1DX M.2 Module - Datasheet

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**Document status: Preliminary** 

# 1DX M.2 Module Datasheet

- 802.11 b/g/n and BT/BLE 4.2
- SDIO 2.0 interface, SDR25@50MHz
- 22 x 44 mm with integrated trace antenna



Get Up-and-Running Quickly and Start Developing Your Application On Day 1!



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# **1** Document Revision History

Revision	Date	Description
PA1	2019-04-16	First version.

### 2 Introduction

This document is a datasheet that specifies and describes the *1DX M.2 module* mainly from a hardware point of view. Software related issues, like the Linux and WICED drivers, are not addressed. There are separate documents for that.

### 2.1 Benefits of Using an M.2 Module to get Wi-Fi/BT Connectivity

There are several benefit to use an *M.2 module* to add connectivity to an embedded design:

- Drop-in, certified solution!
- Modular and flexible approach to evaluate different Wi-Fi/BT solutions with different tradeoffs around performance, cost, power consumption, longevity, etc.
- Access to maintained software drivers (Linux and WICED) with responsive support from Murata.
- Supported by Embedded Artists' Developer's Kits for i.MX RT/6/7/8 development, including advanced debugging support on carrier boards
- One component to buy, instead of 50+
- No RF expertise is required
- Developed in close collaboration with Murata and Cypress

### 2.2 More M.2 Related Information

For more information about the M.2 standard and Embedded Artists' adaptation, see: M.2 Primer

For more general information about the M.2 standard, see: https://en.wikipedia.org/wiki/M.2

The official M.2 specification (PCI Express M.2 Specification) is available from: www.pcisig.com

### 2.3 ESD Precaution and Handling

Please note that the M.2 module come without any case/box and all components are exposed for finger touches – and therefore extra attention must be paid to ESD (electrostatic discharge) precaution, for example use of static-free workstation and grounding strap. Only qualified personnel shall handle the product.



Make it a habit always to first touch the mounting hole (which is grounded) for a few seconds with both hands before touching any other parts of the

**boards.** That way, you will have the same potential as the board and therefore minimize the risk for ESD.

In general touch as little as possible on the boards in order to minimize the risk of ESD damage. The only reasons to touch the board are when mounting/unmounting it on a carrier board.

Note that Embedded Artists does not replace modules that have been damaged by ESD.

### 2.4 Product Compliance

Visit Embedded Artists' website at http://www.embeddedartists.com/product\_compliance for up to date information about product compliances such as CE, RoHS2, Conflict Minerals, REACH, etc.

### 3 Specification

This chapter lists some of the more important characteristics of the M.2 module, but it is not a full specification of performance and timing. The main component in the design is Murata's 1DX module (full part number: LBEE5KL1DX), which in turn is based around Cypress CYW4343W chipset.

For a full specification, see on Murata's 1DX Module (LBEE5KL1DX) see Murata's 1DX product page (https://wireless.murata.com/eng/type-1dx.html) and the 1DX datasheet (https://wireless.murata.com/datasheet?/RFM/data/lbee5kl1dx.pdf).

Module / Chipset			
Murata module	LBEE5KL1DX		
Chipset	Cypress CYW4343W		
Wi-Fi			
Standards	802.11b/g/n		
Network	AP and STA dual mode		
Frequency	2.4GHz band		
Data rates	11, 54, 65 Mbps		
Host interface	SDIO 2.0, SDR25@50MH	Hz	
Bluetooth			
Standards	4.2 BR/EDR/LE		
Power Class	Class 1		
Host interface	4-wire UART@3MBaud		
Audio interface	PCM for audio		
Powering			
	Min	Tup	Max
Supply voltage to M.2 module		Тур	
	-0.5V absolute min 3.0V operating	3.3V	3.6V
Note: Do not exceed maximum voltage. Module will be permanently damaged above this limit!	3.2V RF specification		Note that LBEE5KL1DX module specification is 4.8V, but other components on the M.2 module limits the maximum voltage
Receive mode current (WLAN)	47 mA typical		
Transmit mode current (WLAN)	320 mA typical, 370 mA	\ maxim	านทา
Environmental Specification			
Operational Temperature	30 to +70 degrees Calair		
Operational Temperature Specification Temperature	-30 to +70 degrees Celsin -10 to +55 degrees Celsin		

(for Wi-Fi/BT communication)

### 3.1 Power Up Sequence

The supply voltage shall not rise (10 - 90%) faster than 40 microseconds and not slower than 100 milliseconds.

Signals WL\_REG\_ON or BT\_REG\_ON must be held low for at least 700 microseconds after supply voltage has reached specification level before pulled high. 2 clock cycles of the 32.678kHz clock must also have passed before any of the signals is pulled high. These clock cycles will typically occur during the 700 microseconds but if the clock signal has a long delay during power-up, the 700 microsecond period can be extended.

### 3.2 External Sleep Clock

The sleep clock signals can be applied to a powered and unpowered M.2 module.

Clock Specification	
Frequency	32.768 kHz
Frequency accuracy	±200 ppm
Duty cycle	30 - 70%
Clock jitter	<10000 ppm
Voltage level	3.3V logic, according to M.2 standard

### 3.3 Mechanical Dimensions

The M.2 module is of type: 2230-S3-E according to the M.2 nomenclature. This means width 22 mm, length 30mm (without trace antenna), top side component height 1.5 mm and key-E connector. The table below lists the different dimensions and weight.

M.2 Module Dimension	Value (±0.15 mm)	Unit
Width	22	mm
Height, with pcb trace antenna Height, without pcb trace antenna	44 30	mm mm
PCB thickness	0.8	mm
Maximum component height on top side	1.5	mm
Maximum component height on bottom side	0	mm
Ground hole diameter	3.5	mm
Plating around ground hole, diameter	5.5	mm
Module weight	1.5 ±0.5 gram	gram

Embedded Artists has added a non-standard feature to the 2230 M.2 modules designed together with Murata and Cypress. The pictures below illustrates the how the standard module size has been extended by 14 mm in the length direction in order to include a pcb trace antenna.

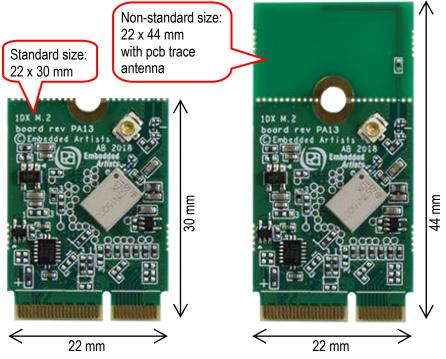


Figure 1 – M.2 Module with, and without, PCB Trace Antenna

The picture below gives dimensions for the grounded center (half) hole and the u.fl. antenna connector.

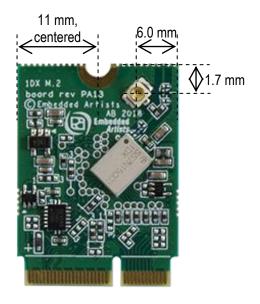


Figure 2 – M.2 Module With, and Without, Trace Antenna

3.4

This section presents the pinning used for the M.2 module. It is essentially M.2 Key-E compliant with enhancements to support additional debug signals and 3.3V VDDIO override. The pin assignment for specific control and debug signals has been jointly defined by Embedded Artists, Murata and Cypress.

The picture below illustrates the edge pin numbering. It starts on the right edge and alternates between top and bottom side. The removed pads in the keying notch counts (but as obviously non-existing).

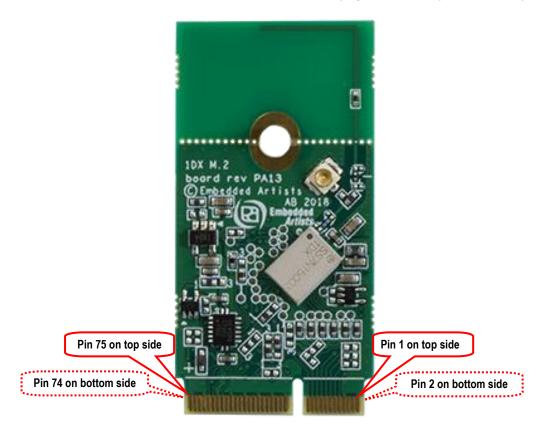


Figure 3 – M.2 Module Pin Numbering

The Wi-Fi interface uses the SDIO interface. The Bluetooth interface uses the UART interface for control and PCM interface for audio. The table below lists the pin usage for the 1DX M.2 modules. The column "When is signal needed" signals four different categories:

- Always: These signals shall always be connected.
- Wi-Fi: These signals shall always be connected then the Wi-Fi interface is used.
- Bluetooth: These signals shall always be connected then the Bluetooth interface is used.
- Optional: These signals are optional to connect.

Pin #	Side of pcb	M.2 Name	Voltage Level and Signal Direction	When is signal needed	Note
1	Тор	GND	GND	Always	Connect to ground
2	Bottom	3.3 V		Always	Power supply input. Connect to stable, low-noise 3.3V supply.
3	Тор	USB_D+			Not connected.
4	Bottom	3.3 V		Always	Power supply input. Connect to stable, low-noise 3.3V supply.
5	Тор	USB_D-			Not connected.

6	Bottom	LED_1#			Not connected.
7	Тор	GND	GND	Always	Connect to ground.
8	Bottom	PCM_CLK	1.8V I/O	Bluetooth audio	For Bluetooth audio interface: BT_PCM_CLK
9	Тор	SDIO CLK	1.8V Input to M.2	Wi-Fi SDIO	For Wi-Fi SDIO interface: SDIO_CLK
					Note that maximum frequency is 50 MHz
10	Bottom	PCM_SYNC	1.8V I/O	Bluetooth audio	For Bluetooth audio interface: BT_PCM_SYNC
11	Тор	SDIO CMD	1.8V I/O	Wi-Fi SDIO	For Wi-Fi SDIO interface: SDIO_CMD
					Note: 10-100K ohm pullup required
12	Bottom	PCM_OUT	1.8V output from M.2	Bluetooth audio	For Bluetooth audio interface: BT_PCM_OUT
13	Тор	SDIO DATA0	1.8V I/O	Wi-Fi SDIO	For Wi-Fi SDIO interface: SDIO_D0
					Note: 10-100K ohm pullup required
14	Bottom	PCM_IN	1.8V input to M.2	Bluetooth audio	For Bluetooth audio interface: BT_PCM_IN
15	Тор	SDIO DATA1	1.8V I/O	Wi-Fi SDIO	For Wi-Fi SDIO interface: SDIO_D1
					Note: 10-100K ohm pullup required
16	Bottom	LED_2#			Not connected.
17	Тор	SDIO DATA2	1.8V I/O	Wi-Fi SDIO	For Wi-Fi SDIO interface: SDIO_D2
					Note: 10-100K ohm pullup required
18	Bottom	GND		Always	Connect to ground.
19	Тор	SDIO DATA3	1.8V I/O	Wi-Fi SDIO	For Wi-Fi SDIO interface: SDIO_D3
					Note: 10-100K ohm pullup required
20	Bottom	UART WAKE#	3.3V OD output from M.2	Bluetooth	For Bluetooth UART interface: BT_HOST_WAKE_L
					Require an external 10K pullup resistor to 3.3V.
21	Тор	SDIO WAKE#	1.8V OD output from M.2	Wi-Fi SDIO	For Wi-Fi SDIO interface WL_HOST_WAKE_L
					Require an external 10K pullup resistor to 1.8V.
22	Bottom	UART TXD	1.8V output from M.2	Bluetooth	For Bluetooth UART interface: BT_UART_TXD
23	Тор	SDIO RESET#			Not connected.
24	Key, non	existing			
25	Key, non	existing			
26	Key, non	existing			
27	Key, non	existing			
28	Key, non	existing			
29	Key, non	existing			
30	Key, non	existing			
31	Key, non	existing			
32	Bottom	UART_RXD	1.8V input to M.2	Bluetooth	For Bluetooth UART interface: BT_UART_RXD
33	Тор	GND		Always	Connect to ground.
34	Bottom	UART_RTS	1.8V output from M.2	Bluetooth	For Bluetooth UART interface: BT_UART_RTS
35	Тор	PERp0			Not connected.
36	Bottom	UART_CTS	1.8V input to M.2	Bluetooth	For Bluetooth UART interface: BT_UART_CTS
37	Тор	PERn0			Not connected.
38	Bottom	VENDOR DEFINED			Not connected.
39	Тор	GND		Always	Connect to ground.

41   Top   PETp0   Not connected.     42   Bottom   VENDOR DEFINED   1.8V input to M.2   Bluetooth   BT_DEV_WAKE_L     43   Top   PETn0   Not connected.     44   Bottom   COEX3   1.8V I/O   Optional   WL_GPIO_1, same as pin 66	
43 Top PETn0 Not connected.   44 Bottom COEX3 1.8V I/O Optional WL_GPIO_1, same as pin 66	
44     Bottom     COEX3     1.8V I/O     Optional     WL_GPIO_1, same as pin 66	
45 Top GND Always Connect to ground.	
46 Bottom COEX_TXD 1.8V I/O Optional WL_GPIO_2	
47 Top REFCLKp0 Not connected.	
48 Bottom COEX_RXD 1.8V I/O Optional WL_GPIO_3	
49 Top REFCLKn0 Not connected.	
50 Bottom SUSCLK 3.3V input to M.2 Always External sleep clock input (32.768kHz)	
51 Top GND Always Connect to ground.	
52 Bottom PERST0# Not connected.	
53 Top CLKREQ0# Not connected.	
54 Bottom W_DISABLE2# 3.3V input to M.2 Always BT_REG_ON, High = BT enabled, Low = BT disable	əd
55 Top PEWAKE0# Not connected.	
56 Bottom W_DISABLE1# 3.3V input to M.2 Always WL_REG_ON, High = Wi-Fi enabled, Low = Wi-Fi d	isabled
57 Top GND Always Connect to ground.	
58 Bottom I2C_SDA Not connected.	
59 Top Reserved Not connected.	
60 Bottom I2C_CLK Not connected.	
61 Top Reserved 1.8V I/O Optional BT_GPIO_3	
62 Bottom ALERT# Not connected.	
63 Top GND Always Connect to ground.	
64 Bottom RESERVED Optional Optional Supply voltage input for control and data si voltage level. Apply a stable, low-noise, 3.3V 100m/ set 3.3V voltage level on all signals.	
65 Top Reserved 1.8V output from M.2 Optional BT_GPIO4	
66 Bottom UIM_SWP 1.8V I/O Wi-Fi SDIO WL_GPIO_1, same as pin 44	
67 Top Reserved 1.8V input to M.2 Optional BT_GPI05	
68 Bottom UIM_POWER_ Not connected.	
69 Top GND Always Connect to ground.	
70 Bottom UIM_POWER_ Not connected. SRC/GPI0_1	
71 Top Reserved Not connected.	
72 Bottom 3.3 V Always Power supply input. Connect to stable, low-noise 3.4	3V supply.
73 Top Reserved Not connected.	
	3V supply.
74     Bottom     3.3 V     Always     Power supply input. Connect to stable, low-noise 3.3	

There are some test points that can be of interest to probe for debugging purposes, as illustrated in the picture below.

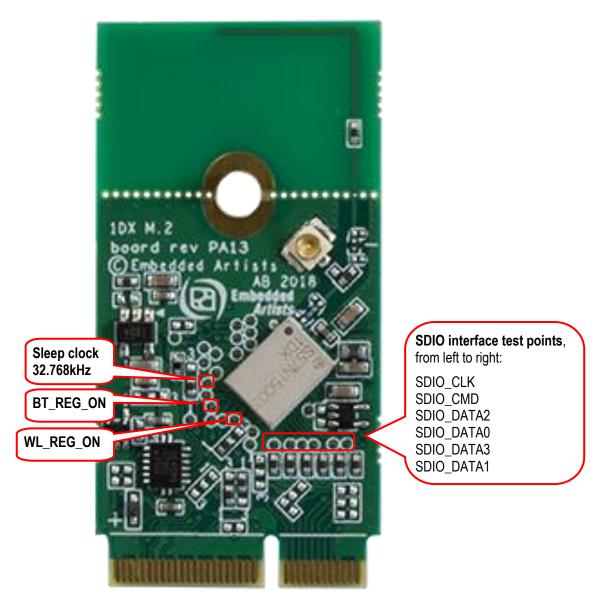


Figure 4 – 1DX M.2 Module Test Points

### 3.6 VDDIO Override Feature

The M.2 standard specify 1.8V logic level on several of the data and control signals. It is possible to override the voltage level for the 1.8V signals via pin 64. Apply a 3.3V / 100 mA supply to pin 64 in order to get 3.3V voltage level on all data and control signals.

### 4 Antenna

This chapter address the antenna side of the module. There is an on-board, reference certified pcb trace antenna. This can be used for testing/evaluation purposes, but also for the final product. Also, for testing and evaluation purposes, it is possible to disconnect the on-board antenna and instead use an u.fl. connector to connect an external antenna.

### 4.1 Mounting and Clearance

Ideally, arrange the M.2 module so that the antenna is located at a corner of the product. Keep plastic case (i.e., non-metallic) away from the antenna area with at least 5 mm clearance (in all directions). Also keep any metal elements (e.g., connectors, battery, etc.) away from the antenna area with at least 5 mm clearance (in all directions). Keep a clearance area under and above the antenna area of at least 7.5mm, both under and over the PCB.

Human hands or body parts should be kept away (in the normal use case) from the antenna area.

The ground hole in the middle shall be grounded. Use a metal stand-off according to M.2 standard (height suitable for selected M.2 connector) and use metal screw to create a proper ground connection.

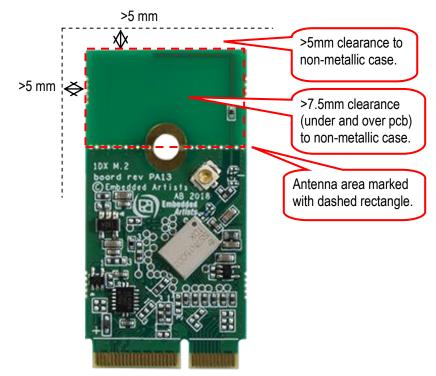


Figure 5 – M.2 Module Clearance Area

### 4.2 Overriding PCB Trace Antenna

The antenna connection from the 1DX module be redirected to the u.fl. connector by just moving one zero ohm 0402 resistor, see illustration below. The on-board trace antenna can be left as-is, or the antenna can be snapped-off.

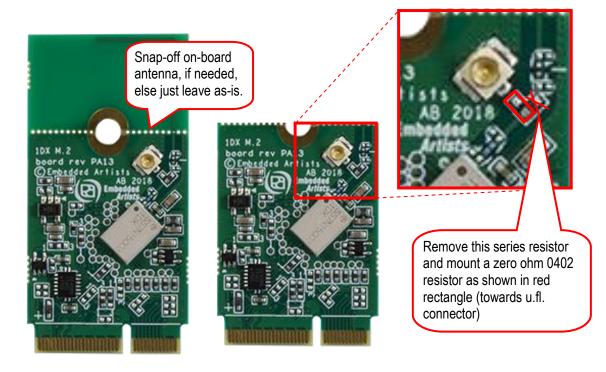


Figure 6 – Rework to Connect U.FL. Connector

### 4.3 On-board Trace Antenna Performance

The on-board pcb trace antenna type is monopole. The 1DX M.2 module has been measured both standalone and mounted on the iMX OEM Carrier Board (which is a typical carrier board design).

The table below lists total efficiency:

Condition	Fre	quency [M	Hz]	Average dB	Average %
Condition	2400	2442	2484	Average up	Average //
M.2 module mounted on reference carrier board	-2.5	-2.3	-2.2	-2.3	58.4
M.2 module standalone	-2.9	-2.8	-2.7	-2.8	52.3

The table below lists peak gain:

Condition	Fre	quency [M	Hz]	Max dBi		
Condition	2400	2442	2484			
M.2 module mounted on reference carrier board	0.0	-0.1	0.1	0.1		
M.2 module standalone	-0.5	-0.1	0.2	0.2		

### 4.3.1 1DX M.2 Module Mounted on iMX OEM Carrier Board

The 3D directivity measurements are presented below for the 2.4 GHz bands when the 1DX M.2 module is mounted on the iMX OEM Carrier Board.

### @2442MHz

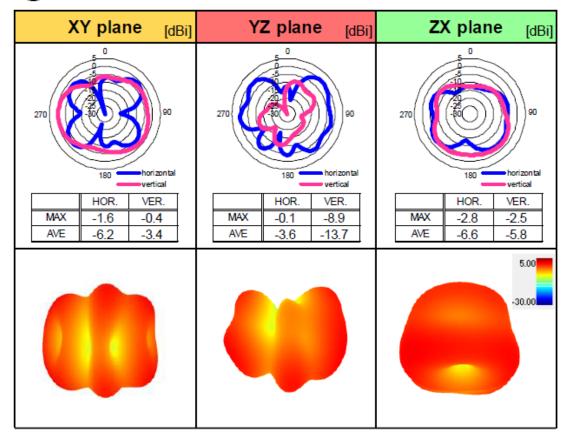


Figure 7 - 3D Directivity Measurements in 2.4 GHz Band (1DX M.2 Mounted on iMX OEM Carrier Board)

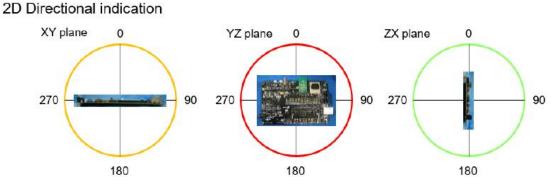


Figure 8 – 3D Directivity Measurements Plane Orientations

The pictures below illustrates the return loss, efficiency and directivity when the 1DX M.2 module is mounted on the iMX OEM Carrier Board.

# <Return Loss>

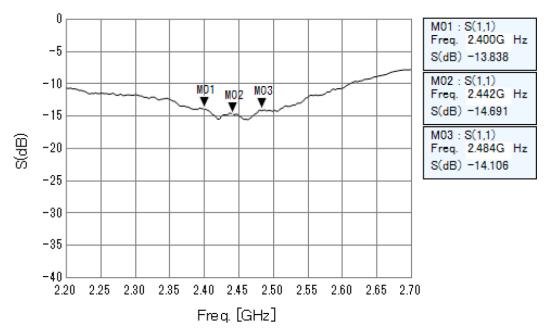


Figure 9 – Return Loss for 1DX M.2 Module Mounted on iMX OEM Carrier Board

### <Efficiency>

[dBi]							[dB]	
LINEAR	LINEAR POLARIZATION		olane	YZ-p	olane	ZX-p	lane	Total
POLARIZAT			ver.	hor.	ver.	hor.	ver.	Efficiency
2400 MHz	MAX.	-2.2	-0.2	0.0	-9.3	-3.2	-2.3	
2400 1011 12	AVE.	-6.8	-3.2	-3.6	-13.8	-7.0	-5.6	-2.5
2442 MHz	MAX.	-1.6	-0.4	-0.1	- <mark>8.9</mark>	-2.8	-2.5	
2442 11172	AVE.	-6.2	-3.4	-3.6	-13.7	-6.6	-5.8	-2.3
2484 MHz	MAX.	-1.2	-0.9	0.1	-8.7	-2.6	-2.6	
2404 10102	AVE.	-5.8	-3.7	-3.6	-13.8	-6.3	-6.0	-2.2

Figure 10 – Efficiency for 1DX M.2 Module Mounted on iMX OEM Carrier Board

# <Directivity>

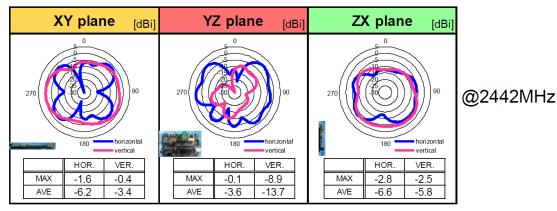


Figure 11 – Directivity for 1DX M.2 Module Mounted on iMX OEM Carrier Board

#### 4.3.2 1DX M.2 Module Standalone

The 3D directivity measurements are presented below for the 2.4 GHz when the 1DX M.2 module is standalone.

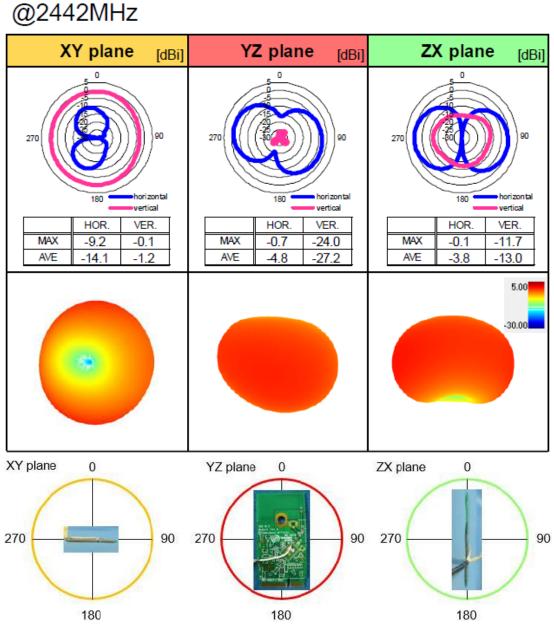
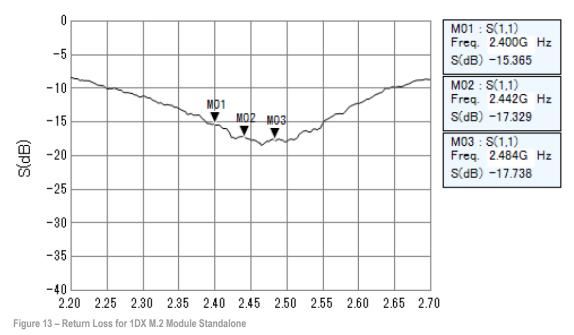


Figure 12 – 3D Directivity Measurements Plane Orientations

The pictures below illustrates the return loss, efficiency and directivity when the 1DX M.2 module is standalone.

# <Return Loss>



# <Efficiency>

[dBi]							[dB]	
LINEAR	LINEAR POLARIZATION		olane	YZ-p	olane	ZX-p	lane	Total
POLARIZAT			ver.	hor.	ver.	hor.	ver.	Efficiency
2400 MHz	MAX.	-9.5	-0.5	-0.7	-23.5	-0.5	-11.4	
2400 10112	AVE.	-14.2	-1.3	-4.7	-27.7	-4.0	-12.9	-2.9
2442 MHz	MAX.	-9.2	-0.1	-0.7	-24.0	-0.1	-11.7	
2442 11172	AVE.	-14.1	-1.2	-4.8	-27.2	-3.8	-13.0	-2.8
2484 MHz	MAX.	-9.4	0.2	-0.4	-23.6	-0.2	-11.9	
2404 10112	AVE.	-14.3	-1.0	-4.8	-27.4	-3.7	-13.1	-2.7

Figure 14 – Efficiency for 1DX M.2 Module Standalone

# <Directivity>

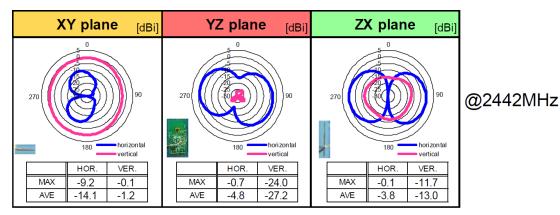


Figure 15 – Directivity for 1DX M.2 Module Standalone

# 5 Regulatory

<TBC>

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