3.3 V V_{DD}



100-Pin TQFP **Commercial Temp Industrial Temp**

16Mb Pipelined and Flow Through 225 MHz-133 MHz Synchronous NBT SRAM 2.5 V or 3.3 V I/O

Features

- User-configurable Pipeline and Flow Through mode
- NBT (No Bus Turn Around) functionality allows zero wait read-write-read bus utilization
- Fully pin-compatible with both pipelined and flow through NtRAMTM, NoBLTM and ZBTTM SRAMs
- IEEE 1149.1 JTAG-compatible Boundary Scan
- On-chip write parity checking; even or odd selectable
- 3.3 V + 10% / -5% core power supply
- 2.5 V or 3.3 V I/O supply
- 3.3 V-compatible inputs
- LBO pin for Linear or Interleave Burst mode
- Pin-compatible with 2M, 4M, and 8M devices
- Byte write operation (9-bit Bytes)
- 3 chip enable signals for easy depth expansion
- Clock Control, registered, address, data, and control
- ZZ pin for automatic power-down
- JEDEC-standard 100-lead TQFP package

		-225	-200	-180	-166	-150	-133	Unit
Pipeline	tCycle	4.4	5	5.5	6	6.6	7.5	ns
3-1-1-1	tka	2.5	3.0	3.2	3.5	3.8	4.0	ns
	ldd	410	375	340	310	290	260	mΑ
Flow	t _{KQ}	7.0	7.5	8	8.5	10	11	ns
Through	tCycle	8.5	10	10	10	10	15	ns
2-1-1-1	ldd	255	235	235	235	235	220	mΑ

Functional Description

The GS8151Z18/36T is a 16Mbit Synchronous Static SRAM.

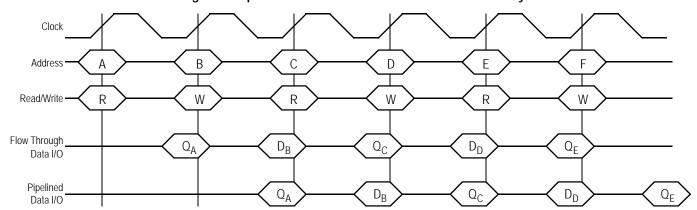
GSI's NBT SRAMs, like ZBT, NtRAM, NoBL or other pipelined read/double late write or flow through read/single late write SRAMs, allow utilization of all available bus bandwidth by eliminating the need to insert deselect cycles when the device is switched from read to write cycles.

Because it is a synchronous device, address, data inputs, and read/ write control inputs are captured on the rising edge of the input clock. Burst order control (LBO) must be tied to a power rail for proper operation. Asynchronous inputs include the Sleep mode enable, ZZ and Output Enable. Output Enable can be used to override the synchronous control of the output drivers and turn the RAM's output drivers off at any time. Write cycles are internally self-timed and initiated by the rising edge of the clock input. This feature eliminates complex offchip write pulse generation required by asynchronous SRAMs and simplifies input signal timing.

The GS8151Z18/36T may be configured by the user to operate in Pipeline or Flow Through mode. Operating as a pipelined synchronous device, in addition to the rising-edge-triggered registers that capture input signals, the device incorporates a rising-edge-triggered output register. For read cycles, pipelined SRAM output data is temporarily stored by the edge triggered output register during the access cycle and then released to the output drivers at the next rising edge of clock.

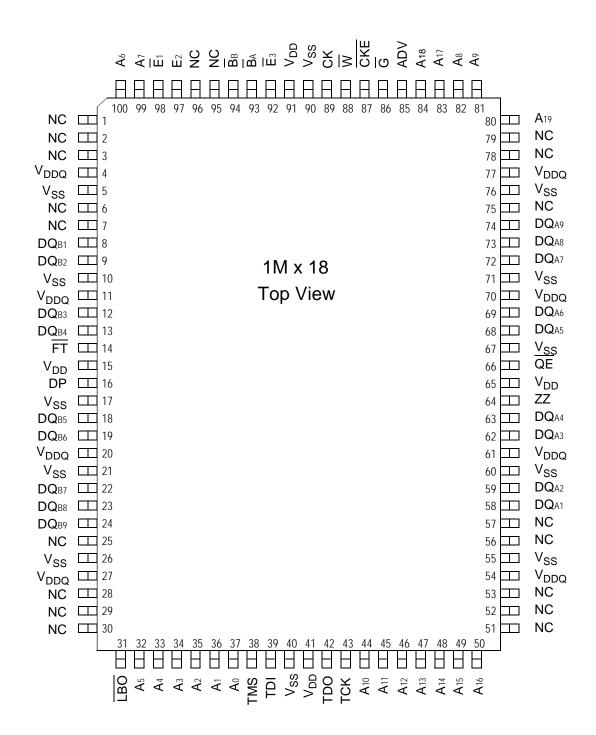
The GS8151Z18/36T is implemented with GSI's high performance CMOS technology and is available in a JEDECstandard 100-pin TQFP package.

Flow Through and Pipelined NBT SRAM Back-to-Back Read/Write Cycles

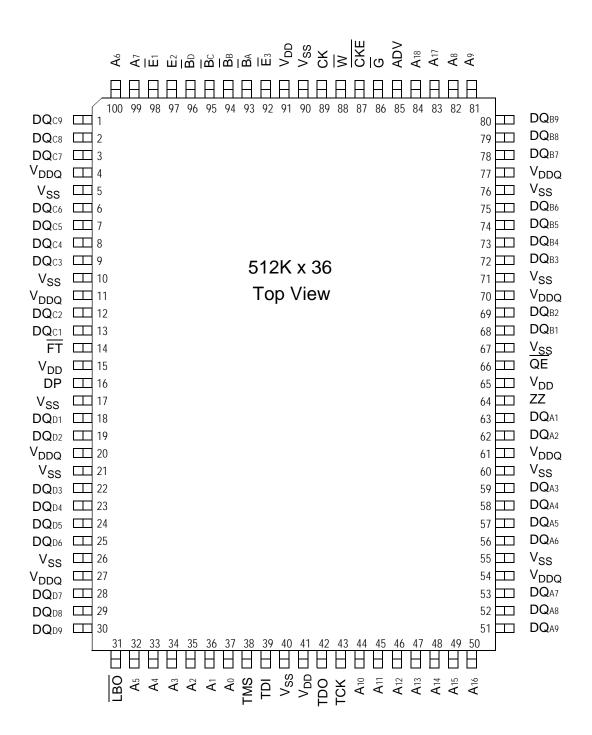


Rev: 1.00 9/2000 © 2000, Giga Semiconductor, Inc.

GS8151Z18T Pinout



GS8151Z36T Pinout





100-Pin TQFP Pin Descriptions

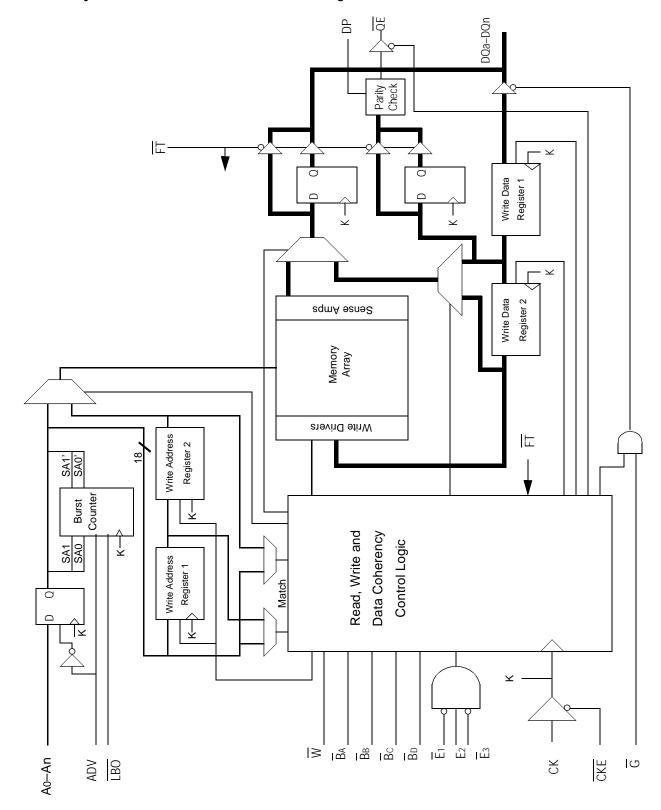
Pin Location	Symbol	Typ e	Description
37, 36	A0, A1	In	Burst Address Inputs; Preload the burst counter
35, 34, 33, 32, 100, 99, 84, 83, 82, 81, 44, 45, 46,47, 48, 49, 50	A2-A18	In	Address Inputs
80	A 19	In	Address Input (x18 Version Only)
89	CK	In	Clock Input Signal
93	Ba	In	Byte Write signal for data inputs DQA1-DQA9; active low
94	Вв	In	Byte Write signal for data inputs DQB1-DQB9; active low
95	Bc	In	Byte Write signal for data inputs DQc1–DQc9; active low (x36 Versions Only)
96	Bo	In	Byte Write signal for data inputs DQp1-DQp9; active low (x36 Versions Only)
88	W	In	Write Enable; active low
98	<u>E</u> 1	In	Chip Enable; active low
97	E2	In	Chip Enable—Active High. For self decoded depth expansion
92	E ₃	In	Chip Enable—Active Low. For self decoded depth expansion
86	G	In	Output Enable; active low
85	ADV	In	Advance/Load; Burst address counter control pin
87	CKE	In	Clock Input Buffer Enable; active low
58, 59, 62,63, 68, 69, 72, 73, 74	DQa1-DQa9	I/O	Byte A Data Input and Output pins.(x18 Version Only)
8, 9, 12, 13, 18, 19, 22, 23, 24	DQB1-DQB9	I/O	Byte B Data Input and Output pins.(x18 Version Only)
51, 52, 53, 56, 57, 75, 78, 79, 1, 2, 3, 6, 7, 25, 28, 29, 30	NC	-	No Connect (x18 Version Only)
51, 52, 53, 56, 57, 58, 59, 62,63	DQa1–DQa9	I/O	Byte A Data Input and Output pins (x36 Versions Only)
68, 69, 72, 73, 74, 75, 78, 79, 80	DQB1-DQB9	I/O	Byte B Data Input and Output pins (x36 Versions Only)
1, 2, 3, 6, 7, 8, 9, 12, 13	DQc1-DQc9	I/O	Byte C Data Input and Output pins (x36 Versions Only)
18, 19, 22, 23, 24, 25, 28, 29, 30	DQD1-DQD9	I/O	Byte D Data Input and Output pins (x36 Versions Only)
64	ZZ	In	Power down control; active high
14	FT	In	Pipeline/Flow Through Mode Control; active low



Pin Location	Symbol	Typ e	Description
31	LBO	In	Linear Burst Order; active low.
38	TMS		Scan Test Mode Select
39	TDI		Scan Test Data In
42	TDO		Scan Test Data Out
43	TCK		Scan Test Clock
15, 41, 65, 91	V_{DD}	In	3.3 V power supply
5,10, 17, 21, 26, 40, 55, 60, 67, 71, 76, 90	V _{SS}	In	Ground
4, 11, 20, 27, 54, 61, 70, 77	V_{DDQ}	In	3.3 V output power supply for noise reduction
16	DP	In	Parity Input; 1 = Even, 0 = Odd
66	QE	Out	Parity Error Out; Open Drain Output



GS8151Z18/36 ByteSafe NBT SRAM Functional Block Diagram





Functional Details

Clocking

Deassertion of the Clock Enable ($\overline{\text{CKE}}$) input blocks the Clock input from reaching the RAM's internal circuits. It may be used to suspend RAM operations. Failure to observe Clock Enable set-up or hold requirements will result in erratic operation.

Pipeline Mode Read and Write Operations

All inputs (with the exception of Output Enable, Linear Burst \underline{Order} and Sleep) are synchronized to rising clock edges. Single cycle read and write operations must be initiated with the Advance/ \underline{Load} pin (ADV) held low, in order to load the new address. Device activation is accomplished by asserting all three of the Chip Enable inputs (\overline{E}_1 , E_2 and \overline{E}_3). Deassertion of any one of the Enable inputs will deactivate the device.

Function	W	BA	BB	Bc	BD
Read	Н	Х	Χ	Χ	Χ
Write Byte "a"	L	L	Н	Н	Н
Write Byte "b"	L	Н	L	Н	Н
Write Byte "c"	L	Н	Н	L	Н
Write Byte "d"	L	Н	Н	Н	L
Write all Bytes	L	L	L	L	L
Write Abort/NOP	L	Н	Н	Н	Н

Read operation is initiated when the following conditions are satisfied at the rising edge of clock: \overline{CKE} is asserted low, all three chip enables (\overline{E}_1 , \overline{E}_2 , and \overline{E}_3) are active, the write enable input signals \overline{W} is deasserted high, and ADV is asserted low. The address presented to the address inputs is latched in to address register and presented to the memory core and control logic. The control logic determines that a read access is in progress and allows the requested data to propagate to the input of the output register. At the next rising edge of clock the read data is allowed to propagate through the output register and onto the output pins.

Write operation occurs when the RAM is selected, CKE is active and the write input is sampled low at the rising edge of clock. The Byte Write Enable inputs $(\overline{B}A, \overline{B}B, \overline{B}C \& \overline{B}D)$ determine which bytes will be written. All or none may be activated. A write cycle with no Byte Write inputs active is a no-op cycle. The pipelined NBT SRAM provides double late write functionality, matching the write command versus data pipeline length (2 cycles) to the read command versus data pipeline length (2 cycles). At the first rising edge of clock, Enable, Write, Byte Write(s), and Address are registered. The Data In associated with that address is required at the third rising edge of clock.

Flow Through Mode Read and Write Operations

Operation of the RAM in Flow Through mode is very similar to operations in Pipeline mode. Activation of a read cycle and the use of the Burst Address Counter is identical. In Flow Through mode the device may begin driving out new data immediately after new address are clocked into the RAM, rather than holding new data until the following (second) clock edge. Therefore, in Flow Through mode the read pipeline is one cycle shorter than in Pipeline mode.

Write operations are initiated in the same way, but differ in that the write pipeline is one cycle shorter as well, preserving the ability to turn the bus from reads to writes without inserting any dead cycles. While the pipelined NBT RAMs implement a double late write protocol, in Flow Through mode a single late write protocol mode is observed. Therefore, in Flow Through mode, address and control are registered on the first rising edge of clock and data in is required at the data input pins at the second rising edge of clock.

Rev: 1.00 9/2000 7/34 © 2000, Giga Semiconductor, Inc.



Synchronous Truth Table

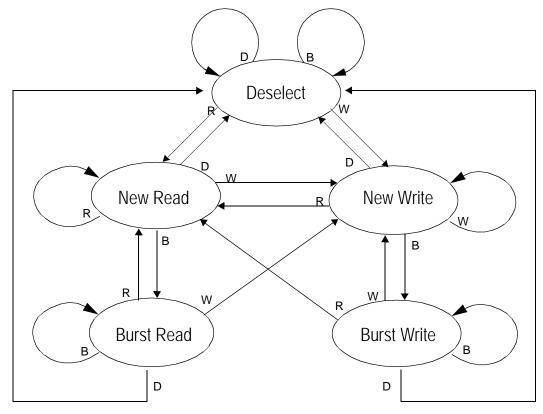
Operation	Туре	Address	<u>E</u> 1	E2	E ₃	ZZ	ADV	W	Вх	G	CKE	СК	DQ	Notes
Deselect Cycle, Power Down	D	None	Н	Χ	Χ	L	L	Χ	Х	Χ	L	L-H	High-Z	
Deselect Cycle, Power Down	D	None	Χ	Χ	Н	L	L	Χ	Χ	Χ	L	L-H	High-Z	
Deselect Cycle, Power Down	D	None	Χ	L	Χ	L	L	Χ	Х	Χ	L	L-H	High-Z	
Deselect Cycle, Continue	D	None	Χ	Χ	Χ	L	Н	Χ	Х	Χ	L	L-H	High-Z	1
Read Cycle, Begin Burst	R	External	L	Н	L	L	L	Н	Χ	L	L	L-H	Q	
Read Cycle, Continue Burst	В	Next	Χ	Χ	Χ	L	Н	Χ	Χ	L	L	L-H	Q	1,10
NOP/Read, Begin Burst	R	External	L	Н	L	L	L	Н	Χ	Н	L	L-H	High-Z	2
Dummy Read, Continue Burst	В	Next	Χ	Χ	Χ	L	Н	Χ	Χ	Н	L	L-H	High-Z	1,2,10
Write Cycle, Begin Burst	W	External	L	Н	L	L	L	L	L	Χ	L	L-H	D	3
Write Cycle, Continue Burst	В	Next	Χ	Χ	Χ	L	Н	Χ	L	Χ	L	L-H	D	1,3,10
NOP/Write Abort, Begin Burst	W	None	L	Н	L	L	L	L	Н	Χ	L	L-H	High-Z	2,3
Write Abort, Continue Burst	В	Next	Χ	Χ	Χ	L	Н	Χ	Н	Χ	L	L-H	High-Z	1,2,3,10
Clock Edge Ignore, Stall		Current	Χ	Χ	Χ	L	Х	Χ	Χ	Χ	Н	L-H	-	4
Sleep Mode		None	Χ	Χ	Χ	Н	Χ	Χ	Χ	Χ	Χ	Х	High-Z	

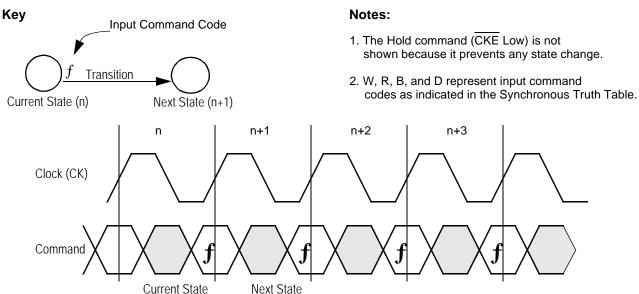
Notes:

- 1. Continue Burst cycles, whether read or write, use the same control inputs. A Deselect continue cycle can only be entered into if a Deselect cycle is executed first.
- 2. Dummy Read and Write abort can be considered NOP's because the SRAM performs no operation. A Write abort occurs when the W pin is sampled low but no Byte Write pins are active so no Write operation is performed.
- 3. G can be wired low to minimize the number of control signals provided to the SRAM. Output drivers will automatically turn off during Write cycles.
- 4. If CKE High occurs during a pipelined Read cycle, the DQ bus will remain active (Low Z). If CKE High occurs during a Write cycle, the bus will remain in High Z.
- 5. X = Don't Care; H = Logic High; L = Logic Low; $\overline{Bx} = High = All Byte Write signals are high; <math>\overline{Bx} = Low = One$ or more Byte/Write signals are low
- 6. All inputs, except \overline{G} and ZZ must meet setup and hold times of rising clock edge.
- 7. Wait states can be inserted by setting $\overline{\mathsf{CKE}}$ high.
- 8. This device contains circuitry that ensures all outputs are in High Z during power-up.
- 9. A 2-bit burst counter is incorporated.
- 10. The address counter is incriminated for all Burst continue cycles.



Pipelined and Flow Through Read Write Control State Diagram

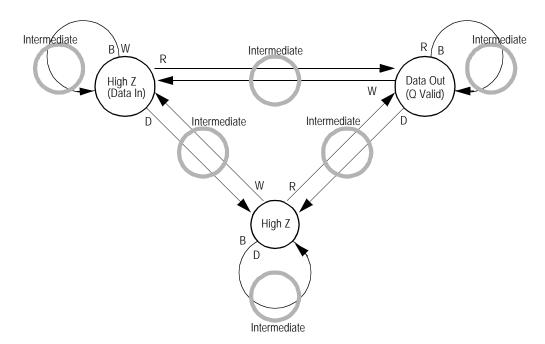


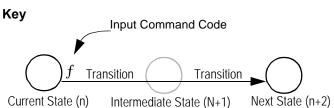


Current State and Next State Definition for Pipelined and Flow Through Read/Write Control State Diagram



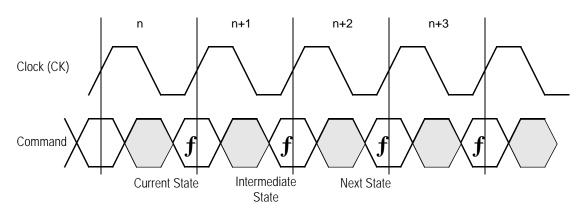
Pipeline Mode Data I/O State Diagram





Notes:

- The Hold command (CKE Low) is not shown because it prevents any state change.
- 2. W, R, B, and D represent input command codes as indicated in the Truth Tables.

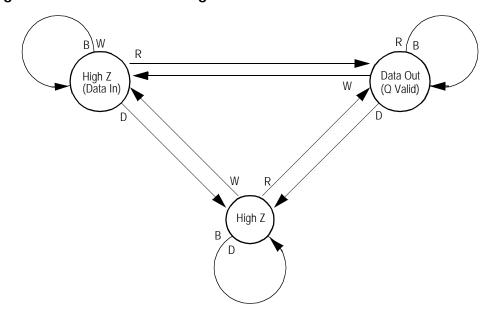


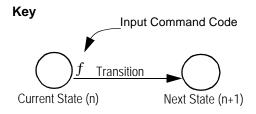
Current State and Next State Definition for Pipeline Mode Data I/O State Diagram

Rev: 1.00 9/2000 10/34 © 2000, Giga Semiconductor, Inc.



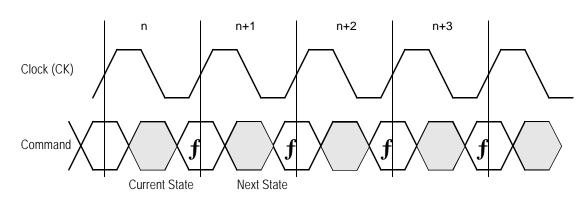
Flow Through Mode Data I/O State Diagram





Notes:

- 1. The Hold command (CKE Low) is not shown because it prevents any state change.
- 2. W, R, B, and D represent input command codes as indicated in the Truth Tables.



Current State and Next State Definition for: Pipeline and Flow through Read Write Control State Diagram



Burst Cycles

Although NBT RAMs are designed to sustain 100% bus bandwidth by eliminating turnaround cycle when there is transition from read to write, multiple back-to-back reads or writes may also be performed. NBT SRAMs provide an on-chip burst address generator that can be utilized, if desired, to further simplify burst read or write implementations. The ADV control pin, when driven high, commands the SRAM to advance the internal address counter and use the counter generated address to read or write the SRAM. The starting address for the first cycle in a burst cycle series is loaded into the SRAM by driving the ADV pin low, into Load mode.

Burst Order

The burst address counter wraps around to its initial state after four addresses (the loaded address and three more) have been accessed. The burst sequence is determined by the state of the Linear Burst Order pin (LBO). When this pin is low, a linear burst sequence is selected. When the RAM is installed with the LBO pin tied high, Interleaved burst sequence is selected. See the tables below for details.

Mode Pin Functions

Mode Name	Pin Name	State	Function
Burst Order Control	LBO	L	Linear Burst
Durst Order Control	LDO	H or NC	Interleaved Burst
Output Register Control	FT	L	Flow Through
Output Register Control	ГІ	H or NC	Pipeline
Power Down Control	77	L or NC	Active
Power Down Control	ZZ	Н	Standby, I _{DD} = I _{SB}
ByteSafe Data Parity Control	DP	L	Check for Odd Parity
bylesale Data Parity Curillul	DP	H or NC	Check for Even Parity

Note:

There are pull up devices on the \overline{LBO} , DP, and \overline{FT} pins and a pull down device on the ZZ pin, so those input pins can be unconnected and the chip will operate in the default states as specified in the above tables.

Burst Counter Sequences Linear Burst Sequence

	A[1:0]	A[1:0]	A[1:0]	A[1:0]
1st address	00	01	10	11
2nd address	01	10	11	00
3rd address	10	11	00	01
4th address	11	00	01	10

Note: The burst counter wraps to initial state on the 5th clock.

Interleaved Burst Sequence

	A[1:0]	A[1:0]	A[1:0]	A[1:0]
1st address	00	01	10	11
2nd address	01	00	11	10
3rd address	10	11	00	01
4th address	11	10	01	00

Note: The burst counter wraps to initial state on the 5th clock.

BPR 1999.05.18

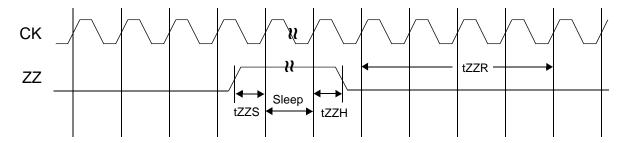


Sleep Mode

During normal operation, ZZ must be pulled low, either by the user or by it's internal pull down resistor. When ZZ is pulled high, the SRAM will enter a Power Sleep mode after 2 cycles. At this time, internal state of the SRAM is preserved. When ZZ returns to low, the SRAM operates normally after 2 cycles of wake up time.

Sleep mode is a low current, power-down mode in which the device is deselected and current is reduced to $I_{SB}2$. The duration of Sleep mode is dictated by the length of time the ZZ is in a high state. After entering Sleep mode, all inputs except ZZ become disabled and all outputs go to High-Z The ZZ pin is an asynchronous, active high input that causes the device to enter Sleep mode. When the ZZ pin is driven high, $I_{SB}2$ is guaranteed after the time tZZI is met. Because ZZ is an asynchronous input, pending operations or operations in progress may not be properly completed if ZZ is asserted. Therefore, Sleep mode must not be initiated until valid pending operations are completed. Similarly, when exiting Sleep mode during tZZR, only a Deselect or Read commands may be applied while the SRAM is recovering from Sleep mode.

Sleep Mode Timing Diagram



Designing for Compatibility

The GSI NBT SRAMs offer users a configurable selection between Flow Through mode and Pipelinemode via the \overline{FT} signal found on Pin 14. Not all vendors offer this option, however most mark Pin 14 as V_{DD} or V_{DDQ} on pipelined parts and V_{SS} on flow through parts. GSI NBT SRAMs are fully compatible with these sockets.

Pin 66, a No Connect (NC) on GSI's GS8160Z18/36 NBT SRAM, the Parity Error open drain output on GSI's GS8161Z18/36 NBT SRAM, is often marked as a power pin on other vendor's NBT compatible SRAMs. Specifically, it is marked V_{DD} or V_{DDQ} on pipelined parts and V_{SS} on flow through parts. Users of GSI NBT devices who are not actually using the ByteSafeTM parity feature may want to design the board site for the RAM with Pin 66 tied high through a 1k ohm resistor in Pipeline mode applications or tied low in Flow Through mode applications in order to keep the option to use non-configurable devices open. By using the pull-up resistor, rather than tying the pin to one of the power rails, users interested in upgrading to GSI's ByteSafe NBT SRAMs (GS8161Z18/36), featuring Parity Error detection and JTAG Boundary Scan, will be ready for connection to the active low, open drain Parity Error output driver at pin 66 on GSI's TQFP ByteSafe RAMs.

ByteSafe™ Parity Functions

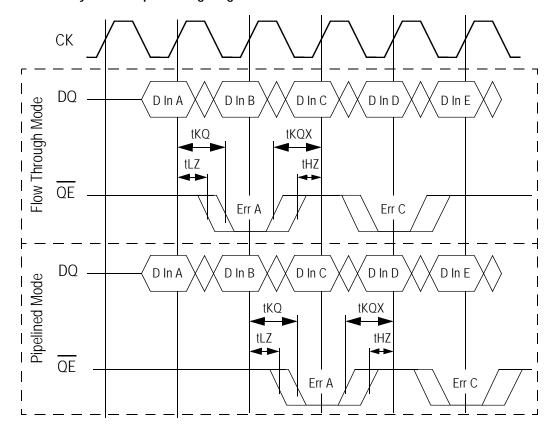
In x32/x16 mode this RAM features a parity encoding and checking function. It is assumed that the RAM is being used in x32/x16 mode because there is no source for parity bits from the system. So, in x32/x16 mode, the device generates parity and stores it along with written data. It is also assumed that there is no facility for parity checking, so the RAM checks read parity and reports an error in the cycle following parity check. In x32/x16 mode the device does not drive the 9th data output, even though the internal ByteSafe parity encoding has been activated. A ByteSafe SRAM, used in x32/x16 mode, allows parity protection of data in applications where parity encoding or checking are not otherwise available. As in any system that checks read parity, reads of unwritten memory locations may well produce parity errors. Initialization of the memory should be implemented to avoid this issue.

This SRAM includes a write data parity check that checks the validity of data coming into the RAM on write cycles. In Flow Through mode, write data errors are reported in the cycle following the data input cycle. In Pipeline mode, write data errors are reported one clock cycle later. (See timing diagram below.) The Data Parity Mode (DP) pin must be tied high to set the RAM to



check for even parity or low to check for odd parity. Read data parity is not checked by the RAM as data validity is best established at the data's destination. The Parity Error Output is an open drain output and drives low to indicate a parity error. Multiple Parity Error Output pins may share a common pull-up resistor.

x18/x36 Mode Write Parity Error Output Timing Diagram



BPR 1999.05.18



Absolute Maximum Ratings

(All voltages reference to V_{SS})

Symbol	Description	Value	Unit
V_{DD}	Voltage on V _{DD} Pins	-0.5 to 4.6	V
V_{DDQ}	Voltage in V _{DDQ} Pins	–0.5 to V _{DD}	V
V _{CK}	Voltage on Clock Input Pin	-0.5 to 6	V
V _{I/O}	Voltage on I/O Pins	$-0.5 \text{ to V}_{DDQ} + 0.5 \ (\le 4.6 \text{ V max.})$	V
V _{IN}	Voltage on Other Input Pins	$-0.5 \text{ to V}_{DD} + 0.5 \ (\le 4.6 \text{ V max.})$	V
I _{IN}	Input Current on Any Pin	+/-20	mA
I _{OUT}	Output Current on Any I/O Pin	+/-20	mA
P _D	Package Power Dissipation	1.5	W
T _{STG}	Storage Temperature	-55 to 125	οС
T _{BIAS}	Temperature Under Bias	-55 to 125	°C

Note:

Permanent damage to the device may occur if the Absolute Maximum Ratings are exceeded. Operation should be restricted to Recommended Operating Conditions. Exposure to conditions exceeding the Absolute Maximum Ratings, for an extended period of time, may affect reliability of this component.

Recommended Operating Conditions

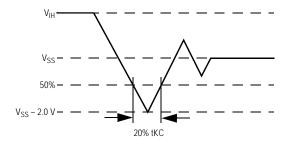
Parameter	Symbol	Min.	Тур.	Max.	Unit	Notes
Supply Voltage	V_{DD}	3.135	3.3	3.6	V	
I/O Supply Voltage	V_{DDQ}	2.375	2.5	V_{DD}	V	1
Input High Voltage	V _{IH}	1.7	_	V _{DD} +0.3	V	2
Input Low Voltage	V _{IL}	-0.3	_	0.8	V	2
Ambient Temperature (Commercial Range Versions)	T _A	0	25	70	°C	3
Ambient Temperature (Industrial Range Versions)	T _A	-40	25	85	°C	3

Notes:

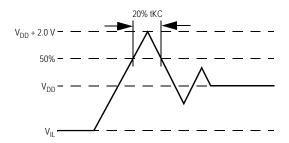
- Unless otherwise noted, all performance specifications quoted are evaluated for worst case at both 2.75 V ≤ V_{DDQ} ≤ 2.375 V (i.e., 2.5 V I/O) and 3.6 V ≤ V_{DDQ} ≤ 3.135 V (i.e., 3.3 V I/O), and quoted at whichever condition is worst case.
- 2. This device features input buffers compatible with both 3.3 V and 2.5 V I/O drivers.
- 3. Most speed grades and configurations of this device are offered in both Commercial and Industrial Temperature ranges. The part number of Industrial Temperature Range versions end the character "I". Unless otherwise noted, all performance specifications quoted are evaluated for worst case in the temperature range marked on the device.
- 4. Input Under/overshoot voltage must be $-2 \text{ V} > \text{Vi} < \text{V}_{DD} + 2 \text{ V}$ with a pulse width not to exceed 20% tKC.



Undershoot Measurement and Timing



Overshoot Measurement and Timing



Capacitance

$$(T_A = 25^{\circ}C, f = 1 \text{ MHz}, V_{DD} = 3.3 \text{ V})$$

Parameter	Symbol	Test conditions	Тур.	Max.	Unit
Input Capacitance	C _{IN}	V _{IN} = 0 V	4	5	pF
Input/Output Capacitance	C _{I/O}	V _{OUT} = 0 V	6 (x36) 12 (x18)	7 (x36) 12 (x18)	pF

Note: These parameters are sample tested.

Package Thermal Characteristics

Rating	Layer Board	Symbol	Max	Unit	Notes
Junction to Ambient (at 200 lfm)	single	$R_{\Theta JA}$	40	°C/W	1,2
Junction to Ambient (at 200 lfm)	four	R_{\ThetaJA}	24	°C/W	1,2
Junction to Case (TOP)	_	$R_{\Theta JC}$	9	°C/W	3

Notes:

- 1. Junction temperature is a function of SRAM power dissipation, package thermal resistance, mounting board temperature, ambient. Temperature air flow, board density, and PCB thermal resistance.
- 2. SCMI G-38-87
- 3. Average thermal resistance between die and top surface, MIL SPEC-883, Method 1012.1

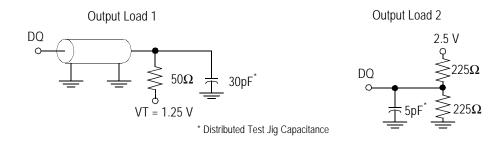


AC Test Conditions

Parameter	Conditions
Input high level	2.3 V
Input low level	0.2 V
Input slew rate	1 V/ns
Input reference level	1.25 V
Output reference level	1.25 V
Output load	Fig. 1& 2

Notes:

- 1. Include scope and jig capacitance.
- 2. Test conditions as specified with output loading as shown in Fig. 1 unless otherwise noted.
- 3. Output Load 2 for $t_{LZ}^{},\,t_{HZ},\,t_{OLZ}$ and t_{OHZ}
- 4. Device is deselected as defined by the Truth Table.



DC Electrical Characteristics

Parameter	Symbol	Test Conditions	Min	Max
Input Leakage Current (except mode pins)	I _{IL}	V _{IN} = 0 to V _{DD}	–1 uA	1 uA
ZZ Input Current	I _{INZZ}	$V_{DD} \ge V_{IN} \ge V_{IH}$ $0 \ V \le V_{IN} \le V_{IH}$	–1 uA –1 uA	1 uA 300 uA
Mode Pin Input Current	I _{INM}	$V_{DD} \ge V_{IN} \ge V_{IL}$ $0 \ V \le V_{IN} \le V_{IL}$	−300 uA −1 uA	1 uA 1 uA
Output Leakage Current	I _{OL}	Output Disable, V _{OUT} = 0 to V _{DD}	–1 uA	1 uA
Output High Voltage	V _{OH}	$I_{OH} = -4 \text{ mA}, V_{DDQ} = 2.375 \text{ V}$	1.7 V	_
Output High Voltage	V _{OH}	$I_{OH} = -4 \text{ mA}, V_{DDQ} = 3.135 \text{ V}$	2.4 V	_
Output Low Voltage	V _{OL}	$I_{OL} = 4 \text{ mA}$	_	0.4 V



Operating Currents

					-2	-225	-5	-200	-180	90	-166	9:	-150	0.	-133	3	
Parameter	Test Conditions		Mode	Symbol		-40	0	-40	0	-40		-40	0 ;	40	0	-40	Unit
					00 10	01 85°C	00 20°C	01 10	00 01	01 85°C	0.07	10 85°C	10 70°C	το 85°C	0°07	10 85°C	
		(36^)	Pipeline	100 1000	335 74	345 84	303	313 76	278 59	288	260	270 65	240	250	218	228 54	mA
Operating	Device Selected; All other inputs	(ocy)	Flow Through	aa _l	199 39	209	177	187 43	177	187 43	177	187 43	177	187 43	134	144	mA
Current	≥V _{IH} or ≤ V _{IL} Output open	(81%)	Pipeline	lpp Ippa	310 37	320 47	281 33	291 43	258 30	268	242 27	252 37	223 25	233	204	214	mA
		(614)	Flow Through	lpp Ippo	186 19	196 29	166	176 27	166	176 27	166 17	176 27	166	176 27	127	137	mA
Standby	:		Pipeline	ISB	10	20	10	20	10	20	10	20	10	20	10	20	mA
Current	$ZZ \ge V_{DD} - 0.2 \text{ V}$		Flow Through	I _{SB}	10	20	10	20	10	20	10	20	10	20	10	20	mA
Deselect	Device Deselected:		Pipeline	aal	08	98	22	08	0/	75	64	70	09	99	20	22	mA
Current	All other inputs $\geq V_{\parallel}$ or $\leq V_{\parallel}$	I	Flow Through	aa _l	09	99	20	22	20	55	50	22	50	22	45	20	mA

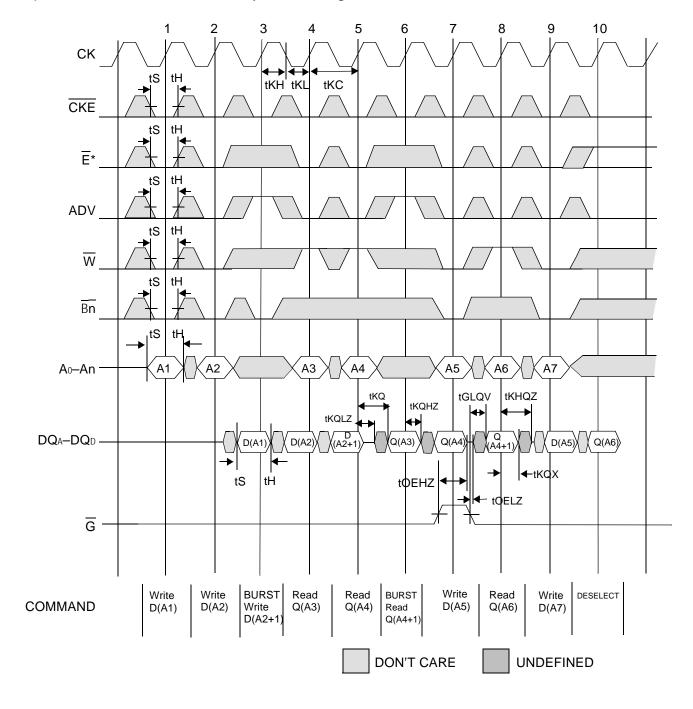


AC Electrical Characteristics

	Parameter	Symbol	-22	25	-20	00	-1	80	-16	6	-1	50	-1	33	Unit
	Parameter	Зупион	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Ullit
	Clock Cycle Time	tKC	4.4	_	5.0	_	5.5	_	6.0	_	6.7	_	7.5	_	ns
Pipeline	Clock to Output Valid	tKQ	_	2.5	1	3.0		3.2	1	3.5	_	3.8		4.0	ns
Pipellile	Clock to Output Invalid	tKQX	1.5	_	1.5	_	1.5	_	1.5	_	1.5		1.5	_	ns
	Clock to Output in Low-Z	tLZ ¹	1.5	_	1.5	_	1.5	_	1.5	_	1.5	_	1.5	_	ns
	Clock Cycle Time	tKC	8.5	_	10.0	_	10.0	_	10.0	_	10.0	_	15.0	_	ns
Flow	Clock to Output Valid	tKQ	_	7.0	1	7.5		8.0		8.5	_	10.0		11.0	ns
Through	Clock to Output Invalid	tKQX	3.0	_	3.0	_	3.0	_	3.0	_	3.0		3.0	_	ns
	Clock to Output in Low-Z	tLZ ¹	3.0	_	3.0		3.0	_	3.0	_	3.0	_	3.0	_	ns
	Clock HIGH Time	tKH	1.3	_	1.3	_	1.3	_	1.3	_	1.5		1.7	_	ns
	Clock LOW Time	tKL	1.5	_	1.5	_	1.5	_	1.5	_	1.7		2	_	ns
	Clock to Output in High-Z	tHZ ¹	1.5	2.5	1.5	3.0	1.5	3.2	1.5	3.5	1.5	3.8	1.5	4.0	ns
	G to Output Valid	tOE	_	2.5	_	3.2	_	3.2	_	3.5	_	3.8		4.0	ns
	G to output in Low-Z	tOLZ ¹	0	_	0	_	0	_	0	_	0	_	0	_	ns
	G to output in High-Z	tOHZ ¹	_	2.5	_	3.0	_	3.2	_	3.5	_	3.8	_	4.0	ns
	Setup time	tS	1.5	_	1.5	_	1.5	_	1.5	_	1.5		1.5	_	ns
	Hold time	tH	0.5	_	0.5	_	0.5	_	0.5	_	0.5	_	0.5	_	ns
	ZZ setup time	tZZS ²	5	_	5	_	5	_	5	_	5	_	5	_	ns
	ZZ hold time	tZZH ²	1	_	1	_	1		1		1	_	1	_	ns
	ZZ recovery	tZZR	100	_	100	_	100		100		100		100	_	ns



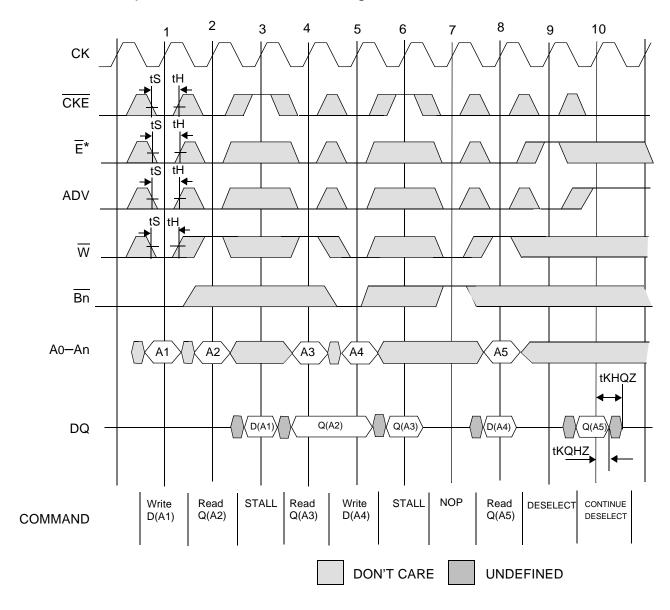
Pipeline Mode Read/Write Cycle Timing



*Note: \overline{E} = High (False) if \overline{E}_1 = 1 or \overline{E}_2 = 0 or \overline{E}_3 = 1



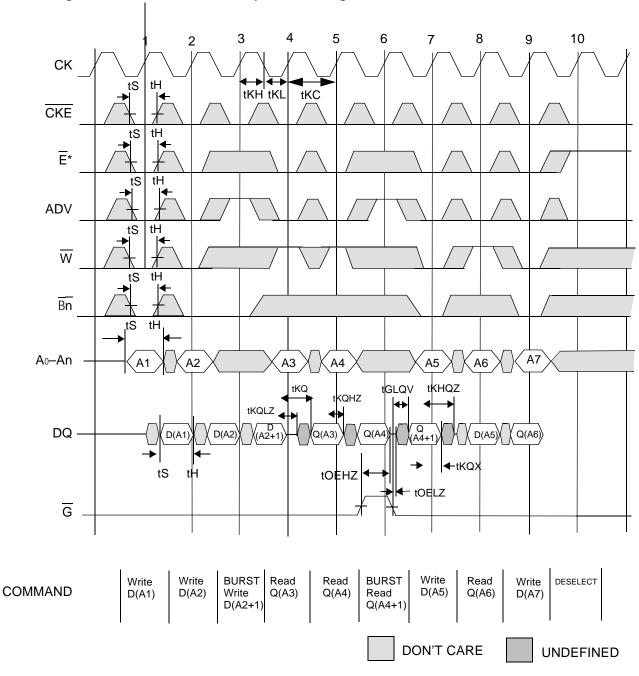
Pipeline Mode No-Op, Stall and Deselect Timing



*Note: \overline{E} = High (False) if \overline{E}_1 = 1 or E_2 = 0 or \overline{E}_3 = 1



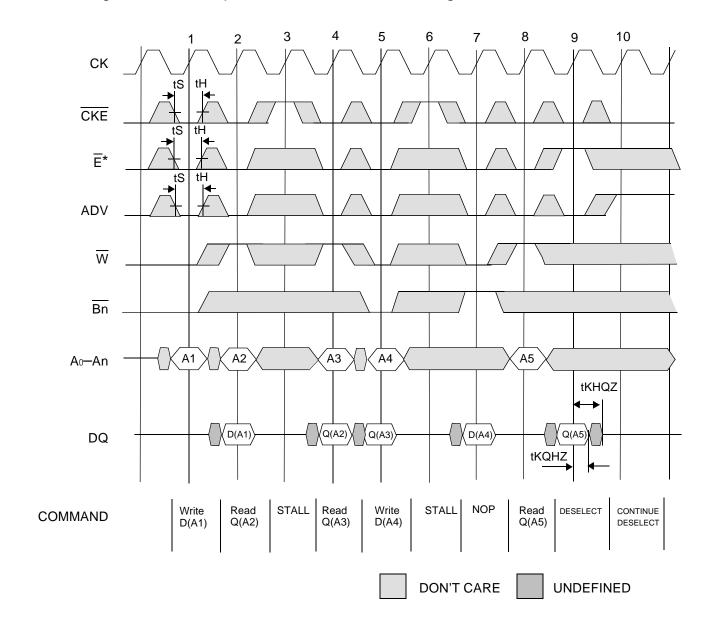
Flow Through Mode Read/Write Cycle Timing



*Note: \overline{E} = High (False) if \overline{E}_1 = 1 or E_2 = 0 or \overline{E}_3 = 1



Flow Through Mode No-Op, Stall and Deselect Timing



*Note: \overline{E} = High (False) if \overline{E}_1 = 1 or \overline{E}_2 = 0 or \overline{E}_3 = 1



JTAG Port Operation

Overview

The JTAG Port on this RAM operates in a manner consistent with IEEE Standard 1149.1-1990, a serial boundary scan interface standard (commonly referred to as JTAG), but does not implement all of the functions required for 1149.1 compliance. Unlike JTAG implementations that have been common among SRAM vendors for the last several years, this implementation does offer a form of EXTEST, known as Clock Assisted EXTEST, reducing or eliminating the "hand coding" that has been required to overcome the test program compiler errors caused by previous non-compliant implementations. The JTAG Port interfaces with conventional 2.5 V CMOS logic level signaling.

Disabling the JTAG Port

It is possible to use this device without utilizing the JTAG port. The port is reset at power-up and will remain inactive unless clocked. TCK, TDI, and TMS are designed with internal pull-up circuits. To assure normal operation of the RAM with the JTAG Port unused, TCK, TDI, and TMS may be left floating or tied to either V_{DD} or V_{SS} . TDO should be left unconnected.

JTAG Pin Descriptions

Pin	Pin Name	I/O	Description
TCK	Test Clock	ln	Clocks all TAP events. All inputs are captured on the rising edge of TCK and all outputs propagate from the falling edge of TCK.
TMS	Test Mode Select	In	The TMS input is sampled on the rising edge of TCK. This is the command input for the TAP controller state machine. An undriven TMS input will produce the same result as a logic one input level.
TDI	Test Data In	In	The TDI input is sampled on the rising edge of TCK. This is the input side of the serial registers placed between TDI and TDO. The register placed between TDI and TDO is determined by the state of the TAP Controller state machine and the instruction that is currently loaded in the TAP Instruction Register (refer to the TAP Controller State Diagram). An undriven TDI pin will produce the same result as a logic one input level.
TDO	Test Data Out	Out	Output that is active depending on the state of the TAP state machine. Output changes in response to the falling edge of TCK. This is the output side of the serial registers placed between TDI and TDO.

Note:

This device does not have a TRST (TAP Reset) pin. TRST is optional in IEEE 1149.1. The Test-Logic-Reset state is entered while TMS is held high for five rising edges of TCK. The TAP Controller is also reset automaticly at power-up.

JTAG Port Registers

Overview

The various JTAG registers, refered to as Test Access Port orTAP Registers, are selected (one at a time) via the sequences of 1s and 0s applied to TMS as TCK is strobed. Each of the TAP Registers is a serial shift register that captures serial input data on the rising edge of TCK and pushes serial data out on the next falling edge of TCK. When a register is selected, it is placed between the TDI and TDO pins.

Instruction Register

The Instruction Register holds the instructions that are executed by the TAP controller when it is moved into the Run, Test/Idle, or the various data register states. Instructions are 3 bits long. The Instruction Register can be loaded when it is placed between the TDI and TDO pins. The Instruction Register is automatically preloaded with the IDCODE instruction at power-up or whenever the controller is placed in Test-Logic-Reset state.



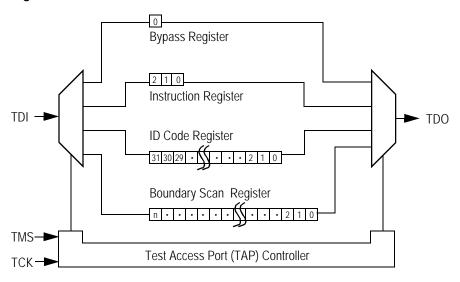
Bypass Register

The Bypass Register is a single bit register that can be placed between TDI and TDO. It allows serial test data to be passed through the RAM's JTAG Port to another device in the scan chain with as little delay as possible.

Boundary Scan Register

The Boundary Scan Register is a collection of flip flops that can be preset by the logic level found on the RAM's input or I/O pins. The flip flops are then daisy chained together so the levels found can be shifted serially out of the JTAG Port's TDO pin. The Boundary Scan Register also includes a number of place holder flip flops (always set to a logic 1). The relationship between the device pins and the bits in the Boundary Scan Register is described in the Scan Order Table following. The Boundary Scan Register, under the control of the TAP Controller, is loaded with the contents of the RAMs I/O ring when the controller is in Capture-DR state and then is placed between the TDI and TDO pins when the controller is moved to Shift-DR state. SAMPLE-Z, SAMPLE/PRELOAD and EXTEST instructions can be used to activate the Boundary Scan Register.

JTAG TAP Block Diagram



Identification (ID) Register

The ID Register is a 32-bit register that is loaded with a device and vendor specific 32-bit code when the controller is put in Capture-DR state with the IDCODE command loaded in the Instruction Register. The code is loaded from a 32-bit on-chip ROM. It describes various attributes of the RAM as indicated below. The register is then placed between the TDI and TDO pins when the controller is moved into Shift-DR state. Bit 0 in the register is the LSB and the first to reach TDO when shifting begins.



ID Register Contents

		Revi	ie sior de	ı					ſ	Not l	Used	d					Co	l/ nfig		ion				ED	Tec EC D C	Ve	nd					Presence Register
Bit #	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	1 1	10	9	8	7	6	5	4	3	2	1	0
x36	Χ	Χ	Χ	Χ	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0	1	1	0	1	1	0	0	1	1
x18	Χ	Χ	Χ	Χ	0	0	0	0	0	0	0	0	0	0	0	0	1	0	1	0	0	0	0	1	1	0	1	1	0	0	1	1

Tap Controller Instruction Set

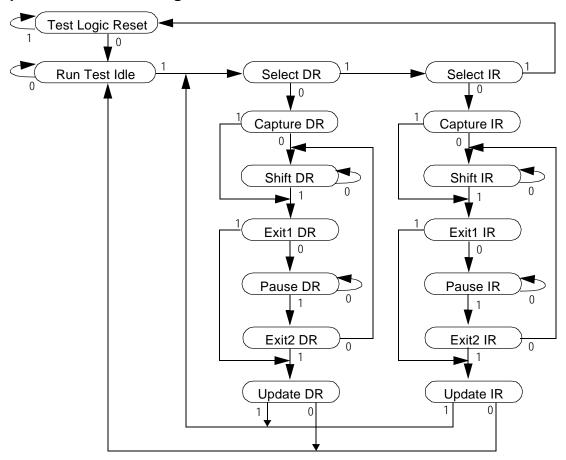
Overview

There are two classes of instructions defined in the Standard 1149.1-1990; the standard (Public) instructions, and device specific (Private) instructions. Some Public instructions are mandatory for 1149.1 compliance. Optional Public instructions must be implemented in prescribed ways. Although the TAP controller in this device follows the 1149.1 conventions, it is not 1194.1 compliant because some of the mandatory instructions are uniquely implemented. The TAP on this device may be used to monitor all input and I/O pads, but cannot be used to load address, data or control signals into the RAM or to preload the I/O buffers. This device will not perform INTEST or the preload portion of the SAMPLE / PRELOAD command.

When the TAP controller is placed in Capture-IR state the two least significant bits of the instruction register are loaded with 01. When the controller is moved to the Shift-IR state the Instruction Register is placed between TDI and TDO. In this state the desired instruction is serially loaded through the TDI input (while the previous contents are shifted out at TDO). For all instructions, the TAP executes newly loaded instructions only when the controller is moved to Update-IR state. The TAP instruction set for this device is listed in the following table.



JTAG Tap Controller State Diagram



Instruction Descriptions

BYPASS

When the BYPASS instruction is loaded in the Instruction Register the Bypass Register is placed between TDI and TDO. This occurs when the TAP controller is moved to the Shift-DR state. This allows the board level scan path to be shortened to facilitate testing of other devices in the scan path.

SAMPLE/PRELOAD

SAMPLE/PRELOAD is a Standard 1149.1 mandatory public instruction. When the SAMPLE / PRELOAD instruction is loaded in the Instruction Register, moving the TAP controller into the Capture-DR state loads the data in the RAMs input and I/O buffers into the Boundary Scan Register. Because the RAM clock is independent from the TAP Clock (TCK) it is possible for the TAP to attempt to capture the I/O ring contents while the input buffers are in transition (i.e. in a metastable state). Although allowing the TAP to sample metastable inputs will not harm the device, repeatable results cannot be expected. RAM input signals must be stabilized for long enough to meet the TAPs input data capture set-up plus hold time (tTS plus tTH). The RAMs clock inputs need not be paused for any other TAP operation except capturing the I/O ring contents into the Boundary Scan Register. Moving the controller to Shift-DR state then places the boundary scan register between the TDI and TDO pins. Because the PRELOAD portion of the command is not implemented in this device, moving the controller to the Update-DR state with the SAMPLE / PRELOAD instruction loaded in the Instruction Register has the same effect as the Pause-DR command. This functionality is not Standard 1149.1 compliant.

EXTEST (EXTEST-A)

EXTEST is an IEEE 1149.1 mandatory public instruction. It is to be executed whenever the instruction register, whatever length it may be in the device, is loaded with all logic 0s. The EXTEST implementation in this device does not, without further user intervention, actually move

Rev: 1.00 9/2000 27/34 © 2000, Giga Semiconductor, Inc.



the contents of the scan chain onto the RAM's output pins. Therefore, this device is not strictly 1149.1-compliant. Nevertheless, this RAM's TAP does respond to an all 0s instruction, EXTEST (000), by overriding the RAM's control inputs and activating the Data I/O output drivers. The RAM's main clock (CK) may then be used to transfer Boundary Scan Register contents associated with each I/O from the scan register to the RAM's output drivers and onto the I/O pins. A single CK transition is sufficient to transfer the data, but more transitions will do no harm.

IDCODE

The IDCODE instruction causes the ID ROM to be loaded into the ID register when the controller is in Capture-DR mode and places the ID register between the TDI and TDO pins in Shift-DR mode. The IDCODE instruction is the default instruction loaded in at power up and any time the controller is placed in the Test-Logic-Reset state.

SAMPLE-Z

If the SAMPLE-Z instruction is loaded in the instruction register, all RAM outputs are forced to an inactive drive state (high-Z) and the Boundary Scan Register is connected between TDI and TDO when the TAP controller is moved to the Shift-DR state.

RFU

These instructions are Reserved for Future Use. In this device they replicate the BYPASS instruction.

JTAG TAP Instruction Set Summary

Instruction	Code	Description	Notes
EXTEST-A	000	Places the Boundary Scan Register between TDI and TDO. This RAM implements an Clock Assisted EXTEST function. *Not 1149.1 Compliant *	1
IDCODE	001	Preloads ID Register and places it between TDI and TDO.	1, 2
SAMPLE-Z	010	Captures I/O ring contents. Places the Boundary Scan Register between TDI and TDO. Forces all RAM output drivers to High-Z.	1
RFU	011	Do not use this instruction; Reserved for Future Use. Replicates BYPASS instruction. Places Bypass Register between TDI and TDO.	1
SAMPLE/PRELOAD	100	Captures I/O ring contents. Places the Boundary Scan Register between TDI and TDO. This RAM does not implement 1149.1 PRELOAD function. *Not 1149.1 Compliant *	1
GSI	101	GSI private instruction.	1
RFU	110	Do not use this instruction; Reserved for Future Use. Replicates BYPASS instruction. Places Bypass Register between TDI and TDO.	1
BYPASS	111	Places Bypass Register between TDI and TDO.	1

Notes:

1. Instruction codes expressed in binary, MSB on left, LSB on right.

2. Default instruction automatically loaded at power-up and in test-logic-reset state.



JTAG Port Recommended Operating Conditions and DC Characteristics

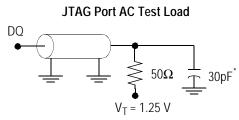
Parameter	Symbol	Min.	Max.	Unit	Notes
Test Port Input High Voltage	V _{IHT}	0.7 * V _{DD}	V _{DD} +0.3	V	1, 2
Test Port Input Low Voltage	V _{ILT}	-0.3	0.3 * V _{DD}	V	1, 2
TMS, TCK and TDI Input Leakage Current	I _{INTH}	-300	1	uA	3
TMS, TCK and TDI Input Leakage Current	I _{INTL}	– 1	1	uA	4
TDO Output Leakage Current	I _{OLT}	- 1	1	uA	5
Test Port Output High Voltage	V _{OHT}	1.7	_	V	6, 7
Test Port Output Low Voltage	V _{OLT}	_	0.4	V	6, 8

Note:

- 1. This device features input buffers compatible with 2.5 V I/O drivers.
- 2. Input Under/overshoot voltage must be -2 V > Vi < V_{DD} +2 V with a pulse width not to exceed 20% tTKC.
- 3. $V_{DD} \ge V_{IN} \ge V_{IL}$
- 4. $0 \text{ V} \leq \text{V}_{IN} \leq \text{V}_{IL}$
- 5. Output Disable, $V_{OUT} = 0$ to V_{DD}
- The TDO output driver is served by the V_{DD} supply.
- 7. $I_{OH} = -4 \text{ mA}$
- 8. $I_{OL} = + 4 \text{ mA}$

JTAG Port AC Test Conditions

Parameter	Conditions
Input high level	2.3 V
Input low level	0.2 V
Input slew rate	1 V/ns
Input reference level	1.25 V
Output reference level	1.25 V



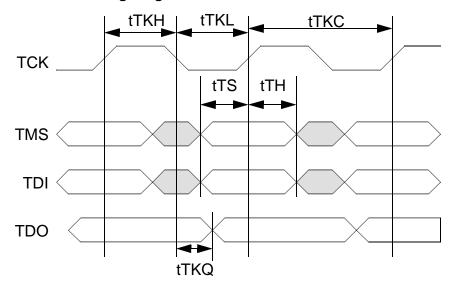
* Distributed Test Jig Capacitance

Notes:

- 1. Include scope and jig capacitance.
- 2. Test conditions as as shown unless otherwise noted.



JTAG Port Timing Diagram



JTAG Port AC Electrical Characteristics

Parameter	Symbol	Min	Max	Unit
TCK Cycle Time	tTKC	20	_	ns
TCK Low to TDO Valid	tTKQ	_	10	ns
TCK High Pulse Width	tTKH	10	-	ns
TCK Low Pulse Width	tTKL	10	-	ns
TDI & TMS Set Up Time	tTS	5	_	ns
TDI & TMS Hold Time	tTH	5	_	ns



GS8151Z18/36T TQFP Boundary Scan Register

Order	х36	x18	Pin
1	PH = ()	n/a
2	PH = ()	n/a
3	A10		44
4	A11		45
5	A 12		46
6	A 13		47
7	A 14		48
8	A 15		49
9	A16		50
10	x36 = DQA9	NC = 1	51
11	DQ _{A8}	NC = 1	52
12	DQ _A 7	NC = 1	53
13	DQA6	NC = 1	56
14	DQ _{A5}	NC = 1	57
15	DQA4	DQa1	58
16	DQ _A 3	59	
17	DQ _{A2}	62	
18	DQa1	DQA4	63
19	ZZ		64
20	QE		66
21	DQ _{B1}	DQ _{A5}	68
22	DQ _{B2}	DQA6	69
23	DQ _{B3}	DQ _{A7}	72
24	DQ _{B4}	DQ _{A8}	73
25	DQ _{B5}	DQa9	74
26	DQ _{B6}	NC = 1	75
27	DQ _{B7}	NC = 1	78
28	DQ _{B8}	NC = 1	79
29	x36 = DQ _{B9}	A 19	80
30	A 9		81
31	A 8		82
32	A 17		83

Order	х36	x18	Pin			
32	ADV		83			
33	A 18		84			
33	ADSP		84			
34	ADV		85			
34	ADSC	•	85			
35	G		86			
36	CKE		87			
36	BW		87			
37	W		88			
37	GW		88			
38	CK		89			
39	PH = ()	n/a			
39	PH = 1		n/a			
40	PH = 1		n/a			
40	PH = ()	n/a			
41	<u>E</u> 3		92			
41	A17	92				
42	BA	Ba				
43	BB		94			
44	Bc	NC = 1	95			
45	BD	NC = 1	96			
46	A 18		97			
46	E2		97			
47	<u>E</u> 1		98			
47	E ₁		98			
48	A 7		99			
49	A 6		100			
50	x36 = DQc9	NC = 1	1			
51	DQc8	NC = 1	2			
52	DQc7	NC = 1	3			
53	DQc6	NC = 1	6			
54	DQc5	NC = 1	7			

Order	x36 x18		Pin
55	DQc4	DQ _{B1}	8
56	DQc3	DQ _{B2}	9
57	DQc2	DQ _{B3}	12
58	DQc1	DQ _{B4}	13
59	FT		14
60	DP		16
61	PH = 1		n/a
62	DQ _{D1}	DQ _{B5}	18
63	DQ _{D2}	DQ _{B6}	19
64	DQ _{D3}	DQ _{B7}	22
65	DQ _{D4}	DQ _{B8}	23
66	DQ _{D5}	DQ _{B9}	24
67	DQ _{D6}	NC = 1	25
68	DQ _{D7}	NC = 1	28
69	DQ _{D8}	NC = 1	29
70	x36 = DQD9	NC = 1	30
71	LBO		31
72	A5	32	
73	A4	33	
74	A3	34	
75	A2		35
76	A1		36
77	A0		37
78	PH = 0		n/a

BPR 1999.05.14

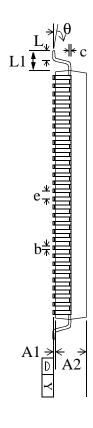
Note:

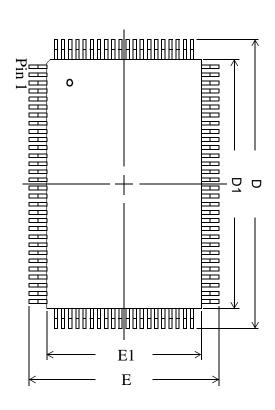
- 1. The Boundary Scan Register contains a number of registers that are not connected to any pin. They default to the value shown at reset.
- 2. Registers are listed in exit order (i.e. Location 1 is the first out of the TDO pin.
- 3. NC = No Connect, NA = Not Active, PH = Place Holder (No associated pin)



TQFP Package Drawing

Symbol	Description	Min.	Nom.	Max
A1	Standoff	0.05	0.10	0.15
A2	Body Thickness	1.35	1.40	1.45
b	Lead Width	0.20	0.30	0.40
С	Lead Thickness	0.09		0.20
D	Terminal Dimension	21.9	22.0	20.1
D1	Package Body	19.9	20.0	20.1
Е	Terminal Dimension	15.9	16.0	16.1
E1	Package Body	13.9	14.0	14.1
е	Lead Pitch		0.65	
L	Foot Length	0.45	0.60	0.75
L1 Lead Length			1.00	
Υ	Coplanarity			0.10
θ Lead Angle		0°		7°





Notes:

- 1. All dimensions are in millimeters (mm).
- 2. Package width and length do not include mold protrusion.

BPR 1999.05.18



Ordering Information—GSI NBT Synchronous SRAM

Org	Part Number ¹	Туре	Package	Speed ² (MHz/ns)	T _A ³	Status
1M x 18	GS8151Z18T-225	ByteSafe NBT Pipeline/Flow Through	TQFP	225/7	С	
1M x 18	GS8151Z18T-200	ByteSafe NBT Pipeline/Flow Through	TQFP	200/7.5	С	
1M x 18	GS8151Z18T-180	ByteSafe NBT Pipeline/Flow Through	TQFP	180/8	С	
1M x 18	GS8151Z18T-166	ByteSafe NBT Pipeline/Flow Through	TQFP	166/8.5	С	
1M x 18	GS8151Z18T-150	ByteSafe NBT Pipeline/Flow Through	TQFP	150/10	С	
1M x 18	GS8151Z18T-133	ByteSafe NBT Pipeline/Flow Through	TQFP	133/11	С	
512K x 36	GS8151Z36T-225	ByteSafe NBT Pipeline/Flow Through	TQFP	225/7	С	
512K x 36	GS8151Z36T-200	ByteSafe NBT Pipeline/Flow Through	TQFP	200/7.5	С	
512K x 36	GS8151Z36T-180	ByteSafe NBT Pipeline/Flow Through	TQFP	180/8	С	
512K x 36	GS8151Z36T-166	ByteSafe NBT Pipeline/Flow Through	TQFP	166/8.5	С	
512K x 36	GS8151Z36T-150	ByteSafe NBT Pipeline/Flow Through	TQFP	150/10	С	
512K x 36	GS8151Z36T-133	ByteSafe NBT Pipeline/Flow Through	TQFP	133/11	С	
1M x 18	GS8151Z18T-225I	ByteSafe NBT Pipeline/Flow Through	TQFP	225/7	I	Not Available
1M x 18	GS8151Z18T-200I	ByteSafe NBT Pipeline/Flow Through	TQFP	200/7.5	I	Not Available
1M x 18	GS8151Z18T-180I	ByteSafe NBT Pipeline/Flow Through	TQFP	180/8	I	
1M x 18	GS8151Z18T-166l	ByteSafe NBT Pipeline/Flow Through	TQFP	166/8.5	I	
1M x 18	GS8151Z18T-150I	ByteSafe NBT Pipeline/Flow Through	TQFP	150/10	I	
1M x 18	GS8151Z18T-133I	ByteSafe NBT Pipeline/Flow Through	TQFP	133/11	I	
512K x 36	GS8151Z36T-225I	ByteSafe NBT Pipeline/Flow Through	TQFP	225/7	I	Not Available
512K x 36	GS8151Z36T-200I	ByteSafe NBT Pipeline/Flow Through	TQFP	200/7.5	I	Not Available
512K x 36	GS8151Z36T-180I	ByteSafe NBT Pipeline/Flow Through	TQFP	180/8	- 1	
512K x 36	GS8151Z36T-166l	ByteSafe NBT Pipeline/Flow Through	TQFP	166/8.5	I	
512K x 36	GS8151Z36T-150I	ByteSafe NBT Pipeline/Flow Through	TQFP	150/10	I	
512K x 36	GS8151Z36T-133I	ByteSafe NBT Pipeline/Flow Through	TQFP	133/11	ı	

Notes:

- 1. Customers requiring delivery in Tape and Reel should add the character "T" to the end of the part number. Example: GS8151Z36T-100IT.
- 2. The speed column indicates the cycle frequency (MHz) of the device in Pipeline mode and the latency (ns) in Flow Through mode. Each device is Pipeline/Flow through mode-selectable by the user.
- 3. $T_A = C = Commercial Temperature Range. T_A = I = Industrial Temperature Range.$
- 4. GSI offers other versions this type of device in many different configurations and with a variety of different features, only some of which are covered in this data sheet. See the GSI Technology web site (www.gsitechnology.com) for a complete listing of current offerings

Rev: 1.00 9/2000 33/34 © 2000, Giga Semiconductor, Inc.



0.18u 16M Sync SRAM Data Sheet Revision History

DS/DateRev. Code: Old; New	Types of Changes Format or Content	Page;Revisions;Reason
8151Z18_r1		Creation of new datasheet