











#### LMH6642, LMH6643, LMH6644

SNOS966Q -MAY 2001-REVISED SEPTEMBER 2014

## LMH664x Low Power, 130 MHz, 75 mA Rail-to-Rail Output Amplifiers

#### 1 Features

 $(V_S = \pm 5 \ V, \ T_A = 25^{\circ}C, \ R_L = 2 \ k\Omega, \ A_V = +1.$ Typical Values Unless Specified).

- $-3 \text{ dB BW } (A_V = +1) 130 \text{ MHz}$
- Supply Voltage Range 2.7 V to 12.8 V
- Slew Rate,  $(A_V = -1) 130V/\mu s^{(1)}$
- Supply Current (no load) 2.7 mA/amp
- Output Short Circuit Current +115 mA to 145 mA
- Linear Output Current ±75 mA
- Input Common Mode Volt. 0.5 V Beyond V<sup>-</sup>, 1 V
- Output Voltage Swing 40 mV from Rails
- Input Voltage Noise (100 kHz) 17nV/√Hz
- Input Current Noise (100 kHz) 0.9pA/√Hz
- THD (5MHz,  $R_L = 2k\Omega$ ,  $V_O = 2V_{PP}$ ,  $A_V = +2$ ) -62 dBc
- Settling Time 68 ns
- Fully Characterized for 3 V, 5 V, and ±5 V
- Overdrive Recovery 100 ns
- Output Short Circuit Protected<sup>(2)</sup>
- No Output Phase Reversal with CMVR Exceeded

## **Applications**

- **Active Filters**
- CD/DVD ROM
- ADC Buffer Amp
- Portable Video
- Current Sense Buffer

#### 3 Description

The LMH664X family true single supply voltage feedback amplifiers offer high speed (130 MHz), low distortion (-62 dBc), and exceptionally high output current (approximately 75 mA) at low cost and with reduced power consumption when compared against existing devices with similar performance.

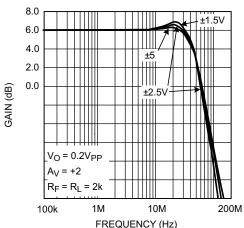
Input common mode voltage range extends to 0.5 V below V<sup>-</sup> and 1 V from V<sup>+</sup>. Output voltage range extends to within 40 mV of either supply rail, allowing wide dynamic range especially desirable in low voltage applications. The output stage is capable of approximately 75 mA in order to drive heavy loads. Fast output Slew Rate (130 V/µs) ensures large peak-to-peak output swings can be maintained even at higher speeds, resulting in exceptional full power bandwidth of 40 MHz with a 3 V supply. These characteristics, along with low cost, are ideal features a multitude of industrial and commercial applications.

#### Device Information<sup>(1)</sup>

PART NUMBER	PACKAGE	BODY SIZE (NOM)		
LMH6642	SOT-23 (5)	2.90 mm × 1.60 mm		
LIVIN0042	SOIC (8)	4.90 mm × 3.91 mm		
LAULCC 40	SOIC (8)	2.00 2.00		
LMH6643	VSSOP (8)	3.00 mm × 3.00 mm		
LMUCCAA	SOIC (14)	8.64 mm × 3.91 mm		
LMH6644	TSSOP (14)	5.00 mm × 4.40 mm		

(1) For all available packages, see the orderable addendum at the end of the datasheet.

#### Closed Loop Gain vs. Frequency for Various Supplies



<sup>(1)</sup> Slew rate is the average of the rising and falling slew rates

 $<sup>^{(2)}</sup>$  Output short circuit duration is infinite for  $V_S < 6 \text{ V}$  at room temperature and below. For V<sub>S</sub> > 6 V, allowable short circuit duration is 1.5 ms.



#### **Table of Contents**

1	Features 1		8.2 Functional Block Diagram	21
2	Applications 1		8.3 Feature Description	21
3	Description 1		8.4 Device Functional Modes	21
4	Revision History2	9	Application and Implementation	22
5	Description (continued)		9.1 Application Information	22
6	Pin Configuration and Functions		9.2 Typical Application	22
7	_	10	Power Supply Recommendations	<mark>2</mark> 4
′	Specifications 5		Layout	
	7.1 Absolute Maximum Ratings		11.1 Layout Guidelines	
	7.2 Handling Ratings		11.2 Layout Example	
	7.3 Recommended Operating Conditions	12	Device and Documentation Support	
	7.4 Thermal Information		12.1 Related Links	
	7.5 3V Electrical Characteristics		12.2 Trademarks	
	7.6 5V Electrical Characteristics		12.3 Electrostatic Discharge Caution	
	7.7 ±5V Electrical Characteristics		12.4 Glossary	
_	7.8 Typical Performance Characteristics	13	Mechanical, Packaging, and Orderable	
8	Detailed Description	13	Information	26
	8.1 Overview			

#### 4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

C	hanges from Revision P (March 2013) to Revision Q	Page
•	Added, revised, or updated the following sections: Device Information Table, Application and Implementation; Powe Supply Recommendations; Device and Documentation Support; Mechanical, Packaging, and Ordering Information	
•	Changed "Junction Temperature Range" to "Operating Temperature Range"	5
•	Deleted T <sub>J</sub> = 25°C for Electrical Characteristics tables.	6
•	Changed from "R <sub>L</sub> " to "Rf"	6
<u>•</u>	Deleted T <sub>J</sub> = 25°C for Typical Performance Characteristics	12
C	hanges from Revision O (March 2013) to Revision P	Page
•	Changed layout of National Data Sheet to TI format	1

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#### 5 Description (continued)

Careful attention has been paid to ensure device stability under all operating voltages and modes. The result is a very well behaved frequency response characteristic (0.1dB gain flatness up the 12 MHz under 150  $\Omega$  load and  $A_V = +2$ ) with minimal peaking (typically 2dB maximum) for any gain setting and under both heavy and light loads. This along with fast settling time (68ns) and low distortion allows the device to operate well in an ADC buffer as well as high frequency filter applications.

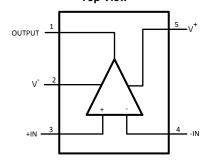
This device family offers professional quality video performance with low DG (0.01%) and DP (0.01°) characteristics. Differential Gain and Differential Phase characteristics are also well maintained under heavy loads (150  $\Omega$ ) and throughout the output voltage range. The LMH664X family is offered in single (LMH6642), dual (LMH6643), and guad (LMH6644) options.

Product Folder Links: LMH6642 LMH6643 LMH6644

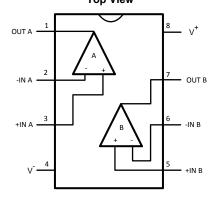
# TEXAS INSTRUMENTS

#### 6 Pin Configuration and Functions

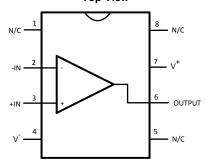
#### 5-Pin SOT-23 (LMH6642) Package DBV05A Top View



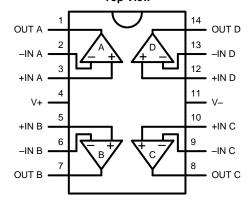
8-Pin SOIC and VSSOP (LMH6643) Package DGK08A Top View



#### 8-Pin SOIC (LMH6642) Package D08A Top View



#### 14-Pin SOIC and 14-Pin TSSOP (LMH6644) Package D14A, PW14A Top View



#### **Pin Functions**

		PIN				
	LMH	6642	LMH6643	LMH6644	I/O	DESCRIPTION
NAME	DBV05A	D08A	DGK08A	D14A and PW14A	.,,	DESCRIPTION
-IN	4	2			I	Inverting Input
+IN	3	3			I	Non-inverting Input
-IN A			2	2	I	ChA Inverting Input
+IN A			3	3	I	ChA Non-inverting Input
-IN B			6	6	I	ChB Inverting Input
+IN B			5	5	I	ChB Non-inverting Input
-IN C				9	I	ChC Inverting Input
+IN C				10	I	ChC Non-inverting Input
-IN D				13	I	ChD Inverting Input
+IN D				12	1	ChD Non-inverting Input
N/C		1,5,8			_	No connection
OUT A			1	1	0	ChA Output
OUT B			7	7	0	ChB Output
OUT C				8	0	ChC Output
OUT D				14	0	ChD Output
OUTPUT	1	6			0	Output
V-	2	4	4	11	I	Negative Supply
V <sup>+</sup>	5	7	8	4	I	Positive Supply

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#### 7 Specifications

#### 7.1 Absolute Maximum Ratings<sup>(1)(2)</sup>

over operating free-air temperature range (unless otherwise noted)

		MIN MAX	UNIT
V <sub>IN</sub> Differential		±2.5	V
Output Short Circuit Duration		See (3) and (4)	
Supply Voltage (V <sup>+</sup> - V <sup>-</sup> )		13.5	V
Voltage at Input/Output pins		V <sup>+</sup> +0.8 V <sup>-</sup> -0.8	V
Input Current		±10	mA
Junction Temperature <sup>(5)</sup>		+150	°C
Outdoor lefensetter	Infrared or Convection Reflow (20 sec)	235	°C
Soldering Information	Wave Soldering Lead Temp.(10 sec)	See (3) and (4)  13.5  V+ +0.8  V0.8  ±10  +150  Reflow (20 sec)  235	°C

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications and the test conditions, see the Electrical Characteristics.
- (2) If Military/Aerospace specified devices are required, please contact the TI Sales Office/Distributors for availability and specifications.
- (3) Applies to both single-supply and split-supply operation. Continuous short circuit operation at elevated ambient temperature can result in exceeding the maximum allowed junction temperature of 150°C.
- (4) Output short circuit duration is infinite for V<sub>S</sub> < 6V at room temperature and below. For V<sub>S</sub> > 6V, allowable short circuit duration is 1.5ms.
- (5) The maximum power dissipation is a function of  $T_{J(MAX)}$ ,  $R_{\theta JA}$ , and  $T_A$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(MAX)} T_A)/R_{\theta JA}$ . All numbers apply for packages soldered directly onto a PC board.

#### 7.2 Handling Ratings

			MIN	MAX	UNIT
T <sub>stg</sub>	Storage temperature ra	nge	-65	+150	°C
		Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins (2)		2000	
V <sub>(ESD)</sub>	V <sub>(ESD)</sub> Electrostatic discharge <sup>(1)</sup>	Machine model (MM) <sup>(3)</sup>		200	V
	districtings	Charged device model (CDM), per JEDEC specification JESD22-C101, all pins (4)		1000	

- (1) Human body model, 1.5 k $\Omega$  in series with 100 pF. Machine Model, 0  $\Omega$  in series with 200 pF.
- 2) JEDEC document JEP155 states that 2000-V HBM allows safe manufacturing with a standard ESD control process.
- (3) JEDEC document JEP157 states that 200-V MM allows safe manufacturing with a standard ESD control process.
- (4) JEDEC document JEP157 states that 1000-V CDM allows safe manufacturing with a standard ESD control process.

#### 7.3 Recommended Operating Conditions<sup>(1)</sup>

over operating free-air temperature range (unless otherwise noted)

	MIN	MAX	UNIT
Supply Voltage (V <sup>+</sup> – V <sup>-</sup> )	2.7	12.8	V
Operating Temperature Range <sup>(2)</sup>	-40	+85	°C

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications and the test conditions, see the Electrical Characteristics.
- (2) The maximum power dissipation is a function of  $T_{J(MAX)}$ ,  $R_{\theta JA}$ , and  $T_A$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(MAX)} T_A) / R_{\theta JA}$ . All numbers apply for packages soldered directly onto a PC board.

#### 7.4 Thermal Information

		LMH	6642	LMH6643	LMH	6644	
	THERMAL METRIC <sup>(1)</sup>	DBV05A	D08A	DGK08A	D14A	PW14A	UNIT
		5 PINS	8 PINS	8 PINS	14 PINS	14 PINS	
$R_{\theta JA}$	Junction-to-ambient Thermal Resistance (2)	265	190	235	145	155	°C/W

(1) For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, SPRA953.

(2) The maximum power dissipation is a function of T<sub>J(MAX)</sub>, R<sub>θJA</sub>, and T<sub>A</sub>. The maximum allowable power dissipation at any ambient temperature is P<sub>D</sub> = (T<sub>J(MAX)</sub> - T<sub>A</sub>)/ R<sub>θJA</sub>. All numbers apply for packages soldered directly onto a PC board.

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#### 3V Electrical Characteristics

Unless otherwise specified, all limits ensured for  $V^+ = 3V$ ,  $V^- = 0V$ ,  $V_{CM} = V_O = V^+/2$ ,  $V_{ID}$  (input differential voltage) as noted (where applicable) and  $R_L = 2k\Omega$  to  $V^+/2$ .

	PARAMETER	TEST CONDITIONS		AT MPERATU EXTREME		V <sub>CM</sub> =	3V, V <sup>-</sup> = V <sub>O</sub> = V <sup>+</sup> /2 2 kΩ to \	2, V <sub>ID</sub>	UNIT
			MIN	TYP	MAX	MIN <sup>(1)</sup>	TYP <sup>(2)</sup>	MAX <sup>(1)</sup>	
BW	-3dB BW	$A_V = +1$ , $V_{OUT} = 200 \text{mV}_{PP}$				80	115		MHz
		$A_V = +2, -1, V_{OUT} = 200 \text{mV}_{PP}$					46		IVII IZ
BW <sub>0.1dB</sub>	0.1dB Gain Flatness	$A_V = +2$ , $R_L = 150\Omega$ to V+/2, Rf = 402 $\Omega$ , $V_{OUT} = 200$ m $V_{PP}$					19		MHz
PBW	Full Power Bandwidth	$A_V = +1$ , $-1dB$ , $V_{OUT} = 1V_{PP}$					40		MHz
e <sub>n</sub>	Input-Referred	f = 100kHz					17		->///\/\ <del> </del>
	Voltage Noise	f = 1kHz					48		nV/√Hz
i <sub>n</sub>	Input-Referred	f = 100kHz					0.90		ο Λ /s/Ll=
	Current Noise	f = 1kHz					3.3		pA/√Hz
THD	Total Harmonic Distortion	$f = 5MHz$ , $V_O = 2V_{PP}$ , $A_V = -1$ , $R_L = 100Ω$ to $V^+/2$					-48		dBc
DG	Differential Gain	$V_{CM} = 1V$ , NTSC, $A_V = +2$ $R_L = 150\Omega$ to $V^+/2$					0.17%		
		$R_L = 1k\Omega$ to $V^+/2$					0.03%		
DP	Differential Phase	$V_{CM} = 1V$ , NTSC, $A_V = +2$ $R_L = 150\Omega$ to $V^+/2$					0.05		deg
		$R_L = 1k\Omega$ to $V^+/2$					0.03		
CT Rej.	Cross-Talk Rejection	f = 5MHz, Receiver: $R_f = R_g = 510\Omega$ , $A_V = +2$					47		dB
T <sub>S</sub>	Settling Time	$V_{O} = 2V_{PP}, \pm 0.1\%, 8pF Load, V_{S} = 5V$					68		ns
SR	Slew Rate (3)	$A_V = -1$ , $V_I = 2V_{PP}$				90	120		V/µs
Vos	Input Offset	For LMH6642 and LMH6644			±7		±1	±5	mV
	Voltage	For LMH6643			±7		±1	±3.4	IIIV
TC V <sub>OS</sub>	Input Offset Average Drift	See <sup>(4)</sup>					±5		μV/°C
I <sub>B</sub>	Input Bias Current	See <sup>(5)</sup>			-3.25		-1.50	-2.60	μΑ
I <sub>OS</sub>	Input Offset Current				1000		20	800	nA
R <sub>IN</sub>	Common Mode Input Resistance						3		МΩ

All limits are ensured by testing or statistical analysis.

Positive current corresponds to current flowing into the device.

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Typical values represent the most likely parametric norm. Slew rate is the average of the rising and falling slew rates. (3)

Offset voltage average drift determined by dividing the change in VOS at temperature extremes by the total temperature change.



#### 3V Electrical Characteristics (continued)

Unless otherwise specified, all limits ensured for  $V^+ = 3V$ ,  $V^- = 0V$ ,  $V_{CM} = V_O = V^+/2$ ,  $V_{ID}$  (input differential voltage) as noted (where applicable) and  $R_L = 2k\Omega$  to  $V^+/2$ .

	PARAMETER	TEST CONDITIONS		AT IPERATU XTREME		V <sup>+</sup> = V <sub>CM</sub> = R <sub>L</sub> =	$\mathbf{v}_{ID}$	UNIT	
		MIN TYP M		MAX	MIN <sup>(1)</sup>	TYP <sup>(2)</sup>	MAX <sup>(1)</sup>		
C <sub>IN</sub>	Common Mode Input Capacitance						2		pF
CMVR	Input Common-	CMRR ≥ 50dB			-0.1		-0.5	-0.2	-0.2 V
	Mode Voltage Range		1.6			1.8	2.0		
CMRR	Common Mode Rejection Ratio	V <sub>CM</sub> Stepped from 0V to 1.5V				72	95		dB
A <sub>VOL</sub>	Large Signal Voltage Gain	$V_{O} = 0.5V \text{ to } 2.5V$ $R_{L} = 2k\Omega \text{ to } V^{+}/2$	75			80	96		— dB
		$V_O = 0.5V$ to 2.5V $R_L = 150\Omega$ to $V^+/2$	70			74	82		
Vo	Output Swing	$R_L = 2k\Omega$ to V <sup>+</sup> /2, $V_{ID} = 200$ mV				2.90	2.98		V
	High	$R_L = 150\Omega$ to V <sup>+</sup> /2, $V_{ID} = 200$ mV				2.80	2.93		V
	Output Swing	$R_L = 2k\Omega$ to V <sup>+</sup> /2, $V_{ID} = -200$ mV					25	75	mV
	Low	$R_L = 150\Omega$ to V <sup>+</sup> /2, $V_{ID} = -200$ mV					75	150	mv
I <sub>SC</sub>	Output Short Circuit Current	Sourcing to V <sup>+</sup> /2 V <sub>ID</sub> = 200mV <sup>(6)</sup>	35			50	95		m Λ
		Sinking to $V^+/2$ $V_{ID} = -200 \text{mV}^{(6)}$	40			55	110		mA
I <sub>OUT</sub>	Output Current	V <sub>OUT</sub> = 0.5V from either supply					±65		mA
+PSRR	Positive Power Supply Rejection Ratio	V <sup>+</sup> = 3.0V to 3.5V, V <sub>CM</sub> = 1.5V				75	85		dB
I <sub>S</sub>	Supply Current (per channel)	No Load			4.50		2.70	4.00	mA

<sup>(6)</sup> Short circuit test is a momentary test. See Note 7 under 5 V Electrical Characteristics.



#### 7.6 5V Electrical Characteristics

Unless otherwise specified, all limits ensured for  $V^+ = 5V$ ,  $V^- = 0V$ ,  $V_{CM} = V_O = V^+/2$ ,  $V_{ID}$  (input differential voltage) as noted (where applicable) and  $R_1 = 2k\Omega$  to  $V^+/2$ .

	PARAMETER	TEST CONDITIONS		EMPERA' XTREME		V <sub>CM</sub> = R <sub>L</sub> =	5V, V <sup>-</sup> = V V <sub>O</sub> = V <sup>+</sup> /2 2kΩ to V	2, V <sub>ID</sub>	UNIT
			MIN	TYP	MAX	MIN <sup>(1)</sup>	TYP <sup>(2)</sup>	MAX <sup>(1)</sup>	
BW	-3dB BW	$A_V = +1$ , $V_{OUT} = 200 \text{mV}_{PP}$				90	120		MHz
		$A_V = +2$ , $-1$ , $V_{OUT} = 200 \text{mV}_{PP}$					46		IVII IZ
BW <sub>0.1dB</sub>	0.1dB Gain Flatness	$A_V = +2$ , $R_L = 150\Omega$ to V+/2, $R_f = 402\Omega$ , $V_{OUT} = 200 \text{mV}_{PP}$					15		MHz
PBW	Full Power Bandwidth	$A_V = +1$ , $-1dB$ , $V_{OUT} = 2V_{PP}$					22		MHz
e <sub>n</sub>	Input-Referred	f = 100kHz					17		->///
	Voltage Noise	f = 1kHz					48		nV/√Hz
i <sub>n</sub>	Input-Referred	f = 100kHz					0.90		- A / /II-
	Current Noise	f = 1kHz					3.3		pA/√ <del>Hz</del>
THD	Total Harmonic Distortion	$f = 5MHz, V_O = 2V_{PP}, A_V = +2$					-60		dBc
DG	Differential Gain	NTSC, $A_V = +2$ $R_L = 150\Omega$ to $V^+/2$					0.16%		
		$R_L = 1k\Omega$ to V <sup>+</sup> /2					0.05%		
DP	Differential Phase	NTSC, $A_V = +2$ $R_L = 150\Omega$ to V <sup>+</sup> /2					0.05		deg
		$R_L = 1k\Omega$ to V <sup>+</sup> /2					0.01		uog
CT Rej.	Cross-Talk Rejection	f = 5MHz, Receiver: $R_f = R_g = 510\Omega$ , $A_V = +2$					47		dB
T <sub>S</sub>	Settling Time	$V_O = 2V_{PP}, \pm 0.1\%, 8pF Load$					68		ns
SR	Slew Rate (3)	$A_V = -1, V_I = 2V_{PP}$				95	125		V/µs
V <sub>OS</sub>	Input Offset	For LMH6642 and LMH6644			±7		±1	±5	.,
	Voltage	For LMH6643			±7		±1	±3.4	mV
TC V <sub>OS</sub>	Input Offset Average Drift	See (4)					±5		μV/°C
I <sub>B</sub>	Input Bias Current	See (5)			-3.25		-1.70	-2.60	μΑ
I <sub>OS</sub>	Input Offset Current				1000		20	800	nA
R <sub>IN</sub>	Common Mode Input Resistance						3		ΜΩ
C <sub>IN</sub>	Common Mode Input Capacitance						2		pF
CMVR	Input Common-	CMRR ≥ 50dB			-0.1		-0.5	-0.2	
	Mode Voltage Range		3.6			3.8	4.0		V
CMRR	Common Mode Rejection Ratio	V <sub>CM</sub> Stepped from 0V to 3.5V				72	95		dB
A <sub>VOL</sub>	Large Signal Voltage Gain	$V_{O} = 0.5V \text{ to } 4.50V$ $R_{L} = 2k\Omega \text{ to } V^{+}/2$	82			86	98		٩D
		$V_O = 0.5V$ to 4.25V $R_L = 150\Omega$ to $V^+/2$	72			76	82		dB

All limits are ensured by testing or statistical analysis.

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Typical values represent the most likely parametric norm. Slew rate is the average of the rising and falling slew rates.

<sup>(3)</sup> 

Offset voltage average drift determined by dividing the change in VOS at temperature extremes by the total temperature change.

<sup>(5)</sup> Positive current corresponds to current flowing into the device.



#### **5V Electrical Characteristics (continued)**

Unless otherwise specified, all limits ensured for  $V^+ = 5V$ ,  $V^- = 0V$ ,  $V_{CM} = V_O = V^+/2$ ,  $V_{ID}$  (input differential voltage) as noted (where applicable) and  $R_1 = 2k\Omega$  to V<sup>+</sup>/2.

	PARAMETER	TEST CONDITIONS		EMPERA XTREME	_	$V^{+} = 5V, V^{-} = 0V,$ $V_{CM} = V_{O} = V^{+}/2, V_{ID}$ $R_{L} = 2k\Omega \text{ to } V^{+}/2$			UNIT
			MIN	TYP	MAX	MIN <sup>(1)</sup>	TYP <sup>(2)</sup>	MAX <sup>(1)</sup>	
Vo	Output Swing	$R_L = 2k\Omega$ to V <sup>+</sup> /2, $V_{ID} = 200$ mV				4.90	4.98		
	High	$R_L = 150\Omega$ to V <sup>+</sup> /2, $V_{ID} = 200$ mV				4.65	4.90		V
	Output Swing	$R_L = 2k\Omega$ to V <sup>+</sup> /2, $V_{ID} = -200$ mV					25	100	\/
	Low	$R_L = 150\Omega$ to V <sup>+</sup> /2, $V_{ID} = -200$ mV					100		mV
I <sub>SC</sub>	Output Short Circuit Current	Sourcing to $V^{+}/2$ $V_{ID} = 200 \text{mV}^{-(6)(7)}$	40			55	115		A
		Sinking to V <sup>+</sup> /2 V <sub>ID</sub> = $-200$ mV <sup>(6)(7)</sup>	55			70	140		mA
I <sub>OUT</sub>	Output Current	V <sub>O</sub> = 0.5V from either supply					±70		mA
+PSRR	Positive Power Supply Rejection Ratio	V <sup>+</sup> = 4.0V to 6V				79	90		dB
I <sub>S</sub>	Supply Current (per channel)	No Load			5.00		2.70	4.25	mA

Short circuit test is a momentary test. See Note 7.

Output short circuit duration is infinite for  $V_S < 6V$  at room temperature and below. For  $V_S > 6V$ , allowable short circuit duration is 1.5ms.



#### 7.7 ±5V Electrical Characteristics

Unless otherwise specified, all limits ensured for  $V^+ = 5V$ ,  $V^- = -5V$ ,  $V_{CM} = V_O = 0V$ ,  $V_{ID}$  (input differential voltage) as noted (where applicable) and  $R_L = 2k\Omega$  to ground.

	PARAMETER	TEST CONDITIONS		MPERATU TREMES		V <sub>CM</sub>	5V, V <sup>-</sup> = - = V <sub>O</sub> = 0V,		UNIT
			MIN	TYP	MAX	MIN <sup>(1)</sup>	TYP <sup>(2)</sup>	MAX <sup>(1)</sup>	
BW	-3dB BW	$A_V = +1$ , $V_{OUT} = 200 \text{mV}_{PP}$				95	130		N41.1-
		$A_V = +2, -1, V_{OUT} = 200 \text{mV}_{PP}$					46		MHz
BW <sub>0.1dB</sub>	0.1dB Gain Flatness	$A_V = +2$ , $R_L = 150\Omega$ to V+/2, $R_f = 806\Omega$ , $V_{OUT} = 200 \text{mV}_{PP}$					12		MHz
PBW	Full Power Bandwidth	$A_V = +1$ , $-1dB$ , $V_{OUT} = 2V_{PP}$					24		MHz
e <sub>n</sub>	Input-Referred	f = 100kHz					17		nV/√ <del>Hz</del>
	Voltage Noise	f = 1kHz					48		ΠV/√HZ
i <sub>n</sub>	Input-Referred	f = 100kHz					0.90		- A /:/II=
	Current Noise	f = 1kHz					3.3		pA/√ <del>Hz</del>
THD	Total Harmonic Distortion	$f = 5MHz, V_O = 2V_{PP}, A_V = +2$					-62		dBc
DG	Differential Gain	NTSC, $A_V = +2$ $R_L = 150\Omega$ to $V^+/2$					0.15%		
		$R_L = 1k\Omega$ to $V^+/2$					0.01%		
DP	Differential Phase	NTSC, $A_V = +2$ $R_L = 150\Omega$ to V <sup>+</sup> /2					0.04		deg
		$R_L = 1k\Omega$ to $V^+/2$					0.01		Ü
CT Rej.	Cross-Talk Rejection	f = 5MHz, Receiver: $R_f = R_g = 510\Omega$ , $A_V = +2$					47		dB
T <sub>S</sub>	Settling Time	$V_{O} = 2V_{PP}, \pm 0.1\%, 8pF Load, V_{S} = 5V$					68		ns
SR	Slew Rate (3)	$A_V = -1$ , $V_I = 2V_{PP}$				100	135		V/µs
Vos	Input Offset	For LMH6642 and LMH6644			±7		±1	±5	m\/
	Voltage	For LMH6643			±7		±1	±3.4	mV
TC V <sub>OS</sub>	Input Offset Average Drift	See (4)					±5		μV/°C
I <sub>B</sub>	Input Bias Current	See (5)			-3.25		-1.60	-2.60	μΑ
Ios	Input Offset Current				1000		20	800	nA
R <sub>IN</sub>	Common Mode Input Resistance						3		ΜΩ
C <sub>IN</sub>	Common Mode Input Capacitance						2		pF
CMVR	Input Common-	CMRR ≥ 50dB			<b>-</b> 5.1		-5.5	-5.2	
	Mode Voltage Range		3.6			3.8	4.0		V
CMRR	Common Mode Rejection Ratio	V <sub>CM</sub> Stepped from −5V to 3.5V				74	95		dB

- (1) All limits are ensured by testing or statistical analysis.
- (2) Typical values represent the most likely parametric norm.
- (3) Slew rate is the average of the rising and falling slew rates.
- (4) Offset voltage average drift determined by dividing the change in V<sub>OS</sub> at temperature extremes by the total temperature change.

(5) Positive current corresponds to current flowing into the device.

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#### ±5V Electrical Characteristics (continued)

Unless otherwise specified, all limits ensured for  $V^+ = 5V$ ,  $V^- = -5V$ ,  $V_{CM} = V_O = 0V$ ,  $V_{ID}$  (input differential voltage) as noted (where applicable) and  $R_L = 2k\Omega$  to ground.

	PARAMETER	TEST CONDITIONS		MPERATU TREMES		V <sup>+</sup> = V <sub>CM</sub>	,	UNIT	
			MIN	TYP	MAX	MIN <sup>(1)</sup>	TYP <sup>(2)</sup>	MAX <sup>(1)</sup>	
A <sub>VOL</sub>	Large Signal Voltage Gain	$V_O = -4.5V$ to 4.5V, $R_L = 2k\Omega$	84			88	96		dВ
		$V_O = -4.0V \text{ to } 4.0V,$ $R_L = 150\Omega$	74			78	82		uБ
Vo	Output Swing	$R_L = 2k\Omega$ , $V_{ID} = 200mV$				4.90	4.96		V
	High	$R_L = 150\Omega, V_{ID} = 200mV$				4.65	4.80		V
	Output Swing	$R_L = 2k\Omega$ , $V_{ID} = -200$ mV					-4.96	-4.90	V
	Low	$R_L = 150\Omega, V_{ID} = -200 \text{mV}$					-4.80	-4.65	V
I <sub>SC</sub>	Output Short Circuit Current	Sourcing to Ground V <sub>ID</sub> = 200mV <sup>(6)(7)</sup>	35			60	115		A
		Sinking to Ground $V_{ID} = -200 \text{mV}^{(6)(7)}$	65			85	145		mA
I <sub>OUT</sub>	Output Current	V <sub>O</sub> = 0.5V from either supply				±75			mA
PSRR	Power Supply Rejection Ratio	$(V^+, V^-) = (4.5V, -4.5V)$ to $(5.5V, -5.5V)$				78	90		dB
I <sub>S</sub>	Supply Current (per channel)	No Load			5.50		2.70	4.50	mA

<sup>(6)</sup> Short circuit test is a momentary test. See <sup>(7)</sup>.

<sup>(7)</sup> Output short circuit duration is infinite for  $V_S < 6V$  at room temperature and below. For  $V_S > 6V$ , allowable short circuit duration is 1.5ms.

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#### 7.8 Typical Performance Characteristics

 $V^+ = +5$ ,  $V^- = -5V$ ,  $R_F = R_L = 2 \text{ k}\Omega$ . Unless otherwise specified.

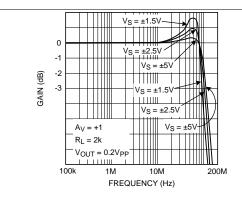
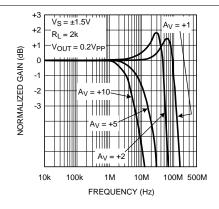


Figure 1. Closed Loop Frequency Response for Various Supplies

Figure 2. Closed Loop Gain vs. Frequency for Various Gain



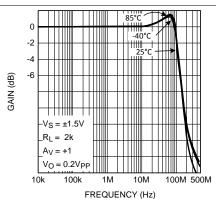
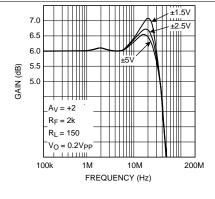


Figure 3. Closed Loop Gain vs. Frequency for Various Gain

Figure 4. Closed Loop Frequency Response for Various Temperature



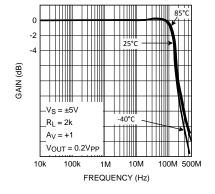


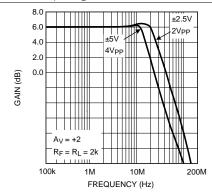
Figure 5. Closed Loop Gain vs. Frequency for Various Supplies

Figure 6. Closed Loop Frequency Response for Various Temperature



#### **Typical Performance Characteristics (continued)**

 $V^+ = +5$ ,  $V^- = -5V$ ,  $R_F = R_L = 2 \text{ k}\Omega$ . Unless otherwise specified.



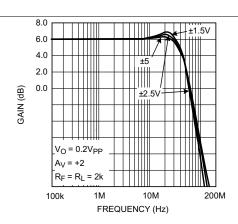
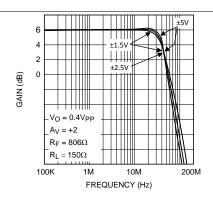


Figure 7. Large Signal Frequency Response

Figure 8. Closed Loop Small Signal Frequency Response for Various Supplies



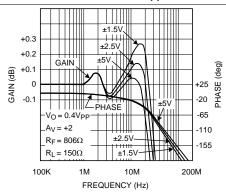
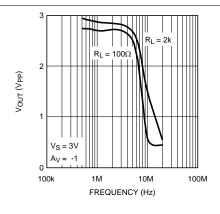


Figure 9. Closed Loop Frequency Response for Various Supplies

Figure 10. ±0.1dB Gain Flatness for Various Supplies



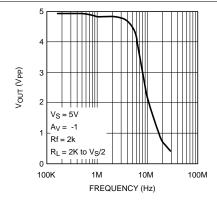


Figure 11.  $V_{OUT}$  ( $V_{PP}$ ) for THD < 0.5%

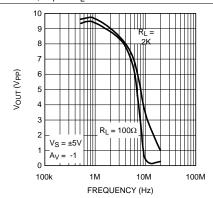
Figure 12.  $V_{OUT}$  ( $V_{PP}$ ) for THD < 0.5%

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#### **Typical Performance Characteristics (continued)**

 $V^+ = +5$ ,  $V^- = -5V$ ,  $R_F = R_L = 2 \text{ k}\Omega$ . Unless otherwise specified.



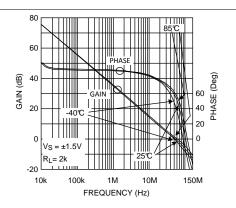
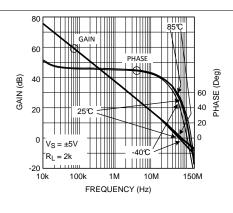


Figure 13.  $V_{OUT}$  ( $V_{PP}$ ) for THD < 0.5%

Figure 14. Open Loop Gain/Phase for Various Temperature



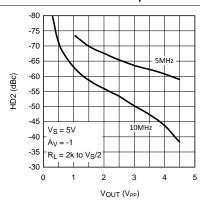
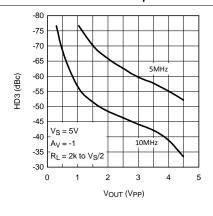


Figure 15. Open Loop Gain/Phase for Various Temperature

Figure 16. HD2 (dBc) vs. Output Swing



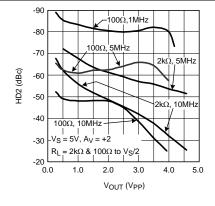


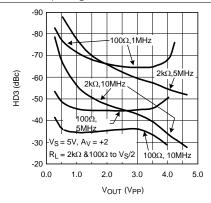
Figure 17. HD3 (dBc) vs. Output Swing

Figure 18. HD2 vs. Output Swing



#### **Typical Performance Characteristics (continued)**

 $V^+ = +5$ ,  $V^- = -5V$ ,  $R_F = R_L = 2 \text{ k}\Omega$ . Unless otherwise specified.



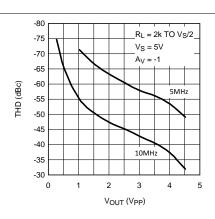


Figure 19. HD3 vs. Output Swing

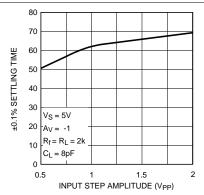


Figure 20. THD (dBc) vs. Output Swing

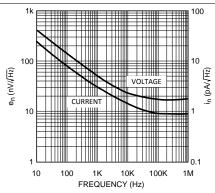


Figure 21. Settling Time vs. Input Step Amplitude (Output Slew and Settle Time)

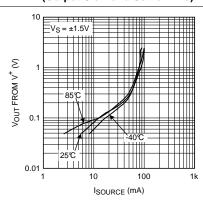


Figure 22. Input Noise vs. Frequency

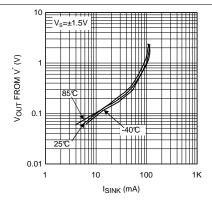


Figure 23. V<sub>OUT</sub> from V<sup>+</sup> vs. I<sub>SOURCE</sub>

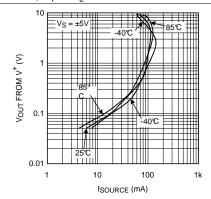
Figure 24.  $V_{OUT}$  from  $V^-$  vs.  $I_{SINK}$ 

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#### **Typical Performance Characteristics (continued)**

 $V^+ = +5$ ,  $V^- = -5V$ ,  $R_F = R_L = 2 \text{ k}\Omega$ . Unless otherwise specified.



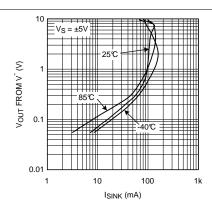


Figure 25. V<sub>OUT</sub> from V<sup>+</sup> vs. I<sub>SOURCE</sub>

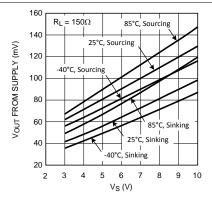


Figure 26. V<sub>OUT</sub> from V<sup>-</sup> vs. I<sub>SINK</sub>

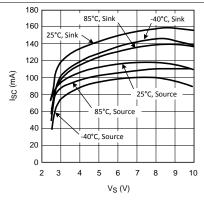


Figure 27. Swing vs. V<sub>S</sub>

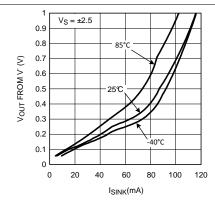


Figure 28. Short Circuit Current (to V<sub>S</sub>/2) vs. V<sub>S</sub>

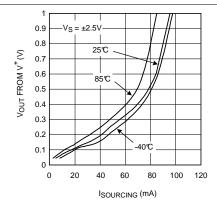


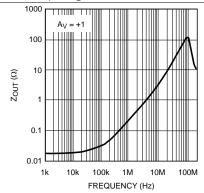
Figure 29. Output Sinking Saturation Voltage vs.  $I_{OUT}$ 

Figure 30. Output Sourcing Saturation Voltage vs. I<sub>OUT</sub>



#### **Typical Performance Characteristics (continued)**

 $V^+ = +5$ ,  $V^- = -5V$ ,  $R_F = R_L = 2 \text{ k}\Omega$ . Unless otherwise specified.



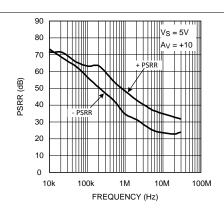
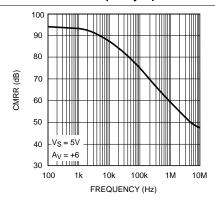


Figure 31. Closed Loop Output Impedance vs. Frequency A<sub>V</sub> = +1

Figure 32. PSRR vs. Frequency



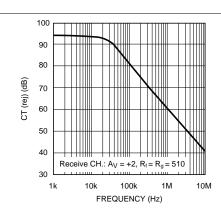
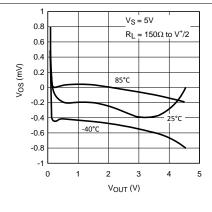


Figure 33. CMRR vs. Frequency

Figure 34. Crosstalk Rejection vs. Frequency (Output to Output)



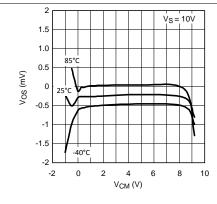


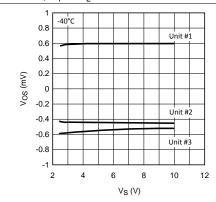
Figure 35. V<sub>OS</sub> vs. V<sub>OUT</sub> (Typical Unit)

Figure 36.  $V_{OS}$  vs.  $V_{CM}$  (Typical Unit)

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#### **Typical Performance Characteristics (continued)**

 $V^+ = +5$ ,  $V^- = -5V$ ,  $R_F = R_L = 2 \text{ k}\Omega$ . Unless otherwise specified.



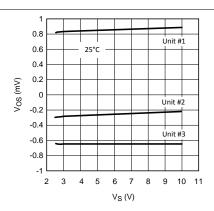


Figure 37. V<sub>OS</sub> vs. V<sub>S</sub> (for 3 Representative Units)

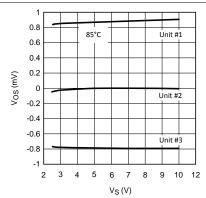


Figure 38. V<sub>OS</sub> vs. V<sub>S</sub> (for 3 Representative Units)

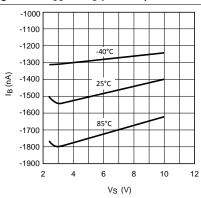


Figure 39. V<sub>OS</sub> vs. V<sub>S</sub> (for 3 Representative Units)

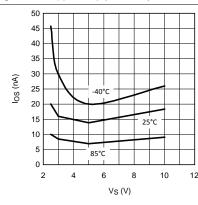


Figure 40. I<sub>B</sub> vs. V<sub>S</sub>

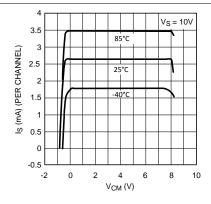


Figure 41. I<sub>OS</sub> vs. V<sub>S</sub>

Figure 42. I<sub>S</sub> vs.  $V_{CM}$ 

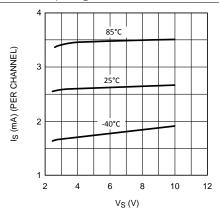
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#### **Typical Performance Characteristics (continued)**

 $V^+ = +5$ ,  $V^- = -5V$ ,  $R_F = R_L = 2 \text{ k}\Omega$ . Unless otherwise specified.



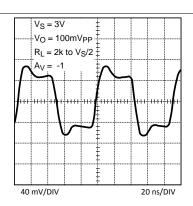
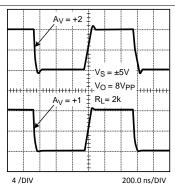


Figure 43. I<sub>S</sub> vs. V<sub>S</sub>





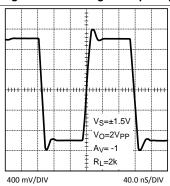
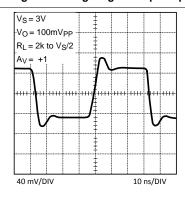


Figure 45. Large Signal Step Response

Figure 46. Large Signal Step Response



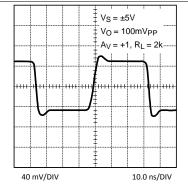


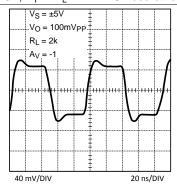
Figure 47. Small Signal Step Response

Figure 48. Small Signal Step Response

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#### **Typical Performance Characteristics (continued)**

 $V^+ = +5$ ,  $V^- = -5V$ ,  $R_F = R_L = 2 k\Omega$ . Unless otherwise specified.



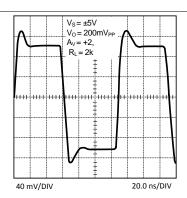


Figure 49. Small Signal Step Response

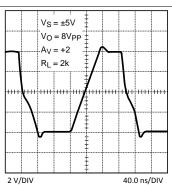


Figure 50. Small Signal Step Response

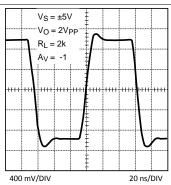


Figure 51. Large Signal Step Response



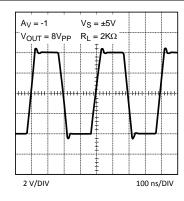


Figure 53. Large Signal Step Response

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#### 8 Detailed Description

#### 8.1 Overview

The LMH664X family is based on proprietary VIP10 dielectrically isolated bipolar process. This device family architecture features the following:

- Complimentary bipolar devices with exceptionally high f<sub>t</sub> (~8 GHz) even under low supply voltage (2.7 V) and low bias current.
- A class A-B "turn-around" stage with improved noise, offset, and reduced power dissipation compared to similar speed devices (patent pending).
- Common Emitter push-push output stage capable of 75 mA output current (at 0.5 V from the supply rails) while consuming only 2.7 mA of total supply current per channel. This architecture allows output to reach within mV of either supply rail.
- Consistent performance over the entire operating supply voltage range with little variation for the most important specifications (for example, BW, SR, I<sub>OLIT</sub>, and so forth)
- Significant power saving (~40%) compared to competitive devices on the market with similar performance.

#### 8.2 Functional Block Diagram

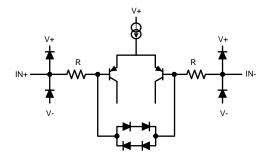


Figure 54. Input Equivalent Circuit

#### 8.3 Feature Description

The LMH664X family is a drop-in replacement for the AD805X family of high speed Op Amps in most applications. In addition, the LMH664X will typically save about 40% on power dissipation, due to lower supply current, when compared to competition. All AD805X family's specified parameters are included in the list of LMH664X ensured specifications in order to ensure equal or better level of performance. However, as in most high performance parts, due to subtleties of applications, it is strongly recommended that the performance of the part to be evaluated is tested under actual operating conditions to ensure full compliance to all specifications.

#### 8.4 Device Functional Modes

With 3-V supplies and a common mode input voltage range that extends 0.5 V below V $^-$ , the LMH664X find applications in low voltage/low power applications. Even with 3-V supplies, the -3dB BW (@  $A_V = +1$ ) is typically 115 MHz with a tested limit of 80 MHz. Production testing guarantees that process variations will not compromise speed. High frequency response is exceptionally stable, confining the typical -3dB BW over the industrial temperature range to  $\pm 2.5\%$ .

As seen in *Typical Performance Characteristics*, the LMH664X output current capability (~75 mA) is enhanced compared to AD805X. This enhancement increases the output load range, adding to the LMH664X's versatility. Since LMH664X is capable of high output current, device junction temperature should not to exceed the Absolute Maximum Ratings.

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#### Application and Implementation

#### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

#### 9.1 Application Information

This device family was designed to avoid output phase reversal. With input overdrive, the output is kept near supply rail (or as closed to it as mandated by the closed loop gain setting and the input voltage). See Figure 56.

However, if the input voltage range of -0.5 V to 1 V from V<sup>+</sup> is exceeded by more than a diode drop, the internal ESD protection diodes will start to conduct. The current in the diodes should be kept at or below 10 mA.

Output overdrive recovery time is less than 100 ns as can be seen in Figure 57.

#### 9.2 Typical Application

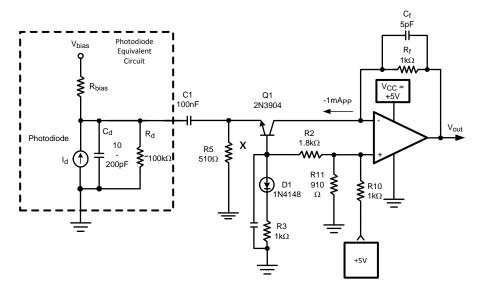


Figure 55. Single Supply Photodiode I-V Converter

#### 9.2.1 Design Requirements

The circuit shown in Figure 55 is used to amplify the current from a photodiode into a voltage output. In this circuit, the emphasis is on achieving high bandwidth and the transimpedance gain setting is kept relatively low. Because of its high slew rate limit and high speed, the LMH664X family lends itself well to such an application. This circuit achieves approximately 1V/mA of transimpedance gain and capable of handling up to 1mApp from the photodiode. Q1, in a common base configuration, isolates the high capacitance of the photodiode (Cd) from the Op Amp input in order to maximize speed. Input is AC coupled through C1 to ease biasing and allow single supply operation. With 5-V single supply, the device input/output is shifted to near half supply using a voltage divider from VCC. Note that Q1 collector does not have any voltage swing and the Miller effect is minimized. D1, tied to Q1 base, is for temperature compensation of Q1's bias point. Q1 collector current was set to be large enough to handle the peak-to-peak photodiode excitation and not too large to shift the U1 output too far from mid-supply.

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#### **Typical Application (continued)**

#### 9.2.1.1 Input and Output Topology

All input / output pins are protected against excessive voltages by ESD diodes connected to V<sup>+</sup> and V<sup>-</sup> rails (see Figure 54). These diodes start conducting when the input / output pin voltage approaches  $1V_{be}$  beyond V<sup>+</sup> or V<sup>-</sup> to protect against over voltage. These diodes are normally reverse biased. Further protection of the inputs is provided by the two resistors (R in Figure 54), in conjunction with the string of anti-parallel diodes connected between both bases of the input stage. The combination of these resistors and diodes reduces excessive differential input voltages approaching  $2V_{be}$ . This occurs most commonly when the device is used as a comparator (or with little or no feedback) and the device inputs no longer follow each other. In such a case, the diodes may conduct. As a consequence, input current increases and the differential input voltage is clamped. It is important to make sure that the subsequent current flow through the device input pins does not violate the Absolute Maximum Ratings of the device. To limit the current through this protection circuit, extra series resistors can be placed. Together with the built-in series resistors of several hundred ohms, these external resistors can limit the input current to a safe number (that is, less than 10mA). Be aware that these input series resistors may impact the switching speed of the device and could slow down the device.

#### 9.2.1.2 Single Supply, Low Power Photodiode Amplifier

The circuit shown in Figure 55 is used to amplify the current from a photodiode into a voltage output. In this circuit, the emphasis is on achieving high bandwidth and the transimpedance gain setting is kept relatively low. Because of its high slew rate limit and high speed, the LMH664X family lends itself well to such an application.

This circuit achieves approximately 1V/mA of transimpedance gain and capable of handling up to  $1mA_{pp}$  from the photodiode. Q1, in a common base configuration, isolates the high capacitance of the photodiode ( $C_d$ ) from the Op Amp input in order to maximize speed. Input is AC coupled through C1 to ease biasing and allow single supply operation. With 5V single supply, the device input/output is shifted to near half supply using a voltage divider from  $V_{CC}$ . Note that Q1 collector does not have any voltage swing and the Miller effect is minimized. D1, tied to Q1 base, is for temperature compensation of Q1's bias point. Q1 collector current was set to be large enough to handle the peak-to-peak photodiode excitation and not too large to shift the U1 output too far from mid-supply.

No matter how low an  $R_f$  is selected, there is a need for  $C_f$  in order to stabilize the circuit. The reason for this is that the Op Amp input capacitance and Q1 equivalent collector capacitance together  $(C_{IN})$  will cause additional phase shift to the signal fed back to the inverting node.  $C_f$  will function as a zero in the feedback path counteracting the effect of the  $C_{IN}$  and acting to stabilized the circuit. By proper selection of  $C_f$  such that the Op Amp open loop gain is equal to the inverse of the feedback factor at that frequency, the response is optimized with a theoretical  $45^{\circ}$  phase margin.

$$C_F = \text{ } \sim \text{ } SQRT \left[ (C_{IN})/(2\pi \cdot GBWP \cdot R_F) \right]$$

where

GBWP is the Gain Bandwidth Product of the Op Amp

Optimized as such, the I-V converter will have a theoretical pole, fp, at:

$$f_P = SQRT \left[ GBWP/(2\pi R_F \cdot C_{IN}) \right]$$
 (2)

With Op Amp input capacitance of 3pF and an estimate for Q1 output capacitance of about 3pF as well,  $C_{IN} = 6$  pF. From the typical performance plots, LMH6642/6643 family GBWP is approximately 57 MHz. Therefore, with  $R_f = 1k$ , from Equation 1 and Equation 2:

$$C_f = \sim 4.1 \text{ pF and } f_0 = 39 \text{ MHz}$$
 (3)

For this example, optimum  $C_f$  was empirically determined to be around 5 pF. This time domain response is shown in Figure 58 below showing about 9 ns rise/fall times, corresponding to about 39 MHz for  $f_p$ . The overall supply current from the +5 V supply is around 5 mA with no load.

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(1)



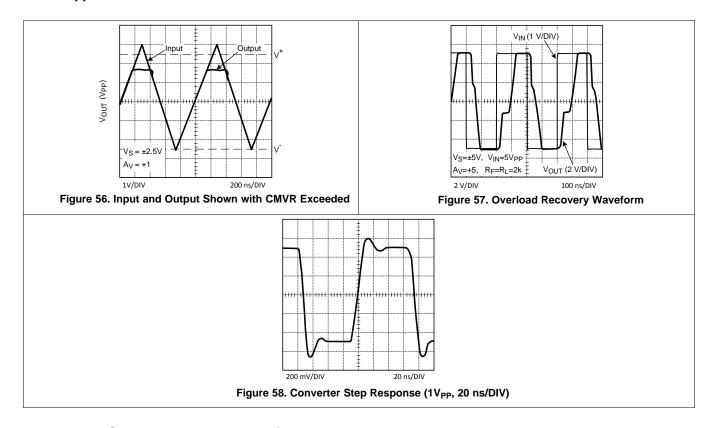
#### Typical Application (continued)

#### 9.2.2 Detailed Design Procedure

No matter how low an Rf is selected, there is a need for C<sub>f</sub> in order to stabilize the circuit. The reason for this is that the Op Amp input capacitance and Q1 equivalent collector capacitance together (C<sub>IN</sub>) will cause additional phase shift to the signal fed back to the inverting node. Cf will function as a zero in the feedback path counteracting the effect of the C<sub>IN</sub> and acting to stabilized the circuit. By proper selection of C<sub>f</sub> such that the Op Amp open loop gain is equal to the inverse of the feedback factor at that frequency, the response is optimized with a theoretical 45° phase margin where GBWP is the Gain Bandwidth Product of the Op Amp, Optimized as such, the I-V converter will have a theoretical pole, fp, at: (2) With Op Amp input capacitance of 3pF and an estimate for Q1 output capacitance of about 3pF as well,  $\hat{C}_{IN}$  = 6 pF. From the typical performance plots, LMH6642/6643 family GBWP is approximately 57 MHz. Therefore, with Rf = 1k, from Equation 2 and Equation 3:  $C_f = \sim 4.1 \text{ pF}$  and fp = 39 MHz.

Single Supply Photodiode I-V Converter For this example, optimum C<sub>f</sub> was empirically determined to be around 5 pF. This time domain response is shown in Figure 58 showing about 9 ns rise/fall times, corresponding to about 39 MHz for fp. The overall supply current from the +5 V supply is around 5 mA with no load.

#### 9.2.3 Application Curves



## 10 Power Supply Recommendations

The LMH664x device family can operate off a single supply or with dual supplies. The input CM capability of the parts (CMVR) extends all the way down to the V- rail to simplify single supply applications. Supplies should be decoupled with low inductance, often ceramic, capacitors to ground less than 0.5 inches from the device pins. The use of ground plane is recommended, and as in most high speed devices, it is advisable to remove ground plane close to device sensitive pins such as the inputs.

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LMH730131



#### 11 Layout

#### 11.1 Layout Guidelines

Generally, a good high frequency layout will keep power supply and ground traces away from the inverting input and output pins. Parasitic capacitances on these nodes to ground will cause frequency response peaking and possible circuit oscillations (see Application Note OA-15, "Frequent Faux Pas in Applying Wideband Current Feedback Amplifiers", SNOA367, for more information). Texas Instruments suggests the following evaluation boards as a guide for high frequency layout and as an aid in device testing and characterization:

DEVICE	PACKAGE	EVALUATION BOARD PN
LMH6642MF	5-Pin SOT-23	LMH730216
LMH6642MA	8-Pin SOIC	LMH730227
LMH6643MA	8-Pin SOIC	LMH730036
LMH6643MM	8-Pin VSSOP	LMH730123
LMH6644MA	14-Pin SOIC	LMH730231

14-Pin TSSOP

**Table 1. Printed Circuit Board Layout And Component Values** 

Another important parameter in working with high speed/high performance amplifiers, is the component values selection. Choosing external resistors that are large in value will effect the closed loop behavior of the stage because of the interaction of these resistors with parasitic capacitances. These capacitors could be inherent to the device or a by-product of the board layout and component placement. Either way, keeping the resistor values lower, will diminish this interaction to a large extent. On the other hand, choosing very low value resistors could load down nodes and will contribute to higher overall power dissipation.

#### 11.2 Layout Example

LMH6644MT

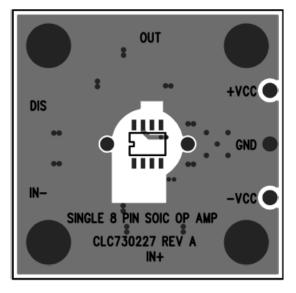


Figure 59. LMH6642/LMH6643/LMH6644 Layer 1

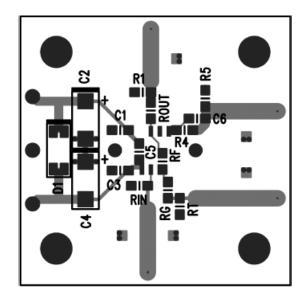


Figure 60. LMH6642/LMH6643/LMH6644 Layer 2



#### 12 Device and Documentation Support

#### 12.1 Related Links

The table below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to sample or buy.

Table 2. Related Links

PARTS	PRODUCT FOLDER	SAMPLE & BUY	TECHNICAL DOCUMENTS	TOOLS & SOFTWARE	SUPPORT & COMMUNITY
LMH6642	Click here	Click here	Click here	Click here	Click here
LMH6643	Click here	Click here	Click here	Click here	Click here
LMH6644	Click here	Click here	Click here	Click here	Click here

#### 12.2 Trademarks

All trademarks are the property of their respective owners.

#### 12.3 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

#### 12.4 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

#### 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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#### **PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead finish/ Ball material	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
LMH6642MA/NOPB	ACTIVE	SOIC	D	8	95	RoHS & Green	SN	Level-1-260C-UNLIM	-40 to 85	LMH66 42MA	Samples
LMH6642MAX/NOPB	ACTIVE	SOIC	D	8	2500	RoHS & Green	SN	Level-1-260C-UNLIM	-40 to 85	LMH66 42MA	Samples
LMH6642MF	LIFEBUY	SOT-23	DBV	5	1000	Non-RoHS & Green	Call TI	Level-1-260C-UNLIM	-40 to 85	A64A	
LMH6642MF/NOPB	ACTIVE	SOT-23	DBV	5	1000	RoHS & Green	SN	Level-1-260C-UNLIM	-40 to 85	A64A	Samples
LMH6642MFX/NOPB	ACTIVE	SOT-23	DBV	5	3000	RoHS & Green	SN	Level-1-260C-UNLIM	-40 to 85	A64A	Samples
LMH6643MA	LIFEBUY	SOIC	D	8	95	Non-RoHS & Green	Call TI	Level-1-235C-UNLIM	-40 to 85	LMH66 43MA	
LMH6643MA/NOPB	ACTIVE	SOIC	D	8	95	RoHS & Green	SN	Level-1-260C-UNLIM	-40 to 85	LMH66 43MA	Samples
LMH6643MAX/NOPB	ACTIVE	SOIC	D	8	2500	RoHS & Green	SN	Level-1-260C-UNLIM	-40 to 85	LMH66 43MA	Samples
LMH6643MM	LIFEBUY	VSSOP	DGK	8	1000	Non-RoHS & Green	Call TI	Level-1-260C-UNLIM	-40 to 85	A65A	
LMH6643MM/NOPB	ACTIVE	VSSOP	DGK	8	1000	RoHS & Green	SN	Level-1-260C-UNLIM	-40 to 85	A65A	Samples
LMH6643MMX/NOPB	ACTIVE	VSSOP	DGK	8	3500	RoHS & Green	SN	Level-1-260C-UNLIM	-40 to 85	A65A	Samples
LMH6644MA/NOPB	ACTIVE	SOIC	D	14	55	RoHS & Green	SN	Level-1-260C-UNLIM	-40 to 85	LMH6644MA	Samples
LMH6644MAX/NOPB	ACTIVE	SOIC	D	14	2500	RoHS & Green	SN	Level-1-260C-UNLIM	-40 to 85	LMH6644MA	Samples
LMH6644MT/NOPB	ACTIVE	TSSOP	PW	14	94	RoHS & Green	NIPDAU   SN	Level-1-260C-UNLIM	-40 to 85	LMH66 44MT	Samples
LMH6644MTX/NOPB	ACTIVE	TSSOP	PW	14	2500	RoHS & Green	NIPDAU   SN	Level-1-260C-UNLIM	-40 to 85	LMH66 44MT	Samples

<sup>&</sup>lt;sup>(1)</sup> The marketing status values are defined as follows: **ACTIVE:** Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design. **PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.



#### PACKAGE OPTION ADDENDUM

www.ti.com 18-Oct-2023

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead finish/Ball material Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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#### TAPE AND REEL INFORMATION



# TAPE DIMENSIONS + K0 - P1 - B0 W Cavity - A0 -

A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LMH6642MAX/NOPB	SOIC	D	8	2500	330.0	12.4	6.5	5.4	2.0	8.0	12.0	Q1
LMH6642MF	SOT-23	DBV	5	1000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMH6642MF/NOPB	SOT-23	DBV	5	1000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMH6642MFX/NOPB	SOT-23	DBV	5	3000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMH6643MAX/NOPB	SOIC	D	8	2500	330.0	12.4	6.5	5.4	2.0	8.0	12.0	Q1
LMH6643MM	VSSOP	DGK	8	1000	178.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
LMH6643MM/NOPB	VSSOP	DGK	8	1000	178.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
LMH6643MMX/NOPB	VSSOP	DGK	8	3500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
LMH6644MAX/NOPB	SOIC	D	14	2500	330.0	16.4	6.5	9.35	2.3	8.0	16.0	Q1
LMH6644MTX/NOPB	TSSOP	PW	14	2500	330.0	12.4	6.95	5.6	1.6	8.0	12.0	Q1



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\*All dimensions are nominal

Till difficilisions are norminal							
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LMH6642MAX/NOPB	SOIC	D	8	2500	367.0	367.0	35.0
LMH6642MF	SOT-23	DBV	5	1000	208.0	191.0	35.0
LMH6642MF/NOPB	SOT-23	DBV	5	1000	208.0	191.0	35.0
LMH6642MFX/NOPB	SOT-23	DBV	5	3000	208.0	191.0	35.0
LMH6643MAX/NOPB	SOIC	D	8	2500	367.0	367.0	35.0
LMH6643MM	VSSOP	DGK	8	1000	208.0	191.0	35.0
LMH6643MM/NOPB	VSSOP	DGK	8	1000	208.0	191.0	35.0
LMH6643MMX/NOPB	VSSOP	DGK	8	3500	367.0	367.0	35.0
LMH6644MAX/NOPB	SOIC	D	14	2500	367.0	367.0	35.0
LMH6644MTX/NOPB	TSSOP	PW	14	2500	367.0	367.0	35.0

## **PACKAGE MATERIALS INFORMATION**

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#### **TUBE**



\*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (µm)	B (mm)
LMH6642MA/NOPB	D	SOIC	8	95	495	8	4064	3.05
LMH6643MA	D	SOIC	8	95	495	8	4064	3.05
LMH6643MA	D	SOIC	8	95	495	8	4064	3.05
LMH6643MA/NOPB	D	SOIC	8	95	495	8	4064	3.05
LMH6644MA/NOPB	D	SOIC	14	55	495	8	4064	3.05
LMH6644MA/NOPB	D	SOIC	14	55	495	8	4064	3.05
LMH6644MT/NOPB	PW	TSSOP	14	94	495	8	2514.6	4.06
LMH6644MT/NOPB	PW	TSSOP	14	94	530	10.2	3600	3.5



SMALL OUTLINE TRANSISTOR



- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
  2. This drawing is subject to change without notice.
  3. Reference JEDEC MO-178.

- 4. Body dimensions do not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.25 mm per side.
- 5. Support pin may differ or may not be present.



SMALL OUTLINE TRANSISTOR



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SMALL OUTLINE TRANSISTOR



NOTES: (continued)

- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.



## D (R-PDSO-G14)

#### PLASTIC SMALL OUTLINE



- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
- Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
- E. Reference JEDEC MS-012 variation AB.



# D (R-PDSO-G14)

## PLASTIC SMALL OUTLINE



- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525 for other stencil recommendations.
- E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.



PW (R-PDSO-G14)

#### PLASTIC SMALL OUTLINE



- A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M—1994.
- B. This drawing is subject to change without notice.
  - Sody length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0,15 each side.
- Body width does not include interlead flash. Interlead flash shall not exceed 0,25 each side.
- E. Falls within JEDEC MO-153



# PW (R-PDSO-G14)

## PLASTIC SMALL OUTLINE



- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525 for other stencil recommendations.
- E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.





SMALL OUTLINE INTEGRATED CIRCUIT



- 1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
- 4. This dimension does not include interlead flash.
- 5. Reference JEDEC registration MS-012, variation AA.



SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SMALL OUTLINE INTEGRATED CIRCUIT



#### NOTES: (continued)

- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.



# DGK (S-PDSO-G8)

# PLASTIC SMALL-OUTLINE PACKAGE



- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 per end.
- Body width does not include interlead flash. Interlead flash shall not exceed 0.50 per side.
- E. Falls within JEDEC MO-187 variation AA, except interlead flash.



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