increasing digital input codes. The DAC7541A is guaranteed monotonic to 12 bits.

**Power Supply Rejection**

Power supply rejection is the measure of the sensitivity of the output (full scale) to a change in the power supply voltage.

**CIRCUIT DESCRIPTION**

The DAC7541A is a 12-bit multiplying D/A converter consisting of a highly stable thin-film R-2R ladder network and 12 pairs of current steering switches on a monolithic chip. Most applications require the addition of a voltage or current reference and an output operational amplifier.

A simplified circuit of the DAC7541A is shown in Figure 1. The R-2R inverted ladder binary divides the input currents that are switched between  $I_{OUT1}$  and  $I_{OUT2}$  bus lines. This switching allows a constant current to be maintained in each ladder leg independent of the input code.

The input resistance at  $V_{REFERENCE}$  (Figure 1) is always equal to  $R_{LDR}$  ( $R_{LDR}$  is the R/2R ladder characteristic resistance and is equal to value "R"). Since  $R_{IN}$  at the  $V_{REFERENCE}$  pin is constant, the reference terminal can be driven by a reference voltage or a reference current, AC or DC, of positive or negative polarity.

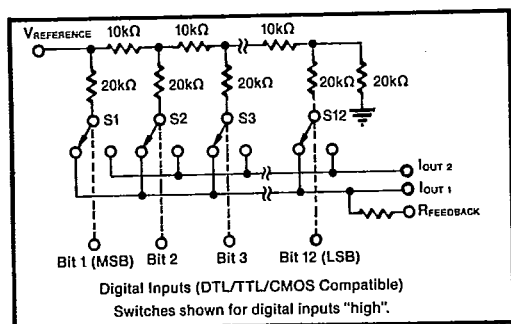


FIGURE 1. Simplified DAC Circuit.

**EQUIVALENT CIRCUIT ANALYSIS**

Figures 2 and 3 show the equivalent circuits for all digital inputs low and high respectively. The reference current is switched to  $I_{OUT2}$  when all inputs are low and  $I_{OUT1}$  when inputs are high. The  $I_{LEAKAGE}$  current source is the combination of surface and junction leakages to the substrate; the  $1/4096$  current source represents the constant one-bit current drain through the ladder termi-

nating resistor. The output capacitance is dependent upon the digital input code, and is therefore modulated between the low and high values.

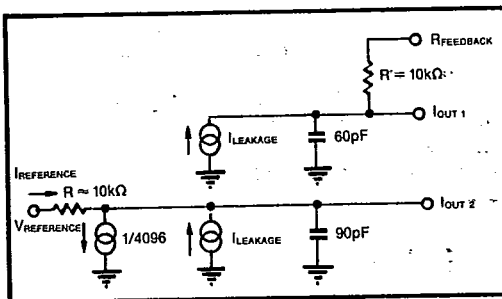


FIGURE 2. DAC7541A Equivalent Circuit (All Inputs Low).

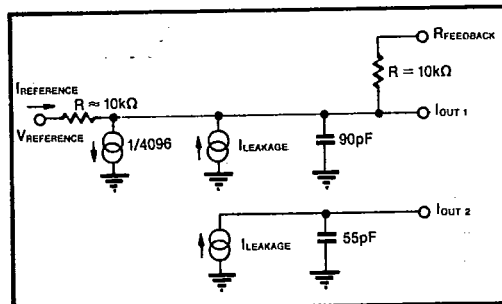


FIGURE 3. DAC7541A Equivalent Circuit (All Inputs High).

**DYNAMIC PERFORMANCE**

**Output Impedance**

The output resistance, as in the case of the output capacitance, is also modulated by the digital input code. The resistance looking back into the  $I_{OUT1}$  terminal may be anywhere between 10kΩ (the feedback resistor alone when all digital inputs are low) and 7.5kΩ (the feedback resistor in parallel with approximately 30kΩ of the R-2R ladder network resistance when any single bit logic is high). The static accuracy and dynamic performance will be affected by this modulation. The gain and phase stability of the output amplifier, board layout, and power supply decoupling will all affect the dynamic performance of the DAC7541A. The use of a compensation capacitor may be required when high-speed operational amplifiers are used. It may be connected across the amplifier's feedback resistor to provide the necessary phase compensation to critically dampen the output. See Figures 4 and 6.

**APPLICATIONS**

**OP AMP CONSIDERATIONS**

The input bias current of the op amp flows through the feedback resistor, creating an error voltage at the output of the op amp. This will show up as an offset through all

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codes of the transfer characteristics. A low bias current op amp such as the OPA606 is recommended.

Low offset voltage and  $V_{OS}$  drift are also important. The output impedance of the DAC is modulated with the digital code. This impedance change (approximately  $10k\Omega$  to  $30k\Omega$ ) is a change in closed-loop gain to the op amp. The result is that  $V_{OS}$  will be multiplied by a factor of one to two depending on the code. This shows up as a linearity error. Offset can be adjusted out using Figure 4. Gain may be adjusted using Figure 5.

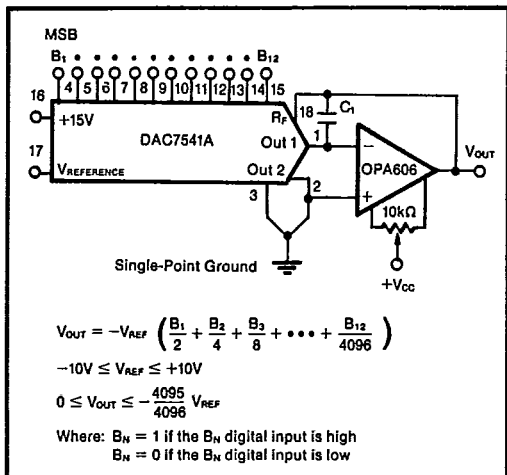


FIGURE 4. Basic Connection With Op Amp  $V_{OS}$  Adjust: Unipolar (two-quadrant) Multiplying Configuration.

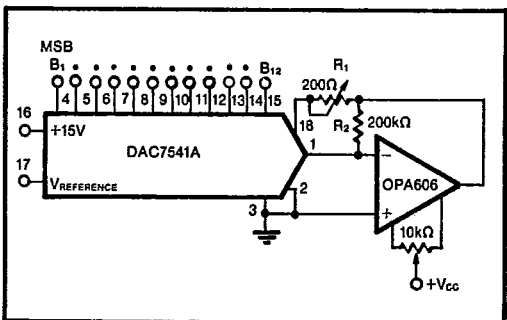


FIGURE 5. Basic Connection with Gain Adjust (allows adjustment up or down).

**UNIPOLAR BINARY OPERATION (TWO-QUADRANT MULTIPLICATION)**

Figure 4 shows the analog circuit connections required for unipolar binary (two-quadrant multiplication) operation. With a DC reference voltage or current (positive or negative polarity) applied at pin 17, the circuit is a

unipolar D/A converter. With an AC reference voltage or current, the circuit provides two-quadrant multiplication (digitally controlled attenuation). The input/output relationship is shown in Table I.

$C_1$  phase compensation (10 to 25pF) in Figure 4 may be required for stability when using high speed amplifiers.  $C_1$  is used to cancel the pole formed by the DAC internal feedback resistance and output capacitance at Out<sub>1</sub>.

TABLE I. Unipolar Codes.

Binary Input		Analog Output
MSB	LSB	
1111	1111 1111	$-V_{REF} (4095/4096)$
1000	0000 0000	$-V_{REF} (2048/4096)$
0000	0000 0001	$-V_{REF} (1/4096)$
0000	0000 0000	0 Volts

$R_1$  in Figure 5 provides full scale trim capability—load the DAC register to 1111 1111 1111, adjust  $R_1$  for  $V_{OUT} = -V_{REF} (4095/4096)$ . Alternatively, full scale can be adjusted by omitting  $R_1$  and  $R_2$  and trimming the reference voltage magnitude.

**BIPOLAR FOUR-QUADRANT OPERATION**

Figure 6 shows the connections for bipolar four-quadrant operation. Offset can be adjusted with the  $A_1$  to  $A_2$  summing resistor, with the input code set to 1000 0000 0000. Gain may be adjusted by varying the feedback resistor of  $A_2$ . The input/output relationship is shown in Table II.

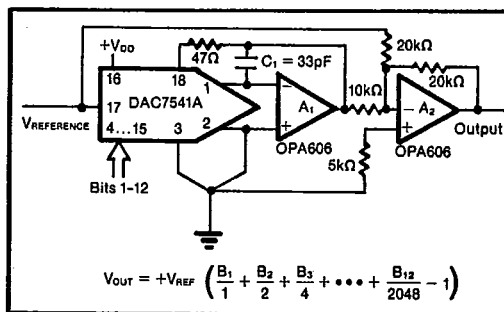


FIGURE 6. Bipolar Four-Quadrant Multiplier.

TABLE II. Bipolar Codes.

Binary Input		Analog Output
MSB	LSB	
1111	1111 1111	$+V_{REF} (2047/2048)$
1000	0000 0000	0 Volts
0111	1111 1111	$-V_{REF} (1/2048)$
0000	0000 0000	$-V_{REF} (2048/2048)$

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**DIGITALLY CONTROLLED GAIN BLOCK**

The 7541A may be used in a digitally controlled gain block as shown in Figure 7. This circuit gives a range of gain from one (all bits = one) to 4096 (LSB = one). The transfer function is:

$$V_{OUT} = \frac{-V_{IN}}{\left(\frac{B_1}{2} + \frac{B_2}{4} + \frac{B_3}{8} + \dots + \frac{B_{12}}{4096}\right)}$$

All bits off is an illegal state, as division by zero is impossible (no op amp feedback). Also, errors increase as gain increases, and errors are minimized at major carries (only one bit on at a time).

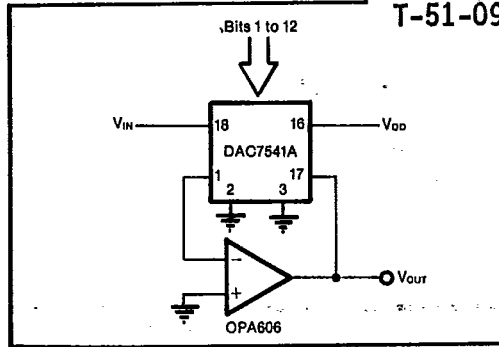


FIGURE 7. Digitally Programmable Gain Block.

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