OCTAL BUS TRANSCEIVER/REGISTER; 3-STATE

FEATURES

- Independent register for A and B buses
- Multiplexed real-time and stored data
- Output capability: bus driver
- I_{CC} category: MSI

GENERAL DESCRIPTION

The 74HC/HCT646 are high-speed Si-gate CMOS devices and are pin compatible with low power Schottky TTL (LSTTL). They are specified in compliance with JEDEC standard no. 7A.

The 74HC/HCT646 consist of bus transceiver circuits with 3-state outputs, D-type flip-flops, and control circuitry arranged for multiplexed transmission of data directly from the internal registers. Data on the "A" or "B" bus will be clocked into the registers as the appropriate clock (CP_{AB} and CP_{BA}) goes to a HIGH logic level. Output enable ($\overline{OE}$) and direction (DIR) inputs are provided to control the transceiver function. In the transceiver mode, data present at the high-impedance port may be stored in either the "A" or "B" register, or in both. The select source inputs (S_{AB} and S_{BA}) can multiplex stored and real-time (transparent mode) data. The direction (DIR) input determines which bus will receive data when $\overline{OE}$ is active (LOW). In the isolation mode ($\overline{OE}$ = HIGH), "A" data may be stored in the "B" register and/or "B" data may be stored in the "A" register.

(continued on next page)

SYMBOL	PARAMETER	CONDITIONS	TYPICAL		UNIT
			HC	HCT	
t_{PHL}/t_{PLH}	propagation delay A_n, B_n to B_n, A_n	C_L = 15 pF; V_{CC} = 5 V	11	13	ns
f_{max}	maximum clock frequency		69	85	MHz
C_I	input capacitance		3.5	3.5	pF
C_{PD}	power dissipation capacitance per channel	notes 1 and 2	30	33	pF

GND = 0 V; T_{amb} = 25 °C; $t_r = t_f$ = 6 ns

Notes

1. C_{PD} is used to determine the dynamic power dissipation (P_D in μW):
   $P_D = C_{PD} \times V_{CC}^2 \times f_i + \Sigma (C_L \times V_{CC}^2 \times f_o)$ where:
   f_i = input frequency in MHz; C_L = output load capacitance in pF
   f_o = output frequency in MHz; V_{CC} = supply voltage in V
   $\Sigma (C_L \times V_{CC}^2 \times f_o)$ = sum of outputs
2. For HC the condition is V_I = GND to V_{CC}
   For HCT the condition is V_I = GND to V_{CC} − 1.5 V

PACKAGE OUTLINES

SEE PACKAGE INFORMATION SECTION

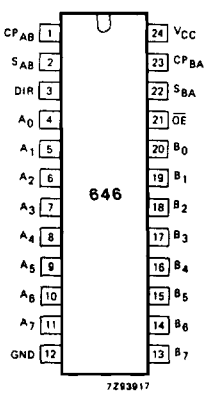

Fig. 1 Pin configuration.

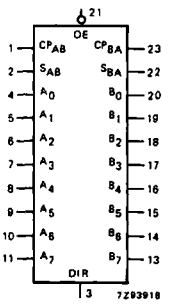

Fig. 2 Logic symbol.

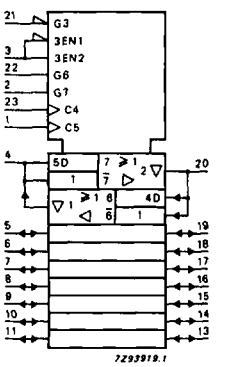

Fig. 3 IEC logic symbol.

PIN DESCRIPTION

PIN NO.	SYMBOL	NAME AND FUNCTION
1	CP_{AB}	A to B clock input (LOW-to-HIGH, edge-triggered)
2	S_{AB}	select A to B source input
3	DIR	direction control input
4, 5, 6, 7, 8, 9, 10, 11	A_0 to A_7	A data inputs/outputs
12	GND	ground (0 V)
20, 19, 18, 17, 16, 15, 14, 13	B_0 to B_7	B data inputs/outputs
21	$\overline{OE}$	output enable input (active LOW)
22	S_{BA}	select B to A source input
23	CP_{BA}	B to A clock input (LOW-to-HIGH, edge-triggered)
24	V_{CC}	positive supply voltage

GENERAL DESCRIPTION

When an output function is disabled, the input function is still enabled and may be used to store and transmit data.
Only one of the two buses, A or B, may be driven at a time.

The "646" is functionally identical to the "648", but has non-inverting data paths.

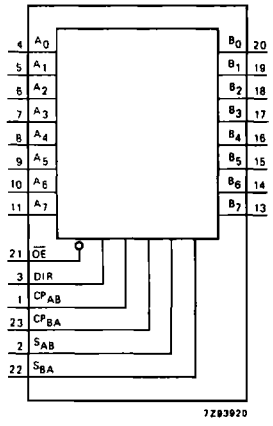

Fig. 4 Functional diagram.

FUNCTION TABLE

INPUTS						DATA I/O *		FUNCTION
$\overline{OE}$	DIR	CP_{AB}	CP_{BA}	S_{AB}	S_{BA}	A_0 to A_7	B_0 to B_7	
H H	X X	H or L ↑	H or L ↑	X X	X X	input	input	isolation store A and B data
L L	L L	X X	X H or L	X X	L H	output	input	real-time B data to A bus stored B data to A bus
L L	H H	X H or L	X X	L H	X X	input	output	real-time A data to B bus stored A data to B bus

* The data output functions may be enabled or disabled by various signals at the $\overline{OE}$ and DIR inputs. Data input functions are always enabled, i.e., data at the bus inputs will be stored on every LOW-to-HIGH transition on the clock inputs.

H = HIGH voltage level
L = LOW voltage level
X = don't care
↑ = LOW-to-HIGH level transition

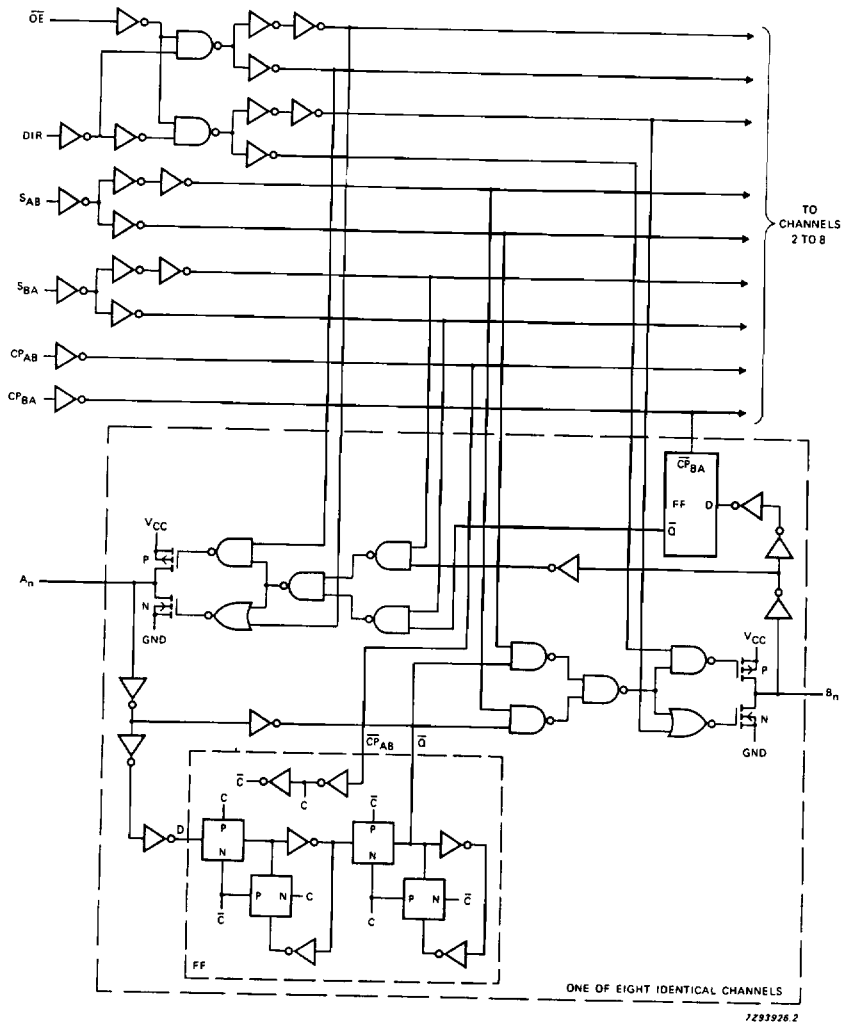

Fig. 5 Logic diagram.

DC CHARACTERISTICS FOR 74HC

For the DC characteristics see chapter "HCMOS family characteristics", section "Family specifications".

Output capability: bus driver
I_{CC} category: MSI

AC CHARACTERISTICS FOR 74HC

GND = 0 V; $t_r = t_f$ = 6 ns; C_L = 50 pF

SYMBOL	PARAMETER	T_{amb} (°C)							UNIT	TEST CONDITIONS	
		74HC								V_{CC} V	WAVEFORMS
		+25			−40 to +85		−40 to +125				
		min.	typ.	max.	min.	max.	min.	max.			
t_{PHL}/t_{PLH}	propagation delay A_n,B_n to B_n,A_n		39 14 11	135 27 23		170 34 29		205 41 35	ns	2.0 4.5 6.0	Fig. 6
t_{PHL}/t_{PLH}	propagation delay CP_{AB},CP_{BA} to B_n,A_n		66 24 19	220 44 37		275 55 47		330 66 56	ns	2.0 4.5 6.0	Fig. 7
t_{PHL}/t_{PLH}	propagation delay S_{AB},S_{BA} to B_n,A_n		55 20 16	190 38 32		240 48 41		285 57 48	ns	2.0 4.5 6.0	Fig. 8
t_{PZH}/t_{PZL}	3-state output enable time $\overline{OE}$ to A_n,B_n		47 17 14	175 35 30		220 44 37		265 53 45	ns	2.0 4.5 6.0	Fig. 9
t_{PHZ}/t_{PLZ}	3-state output disable time $\overline{OE}$ to A_n,B_n		58 21 17	175 35 30		220 44 37		265 53 45	ns	2.0 4.5 6.0	Fig. 9
t_{PZH}/t_{PZL}	3-state output enable time DIR to A_n,B_n		50 18 14	175 35 30		220 44 37		265 53 45	ns	2.0 4.5 6.0	Fig. 10
t_{PHZ}/t_{PLZ}	3-state output disable time DIR to A_n,B_n		50 18 14	175 35 30		220 44 37		265 53 45	ns	2.0 4.5 6.0	Fig. 10
t_{THL}/t_{TLH}	output transition time		14 5 4	60 12 10		75 15 13		90 18 15	ns	2.0 4.5 6.0	Figs 6 and 8
t_W	clock pulse width HIGH or LOW CP_{AB} or CP_{BA}	80 16 14	25 9 7		100 24 20		120 24 20		ns	2.0 4.5 6.0	Fig. 7
t_{su}	set-up time A_n,B_n to CP_{AB},CP_{BA}	60 12 10	−3 −1 −1		75 15 13		90 18 15		ns	2.0 4.5 6.0	Fig. 7
t_h	hold time A_n,B_n to CP_{AB},CP_{BA}	35 7 6	6 2 2		45 9 8		55 11 9		ns	2.0 4.5 6.0	Fig. 7
f_{max}	maximum clock pulse frequency	6.0 30 35	21 63 75		4.8 24 28		4.0 20 24		MHz	2.0 4.5 6.0	Fig. 7

DC CHARACTERISTICS FOR 74HCT

For the DC characteristics see chapter "HCMOS family characteristics", section "Family specifications".

Output capability: bus driver
I_{CC} category: MSI

Note to HCT types

The value of additional quiescent supply current (ΔI_{CC}) for a unit load of 1 is given in the family specifications. To determine ΔI_{CC} per input, multiply this value by the unit load coefficient shown in the table below.

INPUT	UNIT LOAD COEFFICIENT
S_{AB}, S_{BA}	0.60
A_0 to A_7 and B_0 to B_7	0.75

INPUT	UNIT LOAD COEFFICIENT
CP_{AB}, CP_{BA}	1.50
$\overline{OE}$	1.50
DIR	1.25

AC CHARACTERISTICS FOR 74HCT

GND = 0 V; $t_r = t_f$ = 6 ns; C_L = 50 pF

SYMBOL	PARAMETER	T_{amb} (°C)							UNIT	TEST CONDITIONS	
		74HCT								V_{CC} V	WAVEFORMS
		+25			−40 to +85		−40 to +125				
		min.	typ.	max.	min.	max.	min.	max.			
t_{PHL}/t_{PLH}	propagation delay A_n,B_n to B_n,A_n		16	30		38		45	ns	4.5	Fig. 6
t_{PHL}/t_{PLH}	propagation delay CP_{AB},CP_{BA} to B_n,A_n		23	44		55		66	ns	4.5	Fig. 7
t_{PHL}/t_{PLH}	propagation delay S_{AB},S_{BA} to B_n,A_n		26	46		58		69	ns	4.5	Fig. 8
t_{PZH}/t_{PZL}	3-state output enable time $\overline{OE}$ to A_n,B_n		21	40		50		60	ns	4.5	Fig. 9
t_{PHZ}/t_{PLZ}	3-state output disable time $\overline{OE}$ to A_n,B_n		20	35		44		53	ns	4.5	Fig. 9
t_{PZH}/t_{PZL}	3-state output enable time DIR to A_n,B_n		21	40		50		60	ns	4.5	Fig. 10
t_{PHZ}/t_{PLZ}	3-state output disable time DIR to A_n,B_n		21	35		44		53	ns	4.5	Fig. 10
t_{THL}/t_{TLH}	output transition time		5	12		15		18	ns	4.5	Figs 6 and 8
t_W	clock pulse width HIGH or LOW CP_{AB} or CP_{BA}	16	8		20		24		ns	4.5	Fig. 7
t_{su}	set-up time A_n,B_n to CP_{AB},CP_{BA}	12	3		15		18		ns	4.5	Fig. 7
t_h	hold time A_n,B_n to CP_{AB},CP_{BA}	5	1		5		5		ns	4.5	Fig. 7
f_{max}	maximum clock pulse frequency	30	77		24		20		MHz	4.5	Fig. 7

AC WAVEFORMS

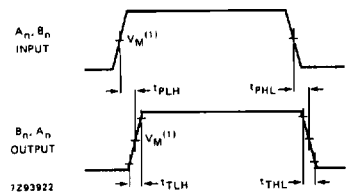

Fig. 6 Waveforms showing the input A_n, B_n to output B_n, A_n propagation delays and the output transition times.

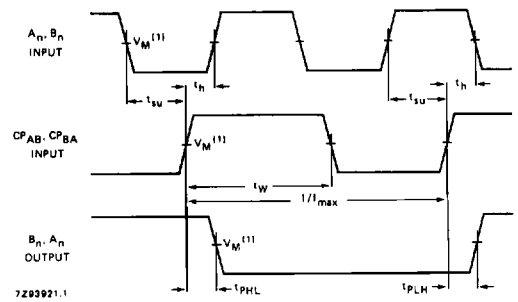

Fig. 7 Waveforms showing the A_n,B_n to CP_{AB},CP_{BA} set-up and hold times, clock CP_{AB},CP_{BA} pulse width, maximum clock pulse frequency and the CP_{AB},CP_{BA} to output B_n,A_n propagation delays.

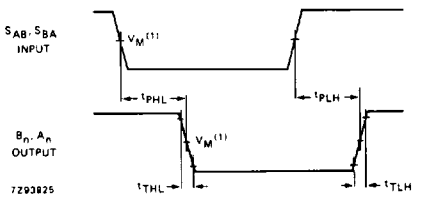

Fig. 8 Waveforms showing the input S_{AB},S_{BA} to output B_n,A_n propagation delays and output transition times.

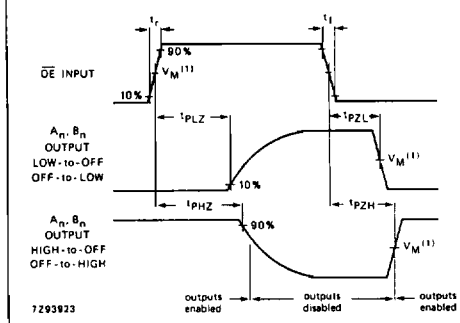

Fig. 9 Waveforms showing the input $\overline{OE}$ to output A_n,B_n 3-state enable and disable times.

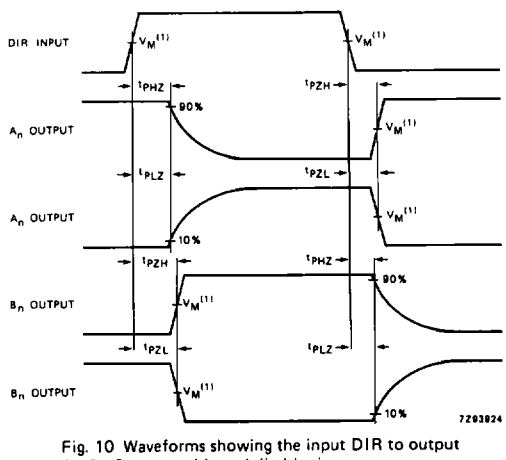

Fig. 10 Waveforms showing the input DIR to output A_n,B_n 3-state enable and disable times.

Note to AC waveforms

(1) HC : V_M = 50%; V_I = GND to V_{CC}.
HCT: V_M = 1.3 V; V_I = GND to 3 V.

APPLICATION INFORMATION

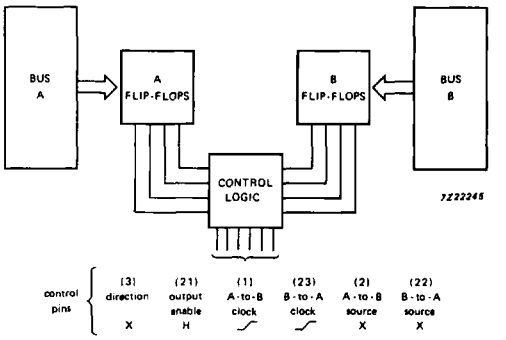

Fig. 11 Data storage from A and/or B bus.

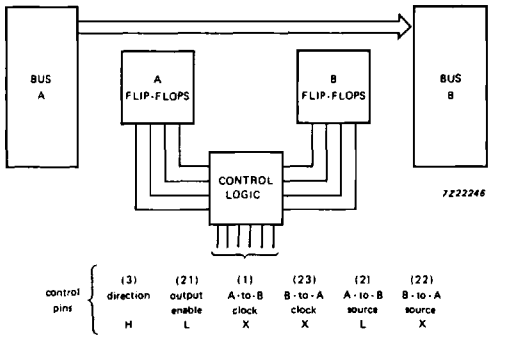

Fig. 12 Real-time transfer from bus A to bus B.

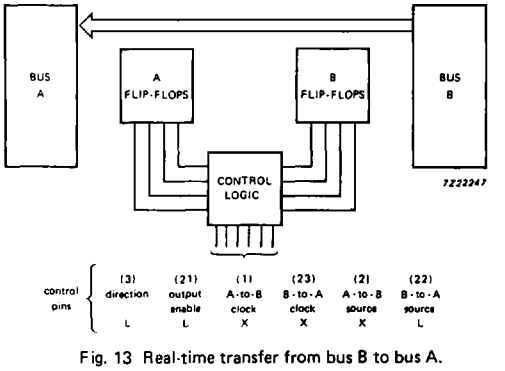

Fig. 13 Real-time transfer from bus B to bus A.