N *National Semiconductor*
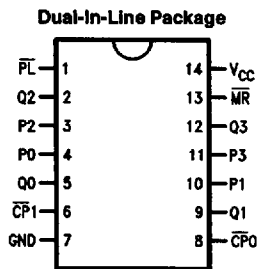
DM74LS196
Presettable Decade Counter

General Description

The 'LS196 decade ripple counter is partitioned into divide-by-two and divide-by-five sections which can be combined to count either in BCD (8421) sequence or in a bi-quinary mode producing a 50% duty cycle output. Both circuit types have a Master Reset ($\overline{MR}$) input which overrides all other inputs and asynchronously forces all outputs LOW. A Parallel Load input ($\overline{PL}$) overrides clocked operations and asynchronously loads the data on the Parallel Data inputs (Pn) into the flip-flops. This preset feature makes the circuits usable as programmable counters. The circuits can also be used as 4-bit latches, loading data from the Parallel Data inputs when $\overline{PL}$ is LOW and storing the data when $\overline{PL}$ is HIGH. In the counting modes, state changes are initiated by the falling edge of the clock.

Features

- High counting rates—typically 60 MHz
- Choice of counting modes—BCD, bi-quinary, binary
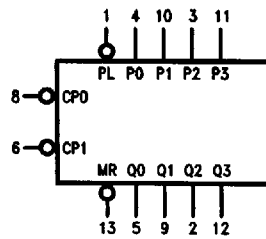- Asynchronous preset and master reset

Connection Diagram

Dual-In-Line Package

TL/F/10179-1

Order Number DM74LS196M or DM74LS196N
See NS Package Number M14A or N14A

Logic Symbol

TL/F/10179-2

V_{CC} = Pin 14
GND = Pin 7

Pin Names	Description
$\overline{CP0}$	÷2 Section Clock Input (Active Falling Edge)
$\overline{CP1}$	÷5 Section Clock Input (Active Falling Edge)
$\overline{MR}$	Asynchronous Master Reset Input (Active LOW)
P0–P3	Parallel Data Inputs
$\overline{PL}$	Asynchronous Parallel Load Input (Active LOW)
Q0–Q3	Flip-Flop Outputs

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Absolute Maximum Ratings (Note)

Supply Voltage	7V
Input Voltage	7V
Operating Free Air Temperature Range	
DM74LS	0°C to +70°C
Storage Temperature Range	−65°C to +150°C

Note: *The "Absolute Maximum Ratings" are those values beyond which the safety of the device cannot be guaranteed. The device should not be operated at these limits. The parametric values defined in the "Electrical Characteristics" table are not guaranteed at the absolute maximum ratings. The "Recommended Operating Conditions" table will define the conditions for actual device operation.*

Recommended Operating Conditions

Symbol	Parameter	DM74LS196			Units
		Min	Nom	Max	
V_{CC}	Supply Voltage	4.75	5	5.25	V
V_{IH}	High Level Input Voltage	2			V
V_{IL}	Low Level Input Voltage			0.8	V
I_{OH}	High Level Output Current			−0.4	mA
I_{OL}	Low Level Output Current			8	mA
T_A	Free Air Operating Temperature	0		70	°C
t_s (H) t_s (L)	Setup Time HIGH or LOW Pn to $\overline{PL}$	8 12			ns
t_h (H) t_h (L)	Hold Time HIGH or LOW Pn to $\overline{PL}$	0 6			ns
t_w (H)	$\overline{CP0}$ Pulse Width HIGH	12			ns
t_w (H)	$\overline{CP1}$ Pulse Width HIGH	24			ns
t_w (L)	$\overline{PL}$ Pulse Width LOW	18			ns
t_w (L)	$\overline{MR}$ Pulse Width LOW	12			ns
t_{rec}	Recovery Time $\overline{PL}$ to $\overline{CP}$n	16			ns
t_{rec}	Recovery Time $\overline{MR}$ to $\overline{CP}$n	18			ns

Electrical Characteristics Over recommended operating free air temperature range (unless otherwise noted)

Symbol	Parameter	Conditions	Min	Typ (Note 1)	Max	Units
V_I	Input Clamp Voltage	V_{CC} = Min, I_I = −18 mA			−1.5	V
V_{OH}	High Level Output Voltage	V_{CC} = Min, I_{OH} = Max, V_{IL} = Max	2.7	3.4		V
V_{OL}	Low Level Output Voltage	V_{CC} = Min, I_{OL} = Max, V_{IH} = Min		0.35	0.5	V
		I_{OL} = 4 mA, V_{CC} = Min		0.25	0.4	
I_I	Input Current @ Max Input Voltage	V_{CC} = Max, V_I = 7V			0.1	mA
I_{IH}	High Level Input Current	V_{CC} = Max, V_I = 5.5V, $\overline{CP1}$			40	μA
I_{IL}	Low Level Input Current	V_{CC} = Max, V_I = 0.4V			−0.4	mA
I_{OS}	Short Circuit Output Current	V_{CC} = Max (Note 2)	−20		−100	mA
I_{CC}	Supply Current	V_{CC} = Max, V_{IN} = GND			20	mA

Note 1: All typicals are at V_{CC} = 5V, T_A = 25°C.
Note 2: Not more than one output should be shorted at a time, and the duration should not exceed one second.

Switching Characteristics

$V_{CC} = +5.0V$, $T_A = +25°C$

| Symbol	Parameter	$R_L = 2k$ $C_L = 15\,pF$		Units
		Min	Max	
f_{max}	Maximum Count Frequency at $\overline{CP}0$	45		MHz
f_{max}	Maximum Count Frequency at $\overline{CP}1$	22.5		MHz
t_{PLH} t_{PHL}	Propagation Delay $\overline{CP}0$ to Q0		15 15	ns
t_{PLH} t_{PHL}	Propagation Delay $\overline{CP}1$ to Q1		15 15	ns
t_{PLH} t_{PHL}	Propagation Delay $\overline{CP}1$ to Q2		34 34	ns
t_{PLH} t_{PHL}	Propagation Delay $\overline{CP}1$ to Q3		15 21	ns
t_{PLH} t_{PHL}	Propagation Delay Pn to Qn		25 35	ns
t_{PLH} t_{PHL}	Propagation Delay $\overline{PL}$ to Qn		31 37	ns
t_{PHL}	Propagation Delay $\overline{MR}$ to Qn		42	ns

Functional Description

The '196 and '197 are asynchronous presettable decade and binary ripple counters. The '196 decade counter is partitioned into divide-by-two and divide-by-five sections while the '197 is partitioned into divide-by-two and divide-by-eight sections, with all sections having a separate Clock input. In the counting modes, state changes are initiated by the HIGH-to-LOW transition of the clock signals. State changes of the Q outputs, however, do not occur simultaneously because of the internal ripple delays. When using external logic to decode the Q outputs, designers should bear in mind that the unequal delays can lead to decoding spikes and thus a decoded signal should not be used as a clock or strobe. The $\overline{CP}0$ input serves the Q0 flip-flop in both circuit types while the $\overline{CP}1$ input serves the divide-by-five or divide-by-eight section. The Q0 output is designed and specified to drive the rated fan-out plus the $\overline{CP}1$ input. With the input frequency connected to $\overline{CP}0$ and with Q0 driving $\overline{CP}1$, the '197 forms a straight forward modulo-16 counter, with Q0 the least significant output and Q3 the most significant output.

The '196 decade counter can be connected up to operate in two different count sequences. With the input frequency connected to $\overline{CP}0$ and with Q0 driving $\overline{CP}1$, the circuit counts in the BCD (8421) sequence. With the input frequency connected to $\overline{CP}1$ and Q3 driving $\overline{CP}0$, Q0 becomes the low frequency output and has a 50% duty cycle waveform. Note that the maximum counting rate is reduced in the latter (bi-quinary) configuration because of the interstage gating delay within the divide-by-five section.

The '196 and '197 have an asynchronous active LOW Master Reset input ($\overline{MR}$) which overrides all other inputs and forces all outputs LOW. The counters are also asynchronously presettable. A LOW on the Parallel Load input ($\overline{PL}$) overrides the clock inputs and loads the data from Parallel Data (P0–P3) inputs into the flip-flops. While $\overline{PL}$ is LOW, the counters act as transparent latches and any change in the Pn inputs will be reflected in the outputs. In order for the intended parallel data to be entered and stored, the recommended setup and hold times with respect to the rising edge of $\overline{PL}$ should be observed.
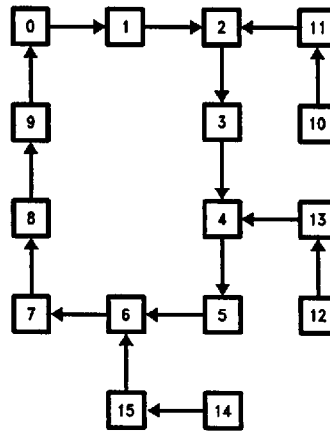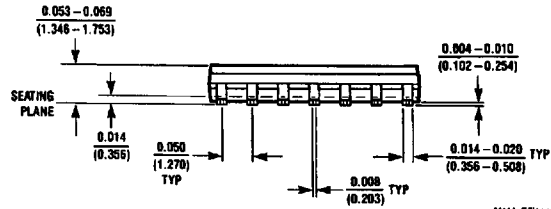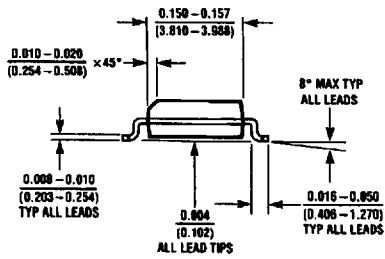
Logic Diagram

TL/F/10179–3

÷5 State Diagram

TL/F/10179–4

BCD State Diagram

TL/F/10179–5
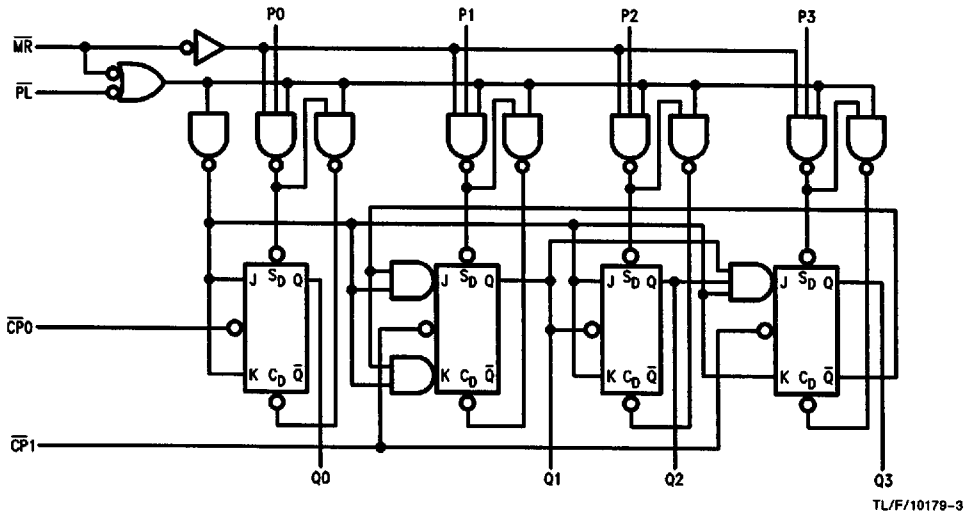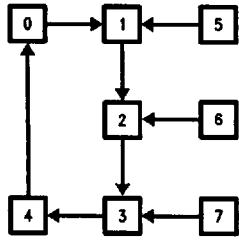
Mode Select Table

Inputs			Response
$\overline{MR}$	$\overline{PL}$	$\overline{CP}$	
L	X	X	Qn forced LOW
H	L	X	Pn → Qn
H	H	⌐⌐	Count Up

H = HIGH Voltage Level
L = LOW Voltage Level
X = Immaterial

Physical Dimensions inches (millimeters)

0.335 – 0.344
(8.509 – 8.738)

14 13 12 11 10 9 8

0.228 – 0.244
(5.791 – 6.198)

LEAD NO. 1
IDENT

30°
TYP

1 2 3 4 5 6 7

0.010 MAX
(0.254)

0.150 – 0.157
(3.810 – 3.988)

0.010 – 0.020
(0.254 – 0.508) ×45°

8° MAX TYP
ALL LEADS

0.009 – 0.010
(0.203 – 0.254)
TYP ALL LEADS

0.004
(0.102)
ALL LEAD TIPS

0.016 – 0.050
(0.406 – 1.270)
TYP ALL LEADS

0.053 – 0.069
(1.346 – 1.753)

SEATING
PLANE

0.014
(0.355)

0.050
(1.270)
TYP

0.004 – 0.010
(0.102 – 0.254)

0.014 – 0.020 TYP
(0.356 – 0.508)

0.008 TYP
(0.203)

M14A (REV H)
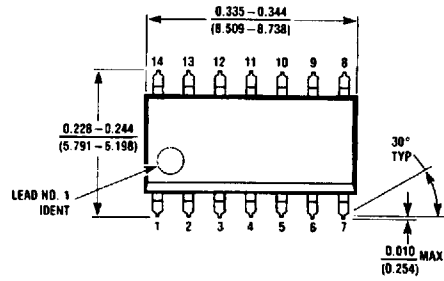
14-Lead Small Outline Molded Package (M)
Order Number DM74LS196M
NS Package Number M14A

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Physical Dimensions inches (millimeters) (Continued)

OPTION 1

OPTION 02
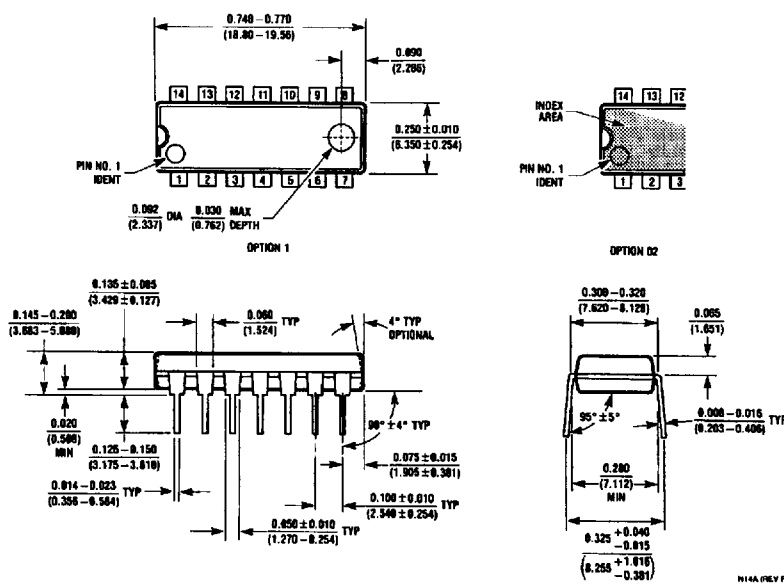
14-Lead Molded Dual-In-Line Package (N)
Order Number DM74LS196N
NS Package Number N14A

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2. A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

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