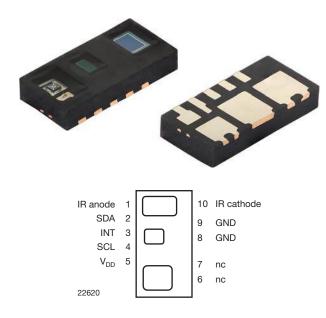
# High Resolution Digital Biosensor for Wearable Applications With I<sup>2</sup>C Interface



## DESCRIPTION

The VCNL4020C is a fully integrated biosensor and ambient light sensor. Fully integrated means that the infrared emitter is included in the package. It has 16 bit resolution. It includes a signal processing IC and features standard I<sup>2</sup>C communication interface. It features an interrupt function.

## APPLICATIONS

- Wearables
- Health monitoring
- Pulse oximetry

# FEATURES

- Package type: surface-mount
- Package form: SMD
- Dimensions (L x W x H in mm): 4.90 x 2.40 x 0.83
- Integrated modules: infrared emitter (IRED), ambient light sensor (ALS), photo diode (PD), and signal conditioning IC
- Interrupt function
- Supply voltage range V<sub>DD</sub>: 2.5 V to 3.6 V
- Supply voltage range IR anode: 2.5 V to 5 V
- Communication via I<sup>2</sup>C interface
- I<sup>2</sup>C bus H-level range: 1.7 V to 5 V
- Floor life: 72 h, MSL 4, according to J-STD-020
- Low stand by current consumption: 1.5 μA
- Material categorization: for definitions of compliance please see <u>www.vishay.com/doc?99912</u>

### **OPTICAL BIOSENSORS FUNCTION**

- Built-in infrared emitter and broader sensitivity photodiode allows to also work with green and red LEDs
- 16 bit effective resolution ensures excellent cross talk immunity
- Programmable LED drive current from 10 mA to 200 mA in 10 mA steps
- Excellent ambient light suppression through signal modulation

### **AMBIENT LIGHT FUNCTION**

- Built-in ambient light photo-pin-diode with close-to-human-eye sensitivity
- 16 bit dynamic range from 0.25 lx to 16 klx
- 100 Hz and 120 Hz flicker noise rejection

PRODUCT	SUMMARY						
PART NUMBER	OPERATING VOLTAGE RANGE (V)	I <sup>2</sup> C BUS VOLTAGE RANGE (V)	LED PULSE CURRENT <sup>(1)</sup> (mA)	AMBIENT LIGHT RANGE (Ix)	SPECTRAL BANDWIDTH RANGE λ <sub>0.5</sub> (nm)	OUTPUT CODE	ADC RESOLUTION BIOSENSOR / AMBIENT LIGHT SENSOR
VCNL4020C	2.5 to 3.6	1.7 to 5	10 to 200	0.25 to 16 383	550 to 970	16 bit, I <sup>2</sup> C	16 bit / 16 bit

#### Note

<sup>(1)</sup> Adjustable through I<sup>2</sup>C interface



RoHS

COMPLIANT

HALOGEN

FREE <u>GREEN</u>

(5-2008)





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ORDERING CODE	PACKAGING	VOLUME <sup>(1)</sup>	REMARKS	
VCNL4020C-GS08	Tapa and real	MOQ: 3300 pcs	4.90 mm x 2.40 mm x 0.83 mm	
VCNL4020C-GS18	Tape and reel	MOQ: 13 000 pcs	4.90 1111 x 2.40 1111 x 0.83 1111	

Note

<sup>(1)</sup> MOQ: minimum order quantity

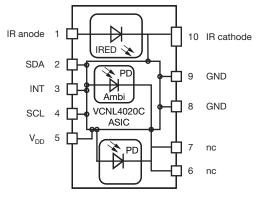
ABSOLUTE MAXIMUM F	ABSOLUTE MAXIMUM RATINGS (T <sub>amb</sub> = 25 °C, unless otherwise specified)										
PARAMETER	TEST CONDITION	SYMBOL	MIN.	MAX.	UNIT						
Supply voltage		V <sub>DD</sub>	-0.3	5.5	V						
Operation temperature range		T <sub>amb</sub>	-25	+85	°C						
Storage temperature range		T <sub>stg</sub>	-25	+85	°C						
Total power dissipation	T <sub>amb</sub> ≤ 25 °C	P <sub>tot</sub>	-	50	mW						
Junction temperature		Tj	-	100	°C						

PARAMETER	TEST CONDITION	SYMBOL	MIN.	TYP.	MAX.	UNIT
Supply voltage V <sub>DD</sub>			2.5	-	3.6	V
Supply voltage IR anode			2.5	-	5	V
I <sup>2</sup> C bus H-level range			1.7	-	5	V
INT H-level range			1.7	-	5	V
INT low voltage	3 mA sink current		-	-	0.4	V
Current consumption	Standby current, no LED-operation		-	1.5	2	μA
Current consumption	2 measurements per second, LED current 20 mA		-	5	-	μA
	250 measurements per second, LED current 20 mA		-	520	-	μA
pulse mode incl. LED (averaged)	2 measurements per second, LED current 200 mA		-	35	-	μA
	250 measurements per second, LED current 200 mA		-	4	5 5 5 0.4 2 - - - - - - - - - - - - - - - - - -	mA
	2 measurements per second averaging = 1		-	2.5	-	μA
Current consumption ambient	8 measurements per second averaging = 1		-	10	-	μA
light mode	2 measurements per second averaging = 64		-	160	-	μA
	8 measurements per second averaging = 64		-	640	-	μA
Ambient light resolution	Digital resolution (LSB count )		-	0.25	-	lx
Ambient light output	E <sub>V</sub> = 100 lx averaging = 64		-	400	-	counts
I <sup>2</sup> C clock rate range		f <sub>SCL</sub>	_	-	3400	kHz



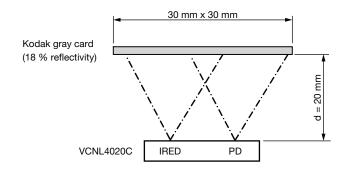
## **CIRCUIT BLOCK DIAGRAM**

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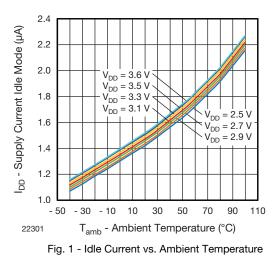
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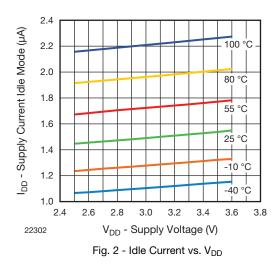
### TEST CIRCUIT

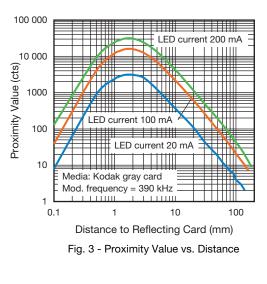


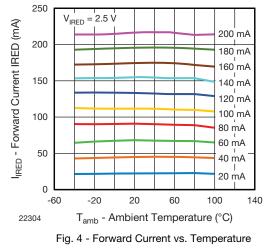
#### Note

### BASIC CHARACTERISTICS (Tamb = 25 °C, unless otherwise specified)









Rev. 1.1, 20-Mar-18

3 contact: sensorster Document Number: 84350

nc must not be electrically connected
 Pads 6 and 7 are only considered as solder pads



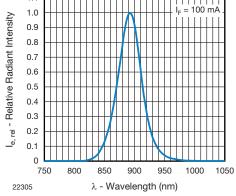


Fig. 5 - Relative Radiant Intensity vs. Wavelength

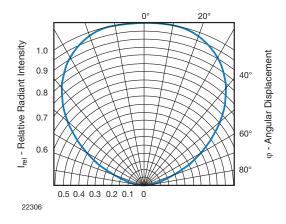


Fig. 6 - Relative Radiant Intensity vs. Angular Displacement

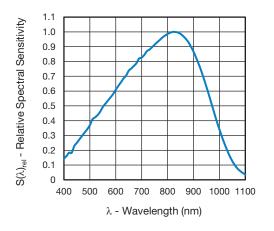


Fig. 7 - Relative Spectral Sensitivity vs. Wavelength (Biosensor)

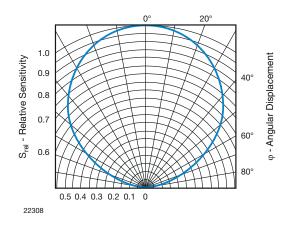


Fig. 8 - Relative Radiant Sensitivity vs. Angular Displacement (Proximity Sensor)

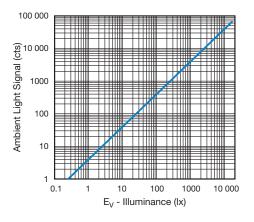


Fig. 9 - Ambient Light Value vs. Illuminance

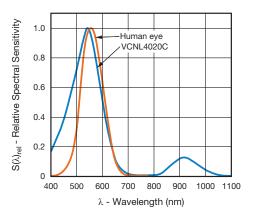


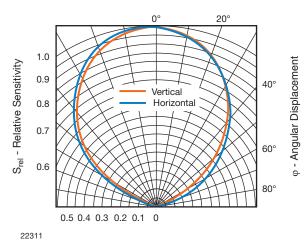
Fig. 10 - Relative Spectral Sensitivity vs. Wavelength (Ambient Light Sensor)

For technical questions, contact: <a href="mailto:sensorstechsupport@vishay.com">sensorstechsupport@vishay.com</a>

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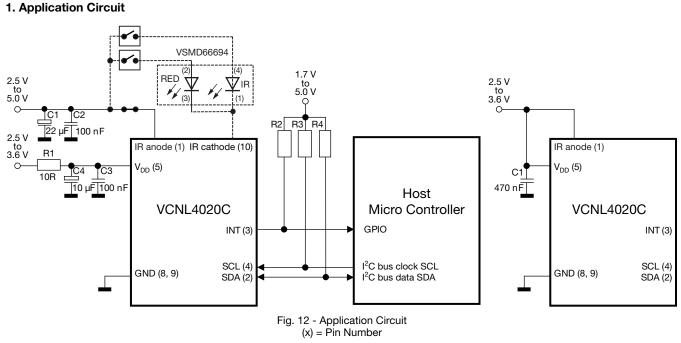
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Fig. 11 - Relative Radiant Sensitivity vs. Angular Displacement (Ambient Light Sensor)

### **APPLICATION INFORMATION**

The digital biosensor VCNL4020C needs just one decoupling-C at V<sub>DD</sub> if connected to a regulated power supply.

IR cathode needs no external connection as the connection to the driver is done internally, but this allows also for adding external LEDs / IREDs to the driver.



#### Note

The interrupt pin is an open drain output. The needed pull-up resistor may be connected to the same supply voltage as the application controller and the pull-up resistors at SDA / SCL. Proposed value R2 should be >1 kΩ, e.g. 10 kΩ to 100 kΩ.
 Proposed value for R3 and R4, e.g. 2.2 kΩ to 4.7 kΩ, depend also on the I<sup>2</sup>C bus speed.

For detailed description about set-up and use of the interrupt as well as more application related information see AN: "Designing VCNL4020C into an Application".

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### 2. I<sup>2</sup>C Interface

The VCNL4020C contains seventeen 8 bit registers for operation control, parameter setup and result buffering. All registers are accessible via I<sup>2</sup>C communication. Figure 13 shows the basic I<sup>2</sup>C communication with VCNL4020C.

The built in I<sup>2</sup>C interface is compatible with all I<sup>2</sup>C modes (standard, fast and high speed).

 $I^2C$  H-level range = 1.7 V to 5 V.

Please refer to the I<sup>2</sup>C specification from NXP for details.

Send byte Write command to VCNL4020C

S	Slave address	Wr	А	Register address	А	I	Data byte	А	Ρ	
Rece	eive byte Read data	from	/CNL4	4020C						
S	Slave address	Wr A Register address A P								
S	Slave address	Rd	А	Data byte	А	Р	Ρ			
S = start condition Host action P = stop condition										
A = a	acknowledge			VCNL4020C respon	se					
	Fig	. 13	- Sei	nd Byte/Receive B	yte F	rotoco	ol			

#### **Device Address**

The VCNL4020C has a fix slave address for the host programming and accessing selection. The predefined 7 bit  $I^2C$  bus address is set to 0010 011 = 13h. The least significant bit (LSB) defines read or write mode. Accordingly the bus address is set to 0010 011x = 26h for write, 27h for read.

#### Register Addresses

VCNL4020C has seventeen user accessible 8 bit registers. The register addresses are 80h (register #0) to 90h (register #16).

### **REGISTER FUNCTIONS**

#### **Register #0 Command Register**

#### Register address = 80h

The register #0 is for starting ambient light or biosensor measurements. This register contains 2 flag bits for data ready indication.

TABLE 1 - COMMAND REGISTER #0											
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0				
config_lock	als_data_rdy	bs_data_rdy	als_od	bs_od	als_en	bs_en	selftimed_en				
			Descr	ription							
config_lock Read only bit. Value = 1											
als_data_rdy Read only bit. Value = 1 when ambient light measurement data is available in the result registers. This bit will be reset when one of the corresponding result registers (reg #5, reg #6) is read.											
bs_da	s_data_rdy Read only bit. Value = 1 when biosensor measurement data is available in the result registers. This b will be reset when one of the corresponding result registers (reg #7, reg #8) is read.										
als	_od	sequence of rea	a single on-demar idings and stores egisters #5(HB) an	the averaged resu	or ambient light. If ılt. Result is availa	averaging is ena ble at the end of	bled, starts a conversion for				
bs_	_od			nd measurement f onversion for read	or biosensor. ling in the registers	s #7(HB) and #8(I	_B).				
als	_en	R/W bit. Enable	s periodic als mea	asurement							
bs	_en	R/W bit. Enable	s periodic biosens	sor measurement							
selftimed_en R/W bit. Enables state machine and LP oscillator for self timed measurements; no measurements performed until the corresponding bit is set						asurement is					

Note

With setting bit 3 and bit 4 at the same write command, a simultaneously measurement of ambient light and biosensor is done. Beside als\_en and / or bs\_en first selftimed\_en needs to be set. On-demand measurement modes are disabled if selftimed\_en bit is set. For the selftimed\_en mode changes in reading rates (reg #4 and reg #2) can be made only when b0 (selftimed\_en bit) = 0. For the als\_od mode changes to the reg #4 can be made only when b4 (als\_od bit) = 0; this is to avoid synchronization problems and undefined states between the clock domains. In effect this means that it is only reasonable to change rates while no selftimed conversion is ongoing.

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#### **Register #1 Product ID Revision Register**

Register address = 81h. This register contains information about product ID and product revision.

Register data value of current revision = 21h.

TABLE 2 -	TABLE 2 - PRODUCT ID REVISION REGISTER #1											
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3 Bit 2 Bit 1 Bit 0								
	Prod	uct ID		Revision ID								
			Descr	iption								
Prod	uct ID	Read only bits.	Value = 2									
Revis	Revision ID Read only bits. Value = 1											

#### **Register #2 Rate of Biosensor Measurement**

Register address = 82h.

TABLE 3 - BIOSENSOR RATE REGISTER #2											
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0				
		n/a	Rate of biosensor Measurement (no. of measurements per second)								
Description											
Bioser	isor rate	R/W bits. 000 - 1.95 mea: 001 - 3.90625 m 010 - 7.8125 m 011 - 16.625 m 100 - 31.25 mea 101 - 62.5 meas 110 - 125 meas 111 - 250 meas	easurements/s easurements/s asurements/s surements/s urements/s	AULT)							

#### Note

• If self\_timed measurement is running, any new value written in this register will not be taken over until the mode is actualy cycled.

#### **Register #3 LED Current Setting for Biosensor Mode**

Register address = 83h. This register is to set the LED current value for biosensor measurement.

The value is adjustable in steps of 10 mA from 0 mA to 200 mA.

This register also contains information about the used device fuse program ID.

TABLE 4 -	TABLE 4 - LED CURRENT REGISTER #3										
Bit 7	Bit 6	Bit 5	Bit 5 Bit 4 Bit 3 Bit 2 Bit 1 Bit 0								
Fuse prog ID         LED current value											
Description											
Fuse p	Fuse prog ID Read only bits. Information about fuse program revision used for initial setup/calibration of the device.										
LED curr	R/W bits. LED current = Value (dec.) x 10 mA.LED current valueValid Range = 0 to 20d. e.g. 0 = 0 mA, 1 = 10 mA,, 20 = 200 mA (2 = 20 mA = DEFAULT)LED Current is limited to 200 mA for values higher as 20d.										



### **Register #4 Ambient Light Parameter Register**

Register address = 84h.

TABLE 5 -	AMBIENT LI	GHT PARAM	ETER REGIS	TER #4						
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0			
Cont. conv. mode		als_rate		Auto offset compensation		Averaging function				
			Desc	ription						
Cont. conve	ersion mode	Enable = 1; Disa This function ca used with ambie	R/W bit. Continuous conversion mode. Enable = 1; Disable = 0 = DEFAULT This function can be used for performing faster ambient light measurements. This mode should only be used with ambient light on-demand measurements. Do not use with self-timed mode. Please refer to the application information chapter 3.3 for details about this function.							
Ambient light m	easurement rate	R/W bits. Ambie 000 - 1 samples 001 - 2 samples 010 - 3 samples 011 - 4 samples 100 - 5 samples 101 - 6 samples 110 - 8 samples 111 - 10 sample	s/s = DEFAULT s/s s/s s/s s/s s/s	ment rate						
Auto offset c	ompensation	<ul> <li>R/W bit. Automatic offset compensation.</li> <li>Enable = 1 = DEFAULT; Disable = 0</li> <li>In order to compensate a technology, package or temperature related drift of the ambient light values there is a built in automatic offset compensation function.</li> <li>With active auto offset compensation the offset value is measured before each ambient light measurement and subtracted automatically from actual reading.</li> </ul>								
Averaging	g function	R/W bits. Averaging function. Bit values sets the number of single conversions done during one measurement cycle. Result is the average value of all conversions. Number of conversions = 2 <sup>decimal_value</sup> e.g. 0 = 1 conv., 1 = 2 conv, 2 = 4 conv.,7 = 128 conv. DEFAULT = 32 conv. (bit 2 to bit 0: 101)								

Note

• If self\_timed measurement is running, any new value written in this register will not be taken over until the mode is actualy cycled.

#### **Register #5 and #6 Ambient Light Result Register**

Register address = 85h and 86h. These registers are the result registers for ambient light measurement readings. The result is a 16 bit value. The high byte is stored in register #5 and the low byte in register #6.

TABLE 6 - AMBIENT LIGHT RESULT REGISTER #5										
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0			
	Description									
Read only bits. High byte (15:8) of ambient light measurement result										

TABLE 7 -	TABLE 7 - AMBIENT LIGHT RESULT REGISTER #6										
Bit 7	Bit 7         Bit 6         Bit 5         Bit 4         Bit 3         Bit 2         Bit 1         Bit 0										
	Description										
Read only bits. Low byte (7:0) of ambient light measurement result											



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### Register #7 and #8 Biosensor Measurement Result Register

Register address = 87h and 88h. These registers are the result registers for biosensor measurement readings. The result is a 16 bit value. The high byte is stored in register #7 and the low byte in register #8.

TABLE 8 - BIOSENSOR RESULT REGISTER #7									
Bit 7	Bit 7         Bit 6         Bit 5         Bit 4         Bit 3         Bit 2         Bit 1         Bit 0								
	Description								
Read only bits. High byte (15:8) of biosensor measurement result									

TABLE 9 - BIOSENSOR RESULT REGISTER #8									
Bit 7	Bit 7         Bit 6         Bit 5         Bit 4         Bit 3         Bit 2         Bit 1         Bit 0								
	Description								
Read only bits. Low byte (7:0) of biosensor measurement result									

#### **Register #9 Interrupt Control Register**

Register address = 89h.

ABLE 10	- INTERRUP	T CONTROL	REGISTER #	9			
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
	Int count exceed		n/a	INT_BS_ ready_EN	INT_ALS_ ready_EN	INT_THRES_EN	INT_THRES
			Desci	ription			
Int coun	t exceed	R/W bits. These threshold 000 - 1 count = 001 - 2 count 010 - 4 count 011 - 8 count 100 -16 count 101 - 32 count 110 - 64 count 111 - 128 count	DEFAULT	number of consec	utive measuremen	nts needed above/	below the
INT_BS_i	ready_EN	R/W bit. Enable	s interrupt genera	tion at biosensor	data ready		
INT_ALS_	ready_EN	R/W bit. Enable	s interrupt genera	tion at ambient da	ata ready		
INT_TH	RES_EN	R/W bit. Enable	s interrupt genera	tion when high or	low threshold is e	exceeded	
INT_THF	RES_SEL		resholds are applied are applied to als	ed to biosensor m measurements	easurements		



### Register #10 and #11 Low Threshold

Register address = 8Ah and 8Bh. These registers contain the low threshold value. The value is a 16 bit word. The high byte is stored in register #10 and the low byte in register #11.

TABLE 11 - LOW THRESHOLD REGISTER #10									
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0		
	Description								
R/W bits. High byte (15:8) of low threshold value									

TABLE 12 - LOW THRESHOLD REGISTER #11									
Bit 7	Bit 7         Bit 6         Bit 5         Bit 4         Bit 3         Bit 2         Bit 1         Bit 0								
Description									
R/W bits. Low byte (7:0) of low threshold value									

#### Register #12 and #13 High Threshold

Register address = 8Ch and 8Dh. These registers contain the high threshold value. The value is a 16 bit word. The high byte is stored in register #12 and the low byte in register #13.

TABLE 13 - HIGH THRESHOLD REGISTER #12									
Bit 7	Bit 7 Bit 6 Bit 5 Bit 4 Bit 3 Bit 2 Bit 1 Bit 0								
	Description								
R/W bits. High byte (15:8) of high threshold value									

TABLE 14 - HIGH THRESHOLD REGISTER #13									
Bit 7	Bit 7         Bit 6         Bit 5         Bit 4         Bit 3         Bit 2         Bit 1         Bit 0								
	Description								
R/W bits. Low byte (7:0) of high threshold value									

#### **Register #14 Interrupt Status Register**

Register address = 8Eh. This register contains information about the interrupt status for either biosensor or ALS function and indicates if high or low going threshold exceeded.

TABLE 15	TABLE 15 - INTERRUPT STATUS REGISTER #14									
Bit 7	Bit 6	Bit 5	Bit 4	4 Bit 3 Bit 2 Bit 1 Bit 0						
	n	/a		int_bs_ready	int_als_ready	int_th_low	int_th_hi			
	Description									
int_bs	_ready	R/W bit. Indicat	es a generated in	terrupt for biosens	sor					
int_als	int_als_ready		es a generated in	terrupt for als						
int_t	h_low	w R/W bit. Indicates a low threshold exceed								
int_	th_hi	R/W bit. Indicat	es a high threshol	d exceed	R/W bit. Indicates a high threshold exceed					

Note

• Once an interrupt is generated the corresponding status bit goes to 1 and stays there unless it is cleared by writing a 1 in the corresponding bit. The int pad will be pulled down while at least one of the status bit is 1.



#### **Register #15 Biosensor Modulator Timing Adjustment**

Register address = 8Fh.

TABLE 16	- BIOSENSO		OR TIMING A	<b>DJUSTMEN</b>	T #15			
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2 Bit 1 Bit 0			
M	odulation delay tir	ne	Biosensor frequency Modulation dead time				ne	
			Desci	ription				
Modulation	n delay time	R/W bits. Setting a delay time between LED signal and detectors input signal evaluation. This function is for compensation of delays from LED and photo diode. Also in respect to the possibility for setting different proximity signal frequency. Correct adjustment is optimizing measurement signal level. (DEFAULT = 0)						
Biosenso	r frequency		neasurement is us Hz (DEFAULT) z Hz	est signal frequenc sing a square sign	,	nt signal. Four diff	erent values are	
Modulation	n dead time	This function is	for reducing of po	evaluation of LED so possible disturbance evel and should be	e effects.	s of the signal. (D	EFAULT = 1)	

Note

• The settings for best performance will be provided by Vishay. With first samples this is evaluated to:

Delay time = 0; dead time = 1 and BS frequency = 00. With that register #15 should be programmed with 1 (= default value).

#### Register #16 Ambient IR Light Level Register

Register address = 90h.

This register is not intended to be used by customer.

## **3. IMPORTANT APPLICATION HINTS AND EXAMPLES**

#### 3.1 Receiver standby mode

In standby mode the receiver has the lowest current consumption of about 1.5 µA. In this mode only the I<sup>2</sup>C interface is active. This is always valid, when there are no measurement demands executed. Also the current sink for the LED is inactive, so there is no need for changing register #3 (LED current).

#### 3.2 Data Read

In order to get a certain register value, the register has to be addressed without data like shown in the following scheme. After this register addressing, the data from the addressed register is written after a subsequent read command.

Rece	Receive byte Read data from VCNL4020C									
S	Slave address Wr A Register address					Ρ				
	-									
S	Slave address Rd A Data byte A P									
P = s	S = start condition     Host action       P = stop condition     VCNL4020C response									
	Fig. 14 - Send	Byte	/ Rec	eive Byte Protocol						

The stop condition between these write and read sequences is not mandatory. It works also with a repeated start condition.

#### Note

For reading out 2 (or more) subsequent registers like the result registers, it is not necessary to address each of the registers separately. After
one read command the internal register counter is increased automatically and any subsequent read command is accessing the next
register.

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Example: read register "Ambient Light Result Register" #5 and #6:

Addressing:command: 26h, 85h (VCNL4020C\_l<sup>2</sup>C\_Bus\_Write\_Adr., Ambient Light Result Register #5 [85])

Read register #5:command: 27h, data (VCNL4020C\_l<sup>2</sup>C\_Bus\_Read\_Adr., {High Byte Data of Ambient Light Result register #5 [85])}

Read register #6:command: 27h, data (VCNL4020C\_I<sup>2</sup>C\_Bus\_Read\_Adr., {Low Byte Data of Ambient Light Result register #6 [86])}

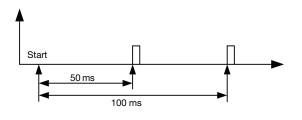
### 3.3 Continuous Conversion Mode in Ambient Light Measurement

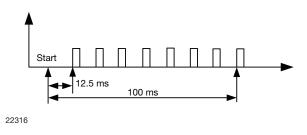
In the following is a detail description of the function "continuous conversion" (bit 7 of register #4)

#### Standard mode (bit 7 of reg #4 = 0):

In standard mode the ambient light measurement is done during a fixed time frame of 100 ms. The single measurement itself takes actually only appr. 300 µs.

The following figures show examples of this measurement timing in standard mode using averaging function 2 and 8 as examples for illustration (possible values up to 128).





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Fig. 15 - Ambient Light Measurement with Averaging = 2; Final Measurement Result = Average of these 2 Measurements Fig. 16 - Ambient Light Measurement with Averaging = 8; Final Measurement Result = Average of these 8 Measurements

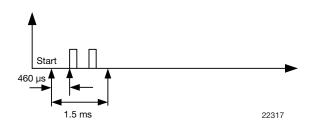
#### Note

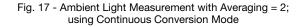
•  $\geq$  Independent of setting of averaging the result is available only after 100 ms.

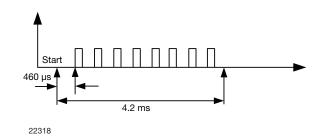
### Continuous conversion mode (bit 7 of register #4 = 1):

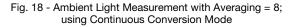
In continuous conversion mode the single measurements are done directly subsequent after each other.

See following examples in figure 17 and 18











0.685

0.65

0.78

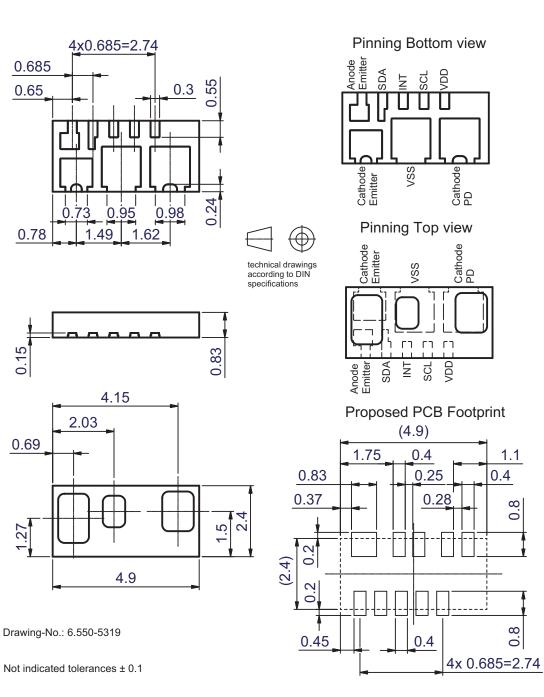
0.15

0.69

2

### **PACKAGE DIMENSIONS** in millimeters

0.73

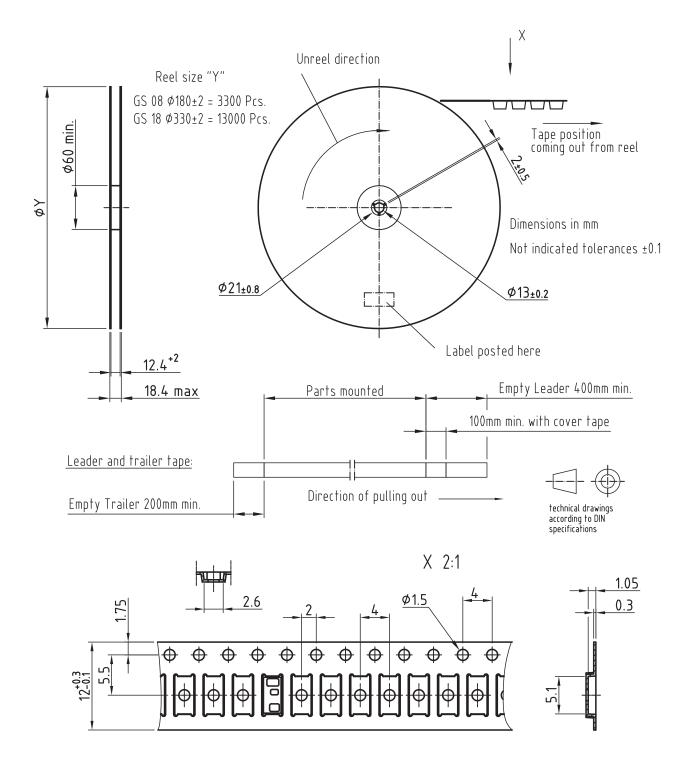


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## TAPE AND REEL DIMENSIONS in millimeters

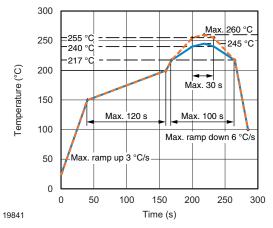


Drawing-No.: 9.700-5387.01-4

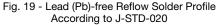
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## SOLDER PROFILE



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#### DRYPACK

Devices are packed in moisture barrier bags (MBB) to prevent the products from moisture absorption during transportation and storage. Each bag contains a desiccant.

## **FLOOR LIFE**

Floor life (time between soldering and removing from MBB) must not exceed the time indicated on MBB label:

Floor life: 72 h

Conditions:  $T_{amb}$  < 30 °C, RH < 60 %

Moisture sensitivity level 4, according to J-STD-020.

#### DRYING

In case of moisture absorption devices should be baked before soldering. Conditions see J-STD-020 or label. Devices taped on reel dry using recommended conditions 192 h at 40 °C (+ 5 °C), RH < 5 %.



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